



MoCA: <u>Memory-Centric</u>, <u>Adaptive Execution</u> for Multi-Tenant Deep Neural Networks

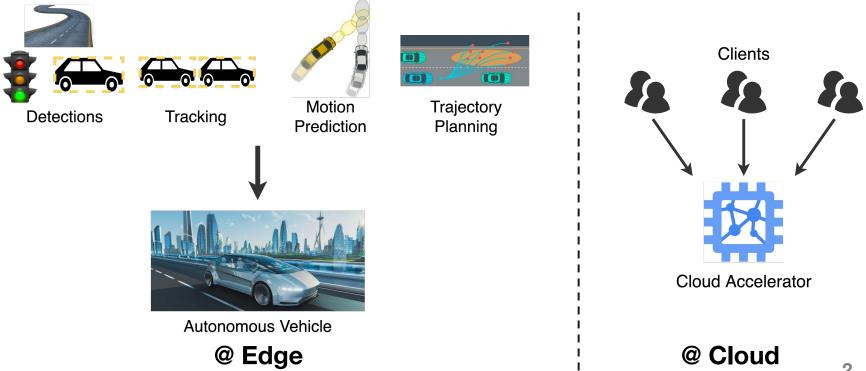
<u>Seah Kim</u>, Hasan Genc, Vadim Nikiforov, Krste Asanovic, Borivoje Nikolic, Yakun Sophia Shao

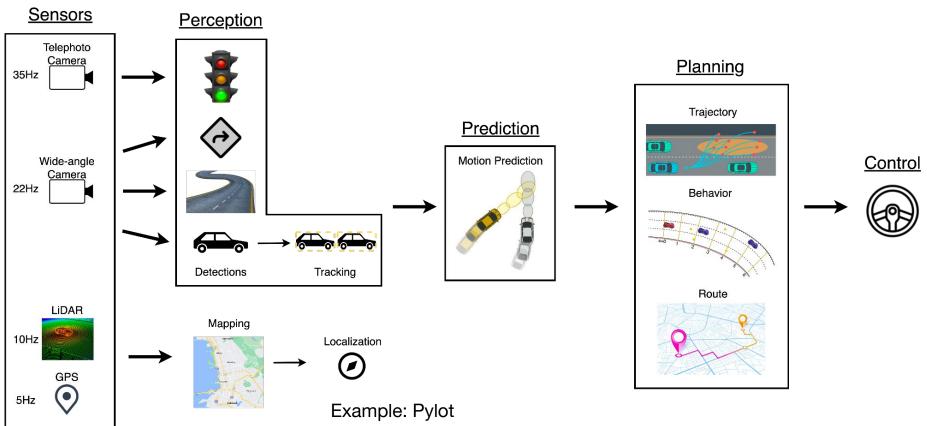


Seah Kim (seah@berkeley.edu)

Multi-tenancy for DNN

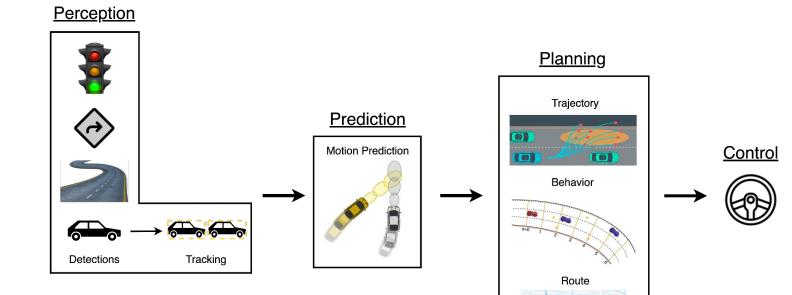






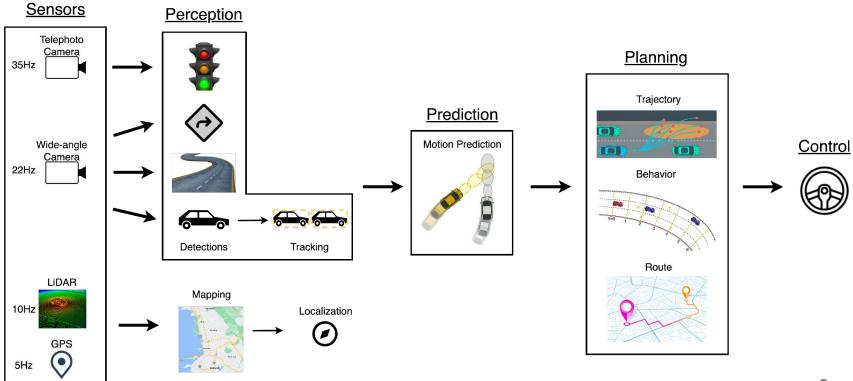
Ionel Gog, Sukrit Kalra, Peter Schafhalter, Matthew A. Wright, Joseph E. Gonzalez, and Ion Stoica. Pylot: A 3 Modular Platform for Exploring Latency-Accuracy Tradeoffs in Autonomous Vehicles, ICRA 2021

