Modern Parallel Languages

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HPC: From Vector Supercomputers to Massively Parallel Systems

Programmed by “annotating” serial programs

Programmed by completely rethinking algorithms and software for parallelism

25% industrial use 50%

Systems
A Brief History of Languages

- When vector machines were king
  - Parallel “languages” were loop annotations (IVDEP)
  - Performance was fragile, but there was good user support
- When SIMD machines were king
  - Data parallel languages popular and successful (CMF, *Lisp, C*, …)
  - Quite powerful: can handle irregular data (sparse mat-vec multiply)
  - Irregular computation is less clear (multi-physics, adaptive meshes, backtracking search, sparse matrix factorization)
- When shared memory multiprocessors (SMPs) were king
  - Shared memory models, e.g., OpenMP, Posix Threads, are popular
- When clusters took over
  - Message Passing (MPI) became dominant

We are at the mercy of hardware, but we get blamed.
Science Across the “Irregularity” Spectrum

Data analysis and simulation

Massive Independent Jobs for Analysis and Simulations

Nearest Neighbor Simulations

All-to-All Simulations

Random access, large data Analysis
### Analytics vs. Simulation Kernels:

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Programming Challenges and Solutions

Message Passing Programming
- Divide up domain in pieces
- Each compute one piece
- Exchange (send/receive) data

PVM, MPI, and many libraries

Global Address Space Programming
- Each start computing
- Grab whatever you need whenever

Global Address Space Languages and Libraries

8/29/13
Why Consider New Languages at all?

• Most of work is in runtime and libraries
• Do we need a language? And a compiler?
  – If higher level syntax is needed for productivity
    • We need a language
  – If static analysis is needed to help with correctness
    • We need a compiler (front-end)
  – If static optimizations are needed to get performance
    • We need a compiler (back-end)
• All of these decisions will be driven by application need
Libraries vs. Languages

- Use libraries when: clear interface between operations
  - Dense and sparse matrix operations: can be done in the library
  - FFTs and other spectral transforms
- Use compilers when: cannot be captured in a traditional library
  - Stencils on structured grids (LBMD and Heat)
  - Graph traversal algorithms
- But aren’t these just higher order functions?
  - Yes, but optimization requires they are instantiated

Use an approach that matches the problem
Two Parallel Language Questions

• What is the parallel control model?
  - Data parallel (single thread of control)
  - Dynamic threads
  - Single program multiple data (SPMD)

• What is the model for sharing/communication?
  - Shared memory
  - Message passing
  - Implied synchronization for message passing, not shared memory
Schedule a set of tasks under one of the following assumptions:

**Easy:** The tasks all have equal (unit) cost.

```
 n items
  ___  ___  ___  ___  ___  ___
```

```
 p bins
  [ ] [ ] [ ] [ ] [ ] [ ]
```

**Harder:** The tasks have different, but known, times.

```
 n items
  [ ] [ ] [ ] [ ] [ ] [ ]
```

```
 p bins
  [ ] [ ] [ ] [ ] [ ] [ ]
```

**Hardest:** The task costs unknown until after execution.

```
 n items
  [ ] [ ] [ ] [ ] [ ] [ ]
```

```
 p bins
  [ ] [ ] [ ] [ ] [ ] [ ]
```

- branch-free loops
- sparse matrix-vector multiply
- GCM, circuits, search
Task Dependency Spectrum

Schedule a graph of tasks under one of the following assumptions:

**Easy:** The tasks can execute in any order.

**Harder:** The tasks have a predictable structure.

- wave-front
- out-tree
- in-tree
- general dag
- balanced or unbalanced

**Hardest:** The structure changes dynamically (slowly or quickly)

- dependence
- free loops
- matrix
- computations (dense, and some sparse, Cholesky)
- linear programming
- search, sparse LU
Task Locality Spectrum

Schedule a set of tasks under one of the following assumptions:

**Easy:** The tasks, once created, do not communicate.  
**embarrassingly parallel**

**Harder:** The tasks communicate in a predictable pattern.  
**unstructured and structured grids**

regular  
irregular

**Hardest:** The communication pattern is unpredictable.  
**discrete event simulation**
Liskov’s Goals of Language Design (circa 1981)

0. Well-define semantics (a requirement, not just a goal)
1. Simplicity: easy to learn; minimality of concepts
2. Generality: computationally complete
3. Expressibility
4. Writability
5. Readability
6. Efficiency of compiler and programs (implementable)
7. Uniformity, economy of concepts,
8. Familiarity (consistent with common notation)
9. Orthogonality
10. Extensible and (maybe) subsetable
11. Secure (safe)
12. Machine independent (portable)
MacLennan’s Principles of Language Design

• **Abstraction:** Information about implementations should be hidden from use; recurring patterns should be reusable.

