

EECS 219C: Formal Methods

Satisfiability Modulo Theories

Examples Used in Lecture

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Equivalence Checking of Program Fragments

```
int fun1(int y) {  
  int x, z;  
  z = y;  
  y = x;  
  x = z;  
  
  return x*x;  
}
```

SMT formula ϕ

Satisfiable iff programs non-equivalent

$$\begin{aligned} & (z = y \wedge y1 = x \wedge x1 = z \wedge \text{ret1} = x1*x1) \\ & \quad \wedge \\ & (\text{ret2} = y*y) \\ & \quad \wedge \\ & (\text{ret1} \neq \text{ret2}) \end{aligned}$$

```
int fun2(int y) {  
  return y*y;  
}
```

What if we use SAT to check equivalence?

Equivalence Checking of Program Fragments

<pre>int fun1(int y) { int x, z; z = y; y = x; x = z; return x*x; }</pre>	<p>SMT formula ϕ Satisfiable iff programs non-equivalent</p> $(z = y \wedge y1 = x \wedge x1 = z \wedge ret1 = x1*x1) \\ \wedge \\ (ret2 = y*y) \\ \wedge \\ (ret1 \neq ret2)$
--	--

```
int fun2(int y) {  
  return y*y;  
}
```

Using SAT to check equivalence (w/ Minisat)
32 bits for y: Did not finish in over 5 hours
16 bits for y: 37 sec.
8 bits for y: 0.5 sec.

Equivalence Checking of Program Fragments

<pre>int fun1(int y) { int x, z; z = y; y = x; x = z; return x*x; }</pre>	<p>SMT formula ϕ'</p> $\begin{aligned} & (z = y \wedge y1 = x \wedge x1 = z \wedge \text{ret1} = \text{sq}(x1)) \\ & \quad \wedge \\ & (\text{ret2} = \text{sq}(y)) \\ & \quad \wedge \\ & (\text{ret1} \neq \text{ret2}) \end{aligned}$
--	--

```
int fun2(int y) {  
  return y*y;  
}
```

Using EUF solver: 0.01 sec

Equivalence Checking of Program Fragments

```
int fun1(int y) {  
    int x;  
    x = x ^ y;  
    y = x ^ y;  
    x = x ^ y;  
  
    return x*x;  
}
```

Does EUF still work?

No!

Must reason about bit-wise XOR.

Need a solver for bit-vector arithmetic.

```
int fun2(int y) {  
    return y*y;  
}
```

Solvable in less than a sec. with a
current bit-vector solver.

Equivalence Checking of Program Fragments

```
int fun1(int y) {  
    int x[2];  
    x[0] = y;  
    y = x[1];  
    x[1] = x[0];
```

```
    return x[1]*x[1];  
}
```

```
int fun2(int y) {  
    return y*y;  
}
```

How can we express the equivalence checking problem as an SMT formula with arrays?

Equivalence Checking of Program Fragments

```
int fun1(int y) {  
    int x[2];  
    x[0] = y;  
    y = x[1];  
    x[1] = x[0];  
  
    return x[1]*x[1];  
}  
  
int fun2(int y) {  
    return y*y;  
}
```

SMT formula ϕ

```
[ x1 = store(x,0,y)  $\wedge$  y1 = select(x1,1)  
   $\wedge$  x2 = store(x1,1,select(x1,0))  
   $\wedge$  ret1 = sq(select(x2,1)) ]  
   $\wedge$   
( ret2 = sq(y) )  
   $\wedge$   
( ret1  $\neq$  ret2 )
```

EUF

- Example:

$$g(g(g(x))) = x$$

$$\wedge g(g(g(g(g(x)))))) = x$$

$$\wedge g(x) \neq x$$

Difference Logic

$$x_1 \geq x_2$$

$$x_3 \leq 0$$

$$x_2 + 3 \geq x_1$$

$$x_1 + 1 \leq x_3$$

$$x_2 + 1 \geq 0$$

$$x_4 + 2 \geq 0$$

$$x_4 \leq x_2 - 2$$

Theory of Arrays

- Two main axioms: For all A, i, j, d
 - $\text{select}(\text{store}(A,i,d), i) = d$
 - $\text{select}(\text{store}(A,i,d), j) = \text{select}(A,j)$, if $i \neq j$
- Decision procedure operates by performing case-splits
- Example:

```
int a[10];
int fun3(int i) {
    int j;
    for(j=0; j<10; j++) a[j] = j;
    assert(a[i] <= 5);
}
```

Theory of Arrays

- Two main axioms: For all A, i, j, d
 - $\text{select}(\text{store}(A, i, d), i) = d$
 - $\text{select}(\text{store}(A, i, d), j) = \text{select}(A, j)$, if $i \neq j$
- Decision procedure operates by performing case-splits
- Example:

$$a[0] = 0 \wedge a[1] = 1 \wedge a[2] = 2 \wedge \dots \wedge a[9] = 9 \wedge a[i] > 5$$