- Consists of multiple different modules
 - Perception, Prediction, Planning, Control

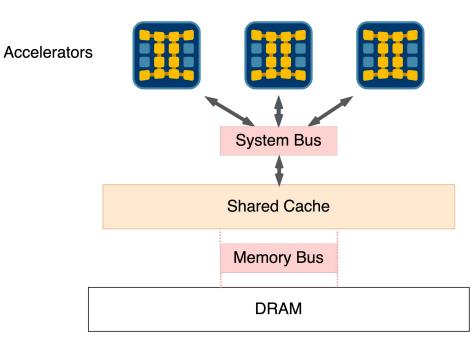


<u>Sensors</u> **Perception** Multiple tasks exists in a module Telephoto Camera 35Hz Vide-angle Camera 22Hz Models with different processing rate -> different target deadline Detections Tracking LiDAR Module consist of different models 10Hz GPS • 5Hz

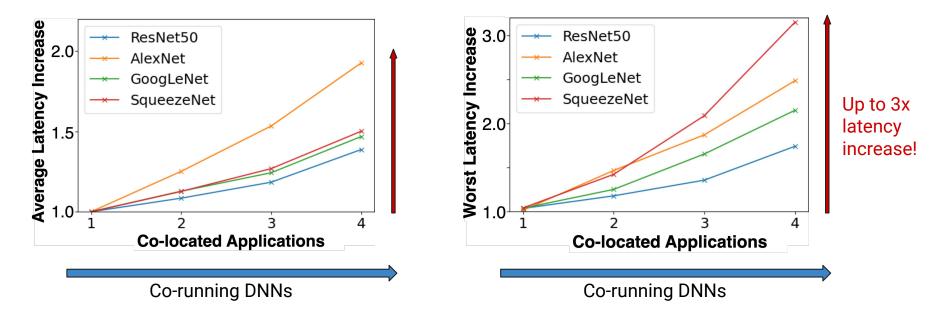
• Need multi-tenancy support by co-running multiple models together



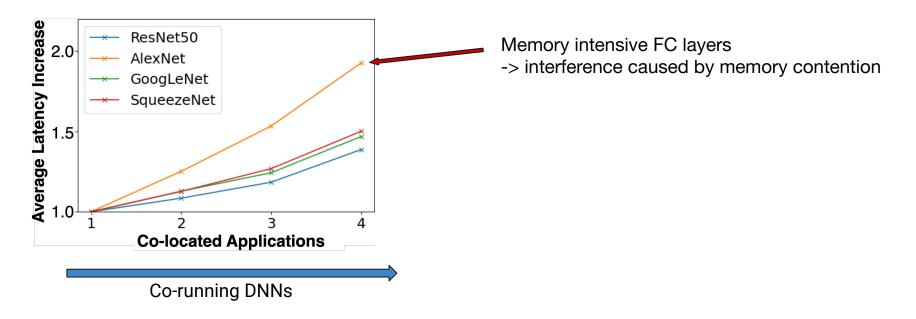
- Performance degradation due to shared resource contention
 - LLC, DRAM, IO, System bus



• Increased system-level interference cause significant performance degradation

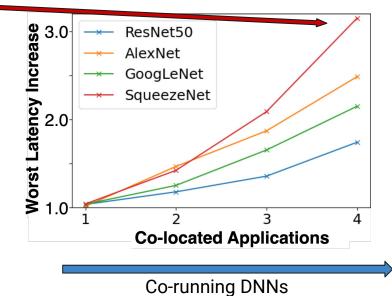


• Increased system-level interference cause significant performance degradation



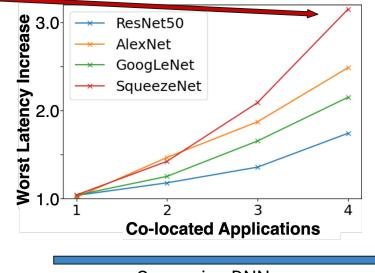
• Increased system-level interference cause significant performance degradation

Short running network -> depends on co-located workload characteristics of using shared resources



• Increased system-level interference cause significant performance degradation

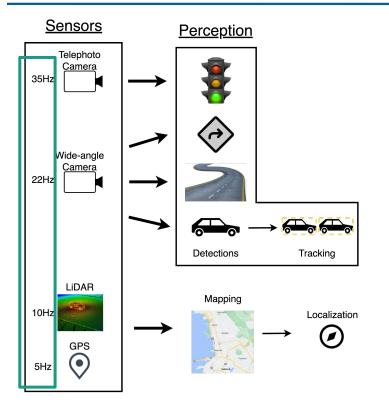
Short running network -> depends on co-located workload characteristics of using shared resources