• **Orthogonality:** Independent functions should be controlled by independent mechanisms.

• **Portability:** Avoid features or facilities that are dependent on a particular machine or a small class of machines.

• **Automation:** Automate mechanical, tedious, or error-prone activities.

• **Redundancy:** Have a series of defenses so that if an error isn’t caught by one, it will probably be caught by another.

• **Transparency:** Expensive things should look expensive.

• **Localized Cost:** Users should only pay for what they use; avoid distributed costs.

• **Consistency:** Regular rules, without exceptions, are easier to learn, use, describe, and implement. Similar things should look similar; different things different.

• **Security:** No program that violates the definition of the language, or its own intended structure, should escape detection.

• **Simplicity:** A language should be as simple as possible. There should be a minimum number of concepts, with simple rules for their combination.
Rules for Language Adoption

• Community with need
• Significant advantage (performance or productivity)
• Incremental adoption path (interoperability)
  – Not the whole shebang!
• Portability
• Familiarity
  – Consider C, C++, Java history
• Access to powerful libraries!
Top Goals of Parallel Language Design

• Performance
  – Control
  – Locality
  – Parallelism and synchronization features

• Portability (main goal of productivity)

• Productivity (expressiveness, simplicity, …)

• Familiarity

• Others?
To Virtualize or Not

• The fundamental question facing in parallel programming models is:
  What should be virtualized?

• Hardware has finite resources
  – Processor count is finite
  – Registers count is finite
  – Fast local memory (cache and DRAM) size is finite
  – Links in network topology are generally $< n^2$

• Does the programming model (language+libraries) expose this or hide it?
  – E.g., one thread per core, or many?
    • Many threads may have advantages for load balancing, fault tolerance and latency-hiding
    • But one thread is better for deep memory hierarchies

• How to get the most out of your machine?
Programming Model Research: Early 90s

• Data-parallel languages
  – Fine-grained parallelism, similar to vectorization, with hard compiler problem to map to coarse-grained machines
  – Examples: HPF, pC++, NESL

• Task parallel
  – Especially for divide-and-conquer problems with little inherent locality
  – Small compilers with sophisticated runtime systems
  – Examples: CILK, Charm++

• Object-oriented parallel languages
  – Computation follows data
  – Examples: CC++, CA

• Global address space languages
  – Small compilers and lightweight runtimes
  – Examples: Split-C, PCP, AC, F--
What Happened to HPF?

• High Performance Fortran (data parallel)
  – Language effort by users, language researchers, vendors
  – Ambitious goals: tried to address many domains
    • Dense linear algebra: block-cyclic data layouts (index overhead)
    • Sparse, unstructured problems: irregular layouts
  – Compiler performs difficult mapping for coarse-grained machines
    • Kennedy: “10-15 years for compiler technology to mature”
  – Abandoned in the U.S. after O(5 years)
  – Seeing some success in Japan/Europe
  – Surprising Gordon Bell prize on the Earth Simulator
Bringing Users Along: UPC Experience

- **Ecosystem:**
  - Users with a need (fine-grained random access)
  - Machines with RDMA (not full hardware GAS)
  - Common runtime; Commercial and free software
  - Sustained funding and Center procurements

- **Success models:**
  - Adoption by users: vectors → MPI, Python and Perl, UPC/CAF
  - Influence traditional models: MPI 1-sided; OpenMP locality control
  - Enable future models: Chapel, X10,…
PyGAS: Combine two popular ideas

- Python
  - No. 6 Popular on http://langpop.com and extensive libraries, e.g., Numpy, Scipy, Matplotliblib, NetworkX
  - 10% of NERSC projects use Python

- PGAS
  - Convenient data and object sharing

- PyGAS: Objects can be shared via Proxies with operations intercepted and dispatched over the network:

  ```python
  num = 1 + 2 * j
  = share(num, from=0)
  num = 1+2*j
  = share(num, from=0)

  print pxy.real # shared read
  pxy.imag = 3   # shared write
  print pxy.conjugate() # invoke
  ```

- Leveraging duck typing:
  - Proxies behave like original objects.
  - Many libraries will automatically work.
Can Architectures Help Make Programming Easier?