Need runtime contention detection

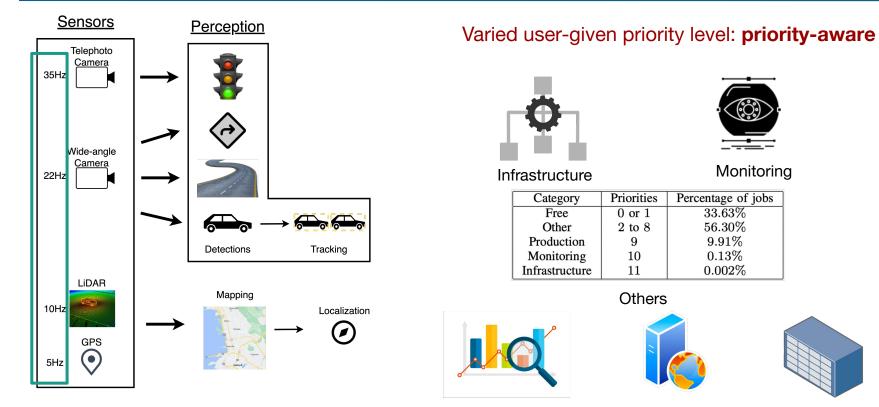
Need management and dynamic manipulation of shared resources

Challenge 2 - Scheduling



Different target latency: target-aware

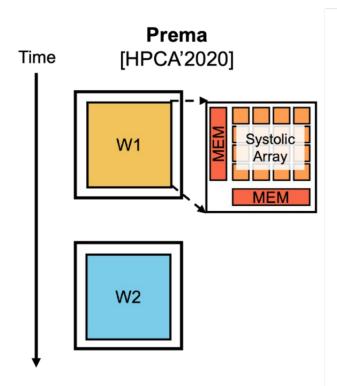
Challenge 2 - Scheduling



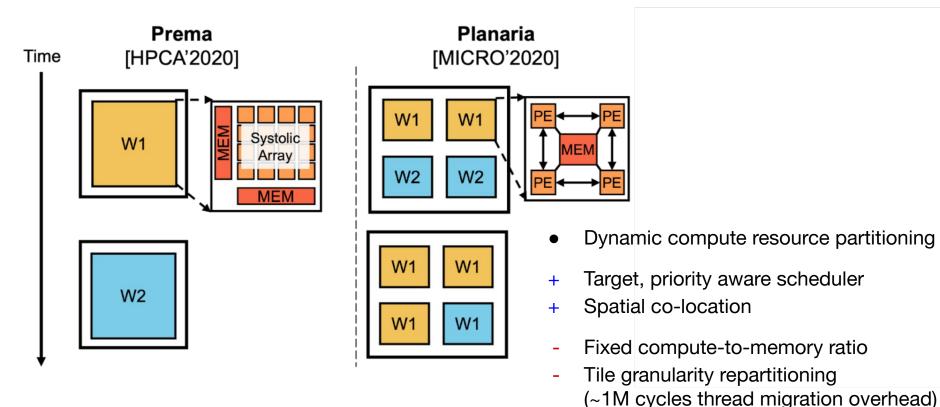
Different target latency: target-aware

P. Minet, É. Renault, I. Khoufi and S. Boumerdassi, "Analyzing Traces from a Google Data Center," 2018 IWCMC

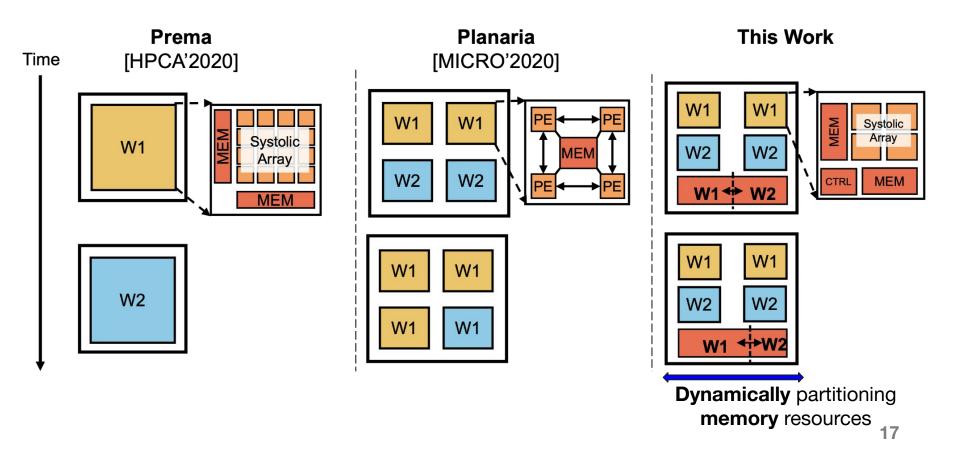
- Two challenges in Multi-tenancy execution
 - System level interference
 - Target & Priority aware scheduling
- How did prior works address the challenges?
- MoCA's advantage over prior works?



- Time multiplexing workloads using preemption
- + Target, priority aware scheduler
- No spatial co-location



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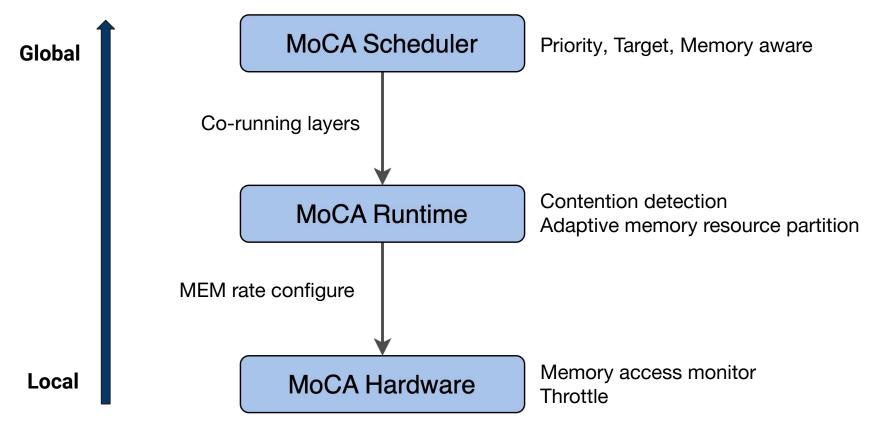


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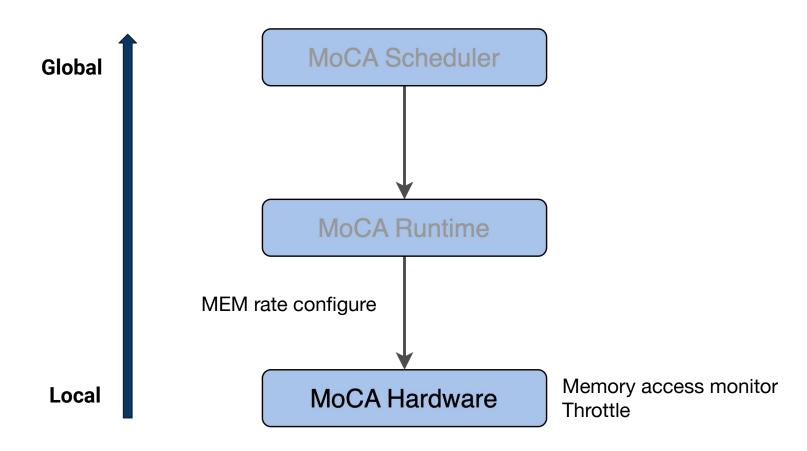
1. Motivation

- 2. MoCA System
- 3. Methodology
- 4. Evaluation results

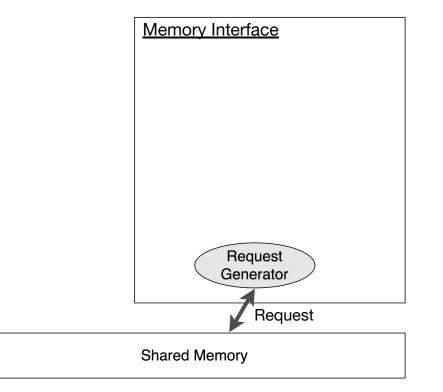
MoCA's Full-Stack Implementation

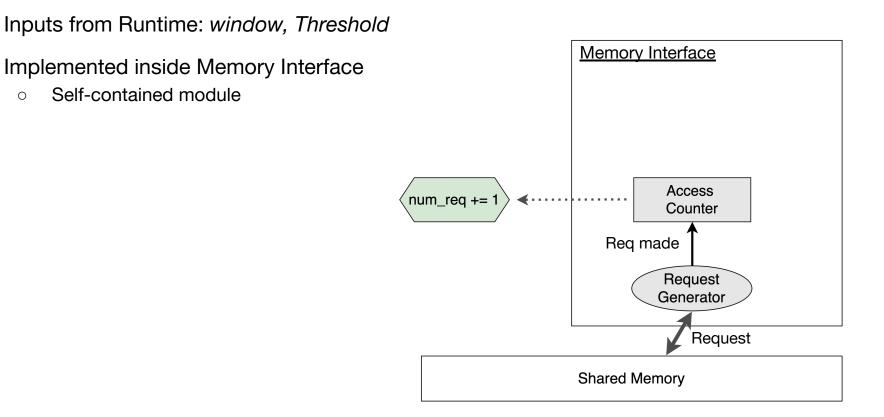


MoCA's Full-Stack Implementation

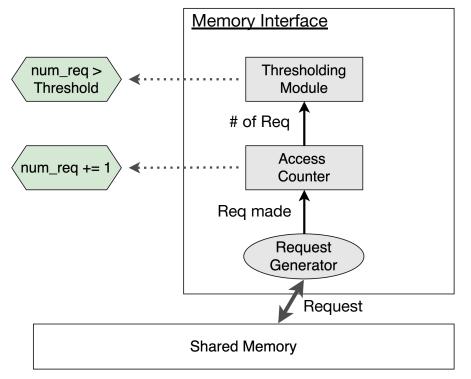


- Inputs from Runtime: *window, Threshold*
- Implemented inside Memory Interface
 - Self-contained module