The vicious cycle:

- All high end programs written in MPI
- All machines support only MPI well

Who is affected:

- the scientists who are not paid enough to program in MPI
- the customers who bought hardware and threw away the performance
Course Goals

• Training in well-defined language design and sufficient documentation: how to recognize good/bad specs
• Design of a future language, e.g., PyGAS
• Design of future autotuners, aka DSLs
• Language and compiler support for communication-avoiding algorithm support
• Priorities based on interests of participants
Course Mechanics

• Web page:
  
  http://www.cs.berkeley.edu/~yelick/cs294-f13

• Course lectures in 3 parts:
  
  - GP Language overviews: X10, Chapel, Titanium or UPC,…
  - Cross-cuts: Memory Consistency, Collectives, Liveness, Array abstractions…
  - Presentations by students and auditors on topics of interest: DSLs (SEJITS), communication avoiding compilers (HBL), Data languages (Hadoop), PyGAS

• Prerequisites:
  
  - Understanding of parallel (scientific) computing: CS267 or equivalent
  - Familiarity with multiple languages and interest in learning more!

• Grading: This is an advanced graduate class
  
  - Programming assignments in first half of semester
  - Final projects

• Class computer accounts at NERSC (using mp309, CS267 repo)
  
  - Search for “NERSC new user” which should take you to the following URL
  - https://nim.nersc.gov/nersc_account_request.php
How to fill out the NERSC Account form

NERSC New Account Request Form

Please fill out and submit this form to request a new NERSC account to be associated with an existing NERSC repository, project, or share.

If you are already a NERSC user, please contact your project’s Principal Investigator to be added to an existing NERSC repository.

If you are not a NERSC user and wish to submit a proposal to create a new NERSC project, please go to “ERCAP Access to new PI’s and PI Proxies”. If you are an existing NERSC user and wish to submit a new project proposal, please do so through NIM.

Account Type: Standard

First Name: Jane

Middle Initial (optional): 

Last Name: Doe

Preferred Username: jdoe (if you do not already have a NERSC username, enter a preferred username. Maximum of 8 characters.)

Citizenship: 

Email Address: 

Work phone is required. (Format: 123-456-7890, non-U.S. users please include country code)

Telephone: 

Organization: USA: University of California Berkeley

Principle Investigator and repository name: Kathy Yelick: mp309 – Class Account for UCB CS267 / CS194 “Applications of Parallel Computing” – Proxies

Select the project you wish to be added to. You can search by PI name, repository, share name, or experiment, by the Project’s Description or by a PI Proxy’s name. Be sure to select from the list that is presented.

Please provide a description of the work you will be doing and the name of the person you will be working with:

(2000 character maximum)

Exercising new parallel programming languages

NERSC Electronic Computer User Agreement form

The following is a list of general computer use policies and security rules that apply to individual users of NERSC. Further information on NERSC security policies and practices can be found on the NERSC Computer Security page. Principal Investigators are responsible for implementing these policies and procedures in their organization and ensuring that users fulfill their responsibilities.

User Accountability

Users are accountable for their actions. Violations of policy may result in applicable administrative or legal sanctions.

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Data Parallelism

• For next week, read about data parallelism:
  • NESL: Nested Data parallelism
    - [http://www.cs.cmu.edu/~scandal/nesl.html](http://www.cs.cmu.edu/~scandal/nesl.html)
  • HTA: Hierarchically Tiled Arrays
    - [http://dl.acm.org/citation.cfm?id=1122981](http://dl.acm.org/citation.cfm?id=1122981)
  • Chapel (more than just data parallel)
    - [http://chapel.cray.com](http://chapel.cray.com)
    - [http://chapel.cray.com/spec/spec-0.93.pdf](http://chapel.cray.com/spec/spec-0.93.pdf)

In each case the first link is to a web page for the project, and the second is a specific paper you should read.