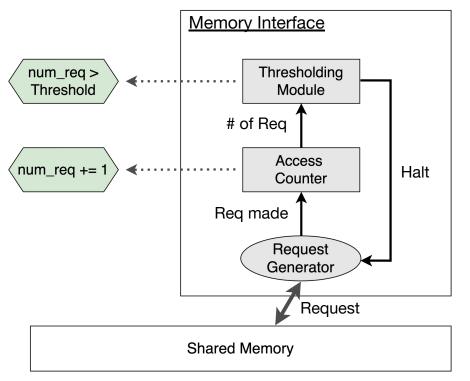




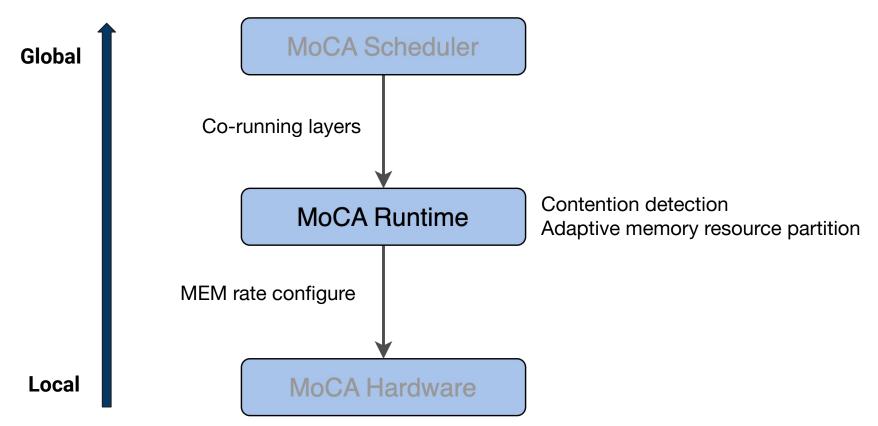
- Inputs from Runtime: window, Threshold
- Implemented inside Memory Interface
 - Self-contained module
- Controls Mem req rate using 2 params
 - Monitoring time "window"
 - # request "Threshold" per time window



- Inputs from Runtime: window, Threshold
- Implemented inside Memory Interface
 - Self-contained module
- Controls Mem req rate using 2 params
 - Monitoring time "window"
 - *# request "Threshold"* per time *window*
- Generates Id/st to meet configured rate
 - Halt if it goes over

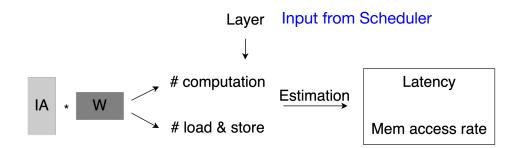


MoCA's Full-Stack Implementation

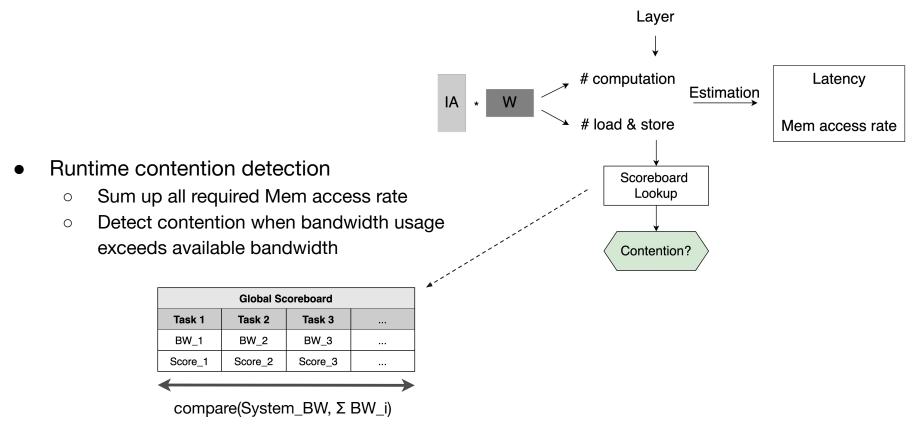


MoCA Runtime

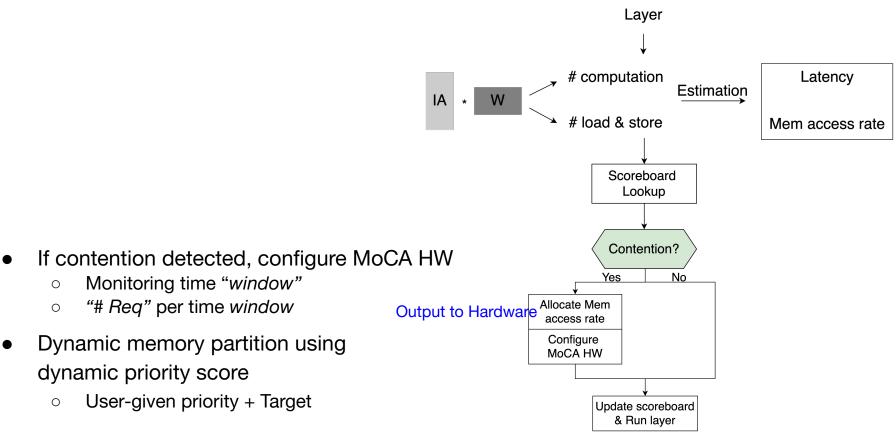
- Leverage DNN regularity
- Calculates latency estimate of a layer
 - Using # of computation, # of Id/st
- Calculates required Mem access rate



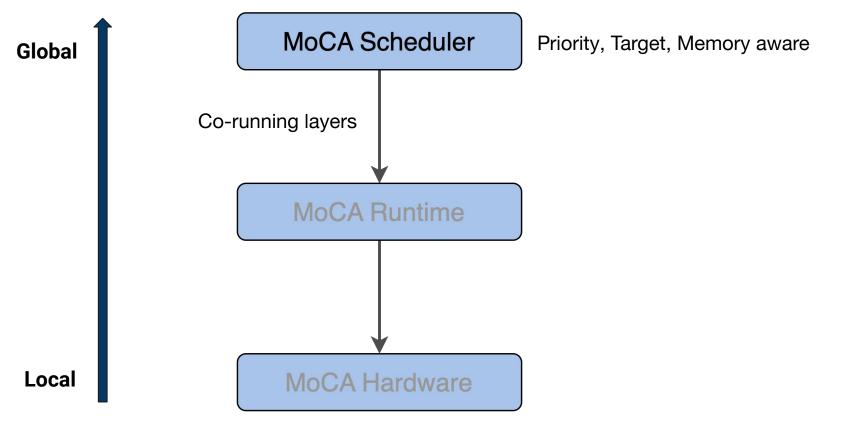
MoCA Runtime



MoCA Runtime



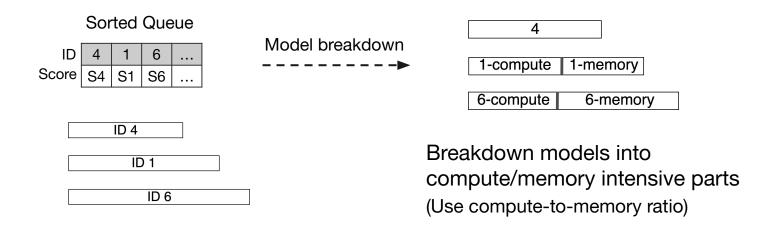
MoCA's Full-Stack Implementation

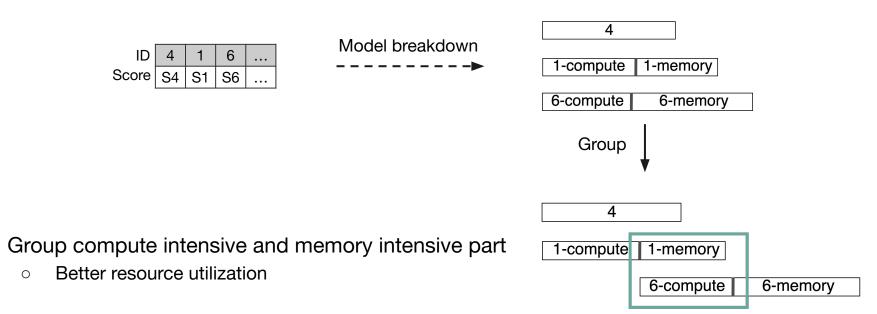


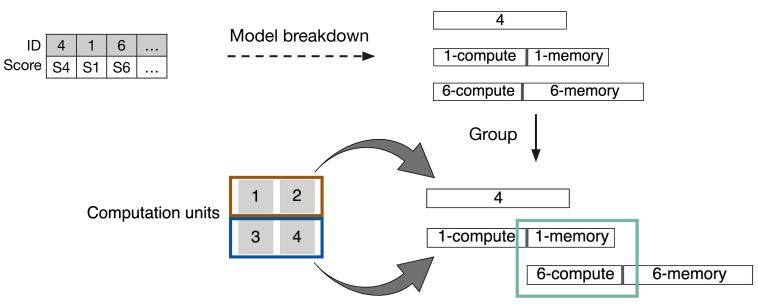
Task Table				1		Pick Score > Threshold								
ID	User_given_priority	Dispatched_time	Target											
1	Priority 1	Time 1	Target 1	Compute Score		ID	0	1	2	3	4	5	6	
2	Priority 2	Time 2	Target 2	(priority, slack)		Score	0			-				
3	Priority 3	Time 3	Target 3				S0	S1	S2	S3	S4	S5	S6	
v_down _i = waiting_time _i /estimated_time _i							Sort(Score)							
h	nic score _i =												1	

Sorted Queue

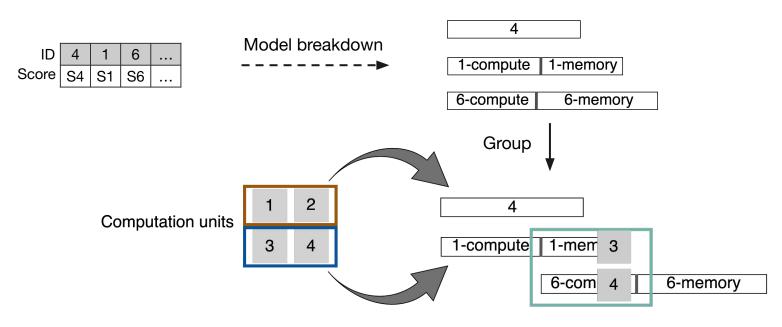
- Priority, target aware dynamic scoring
- Lightweight, low overhead







- Allocate computation resources
- Decides workload to run concurrently



- Decides workload to run concurrently
 - Memory-demanding & Compute-demanding tasks co-scheduled

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MoCA Evaluation

- Implementation details
 - Hardware: Chisel RTL language, Gemmini
 - Software: C++, Linux pthread
 - Runs on top of full Linux stack
 - Simulator: FireSim





Parameter	Value			
Systolic array dimension (per tile)	16x16			
Scratchpad size (per tile)	128KiB			
Accumulator size (per tile)	64KiB			
# of accelerator tiles	8			
Shared L2 size	2MB			
Shared L2 banks	8			
DRAM bandwidth	16GB/s			
Frequency	1GHz			

Chipyard SoC configuration

MoCA Evaluation

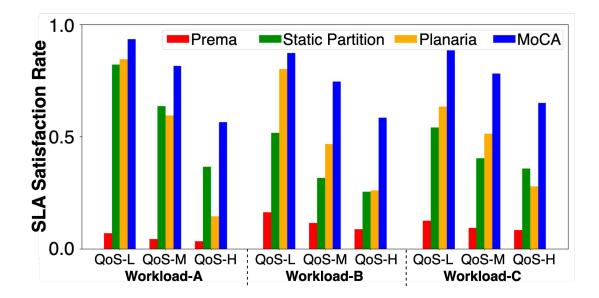
- Multi-tenant DNN accelerator baselines
 - **PREMA**: time-multiplexing
 - **Static Partitioning**: no repartitioning resource during runtime
 - Planaria: dynamically repartition of compute resources
- Benchmarks: 7 different DNN inference models
 - Grouped by model size, 3 sets
- QoS targets
 - 3 different latency targets
 - QoS-H: 1.2x
 - QoS-M: 1x
 - QoS-L: 0.8x

Workload	Model Size	DNN Models
Workload set-A	Light	SqueezeNet, Yolo-LITE, KWS
Workload set-B	Heavy	GoogLeNet, AlexNet, ResNet50, YoloV2
Workload set-C	Mixed	All

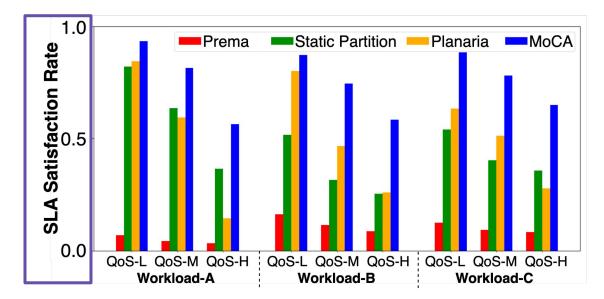
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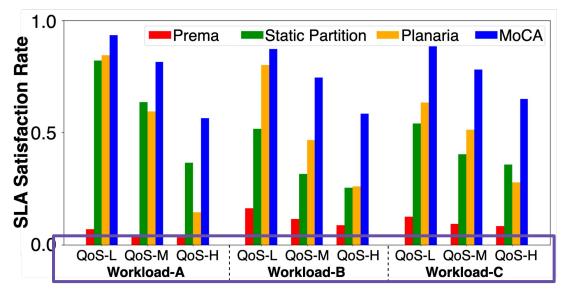
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- SLA (Service Level Agreement) satisfaction
 - Whether the request meets QoS target



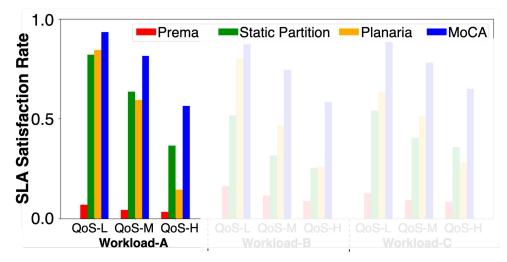
- SLA satisfaction rate
 - Absolute value
 - Range 0 (all fail) ~ 1 (all met QoS)



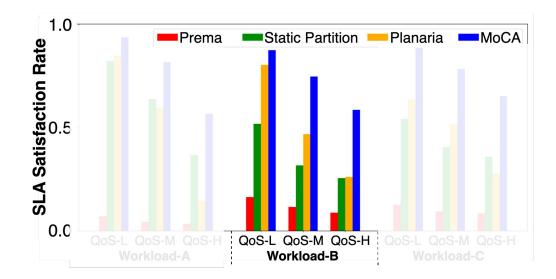


- 2-level x-axis
 - Each workload set subdivided into QoS target level

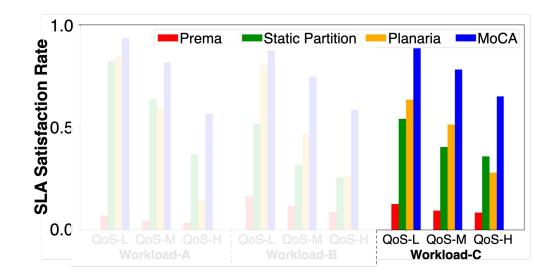
- Workload-A: Light models
 - Prema: poor due to low scalability of light models
 - Planaria: poor due to pronounced thread migration overhead
 - MoCA's advantage more pronounced for QoS-H



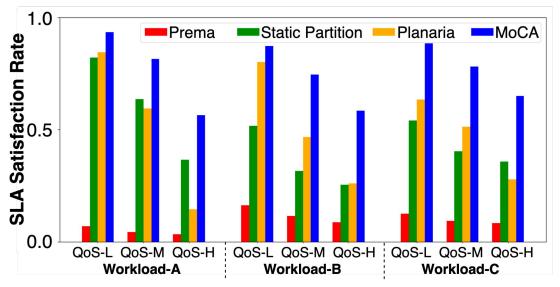
- Workload-B: Heavy models
 - MoCA's advantage over Planaria more pronounced for QoS-H
 - Less thread migration overhead



- Workload-C: All models
 - Baselines: in between workload-A & -B
 - MoCA: co-schedule memory-intensive & light model with mixed workload set



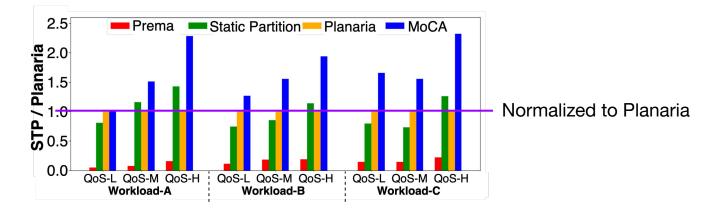
- MoCA improves SLA satisfaction rate:
 - Shows effectiveness of ability to modulate shared memory contention
 - Shows good adaptiveness without thread migration overhead



- To Prema: 8.7x (geomean), 18.1x (max)
- To Static Partition: 1.8x (geomean), 2.4x (max)
- To Planaria: 1.8x (geomean), 3.9x (max)

Throughput Comparison

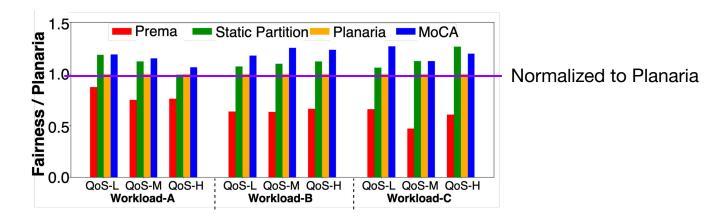
- MoCA constantly shows better throughput than baselines
- Workload-C (mixed): shows highest improvement
 - Better compute/memory utilization
 - More co-location of memory and compute intensive layers



- To Prema: 12.5x (geomean), 20.5x (max)
- To Static Partition: 1.7x (geomean), 2.1x (max)
- To Planaria: 1.7x (geomean), 2.3x (max)

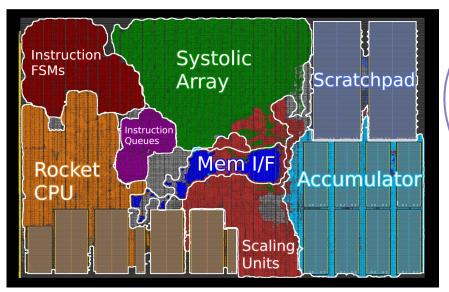
Fairness Comparison

- Fairness metric:
 - Measures the degree to which all programs have equal progress
 - Evaluate priority aware scoring
- Fairness improvement
 - Co-runners do not unequally starve



Physical Design & Area Analysis

- Synthesize, Place & Route using GF 12nm
 - Synthesis: Cadence Genus
 - Place-and-route: Cadence Innovus



Layout of an accelerator tile with MoCA

MoCA takes only small area: 0.02% out of entire

Component	Area (μ m ²)	% of System Area
Rocket CPU	101K	20.5%
Scratchpad	58K	11.7%
Accumulator	75K	15.2%
Systolic Array	78K	15.8%
Instruction Queues	14K	2.8%
Memory Interface w/o MoCA	8.6K	1.7%
MoCA hardware	0.1K	0.02%
Tile	493K	100%

Area breakdown of an accelerator tile with MoCA

Artifact Evaluation Badging

- Artifact evaluated & available
 - ORO (opened) / ROR (reviewed) / ROR-R (result reproduced)



Artifact repo: https://github.com/ucb-bar/MoCA

Acknowledgement

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Contribution

- Develop MoCA System for multi-tenant DNN accelerator
 - Adaptively adjust contentiousness under system-level contention
- MoCA Hardware
 - Monitor memory accesses and limit the request
- MoCA Runtime
 - Runtime contention detection
 - Adaptively configure hardware based on target and priority
- MoCA Scheduler
 - Priority, target, memory contention aware scheduler for multi-tenant execution

Thanks!

Please contact seah@berkeley.edu if you have any questions