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Weak Duality: $R \le C$. **Proof:** Better to go second.

Note:

In situation *R. y* plays "Defense". *x* plays "Offense." In situation *C. x* plays "Defense". *y* plays "Offense."

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At Equilibrium (x^*, y^*) , payoff *v*:

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Weak Duality: $R \le C$. **Proof:** Better to go second. Note:

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In situation *R*. *y* plays "Defense". *x* plays "Offense." In situation *C*. *x* plays "Defense". *y* plays "Offense."

At Equilibrium (x^*, y^*) , payoff v: row payoffs (Ay^*) all $\geq v \implies R \geq v$.

$$R = \max_{y} \min_{x} (x^{t}Ay).$$

$$C = \min_{x} \max_{y} (x^{t}Ay).$$

Weak Duality: $R \le C$. **Proof:** Better to go second. Note:

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At Equilibrium (x^*, y^*) , payoff v: row payoffs (Ay^*) all $\geq v \implies R \geq v$. column payoffs $((x^*)^t A)$ all $\leq v$

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Equilibrium \implies R = C!

$$R = \max_{y} \min_{x} (x^{t}Ay).$$
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Equilibrium \implies R = C!

Strong Duality: There is an equilibrium point!

$$R = \max_{y} \min_{x} (x^{t}Ay).$$
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In situation *R. y* plays "Defense". *x* plays "Offense." In situation *C. x* plays "Defense". *y* plays "Offense."

At Equilibrium (x^*, y^*) , payoff v: row payoffs (Ay^*) all $\geq v \implies R \geq v$. column payoffs $((x^*)^t A)$ all $\leq v \implies v \geq C$. $\implies R \geq C$

Equilibrium \implies R = C!

Strong Duality: There is an equilibrium point! and R = C!

$$R = \max_{y} \min_{x} (x^{t}Ay).$$
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In situation *R. y* plays "Defense". *x* plays "Offense." In situation *C. x* plays "Defense". *y* plays "Offense."

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column payoffs $((x^*)^t A)$ all $\le v \implies v \ge C$.
 $\implies R \ge C$

Equilibrium \implies R = C!

Strong Duality: There is an equilibrium point! and R = C!

Doesn't matter who plays first!

Zero sum game:

Zero sum game: $m \times n$ matrix A

Zero sum game: $m \times n$ matrix A row minimizes.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x* ... probability distribution over rows.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x* ... probability distribution over rows.

column maximizes.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

... probability distribution over rows.

column maximizes. strategy: vector *m*-dimensional vector *x* ... probability distribution over columns.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

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Payoff (x, y): $x^T Ay$.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

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Payoff (x, y): $x^T Ay$.

Nash equilibrium (x^*, y^*) :

Zero sum game: $m \times n$ matrix A

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Payoff (x, y): $x^T A y$.

Nash equilibrium (x^*, y^*) :

neither player has better response against others.

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neither player has better response against others.

If there is an equilibrium: no disadvantage in announcing strategy!

Zero sum game: $m \times n$ matrix A

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All equilibrium points all have same payoff.

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Why? Equilibriums: $x_1^T A y_1 < x_2^T A y_2$. $\implies \min_i (A y_2)_i > \min_i (A y_1)_i$

Zero sum game: $m \times n$ matrix A

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Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

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Payoff (x, y): $x^T Ay$.

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Why? Equilibriums: $x_1^T A y_1 < x_2^T A y_2$.

 \implies min_i(Ay₂)_i > min_i(Ay₁)_i Since x zero on non-best.

Best row is worse under y_2 .

 \implies Column player has incentive to change.

Zero sum game: $m \times n$ matrix A

row minimizes. strategy: *m*-dimensional vector *x*

... probability distribution over rows.

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Best row is worse under y_2 .

 \implies Column player has incentive to change.

 x_1, y_1 is not equilibrium.

"Catch me."

"Catch me."

Given: G = (V, E).

"Catch me."

Given: G = (V, E). Given $a, b \in V$.

"Catch me."

Given: G = (V, E). Given $a, b \in V$. Row ("Catch me"): choose path from *a* to *b*.

"Catch me."

Given: G = (V, E). Given $a, b \in V$. Row ("Catch me"): choose path from *a* to *b*. Column("Catcher"): choose edge.
"Catch me."

Given: G = (V, E). Given $a, b \in V$. Row ("Catch me"): choose path from *a* to *b*. Column("Catcher"): choose edge. Row pays if column chooses edge on path.

"Catch me."

```
Given: G = (V, E).
Given a, b \in V.
Row ("Catch me"): choose path from a to b.
Column("Catcher"): choose edge.
Row pays if column chooses edge on path.
```

Matrix:

row for each path: p

"Catch me."

```
Given: G = (V, E).
Given a, b \in V.
Row ("Catch me"): choose path from a to b.
Column("Catcher"): choose edge.
Row pays if column chooses edge on path.
```

Matrix: row for each path: *p* column for each edge: *e*

"Catch me."

```
Given: G = (V, E).
Given a, b \in V.
Row ("Catch me"): choose path from a to b.
Column("Catcher"): choose edge.
Row pays if column chooses edge on path.
```

Matrix: row for each path: pcolumn for each edge: eA[p,e] = 1 if $e \in p$.





Catchme: Use Blue Path.

Catcher:



Catchme: Use Blue Path.

Catcher: Caught!



Blue with prob. 1/2. Green with prob. 1/2.

Catcher:



Blue with prob. 1/2. Green with prob. 1/2.

Catcher: Caught!



Blue with prob. 1/3. Green with prob. 1/6. Pink with prob. 1/2.

Catcher:



Blue with prob. 1/3. Green with prob. 1/6. Pink with prob. 1/2.

Catcher: Caught, sometimes. With probability 1/2.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.)

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

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Defense:

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path?

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut. **Minimum cut** allows the maximum toll on any edge!

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut. **Minimum cut** allows the maximum toll on any edge!

What should "catch me" do to avoid catcher?

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut. **Minimum cut** allows the maximum toll on any edge!

What should "catch me" do to avoid catcher? minimize maximum load on any edge!

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut. **Minimum cut** allows the maximum toll on any edge!

What should "catch me" do to avoid catcher? minimize maximum load on any edge! Max-Flow Problem.

Row solution: $Pr[p_1] = 1/2$, $Pr[p_2] = 1/3$, $Pr[p_3] = 1/6$. Edge solution: $Pr[e_1] = 1/2$, $Pr[e_2] = 1/2$

Offense (Best Response.):

Catch me: route along shortest path. (Knows catcher's distribution.) Catcher: raise toll on most congested edge. (Knows catch me's distribution.)

Defense:

Where should "catcher" play to catch any path? a cut. **Minimum cut** allows the maximum toll on any edge!

What should "catch me" do to avoid catcher? minimize maximum load on any edge! Max-Flow Problem.

Note: exponentially many strategies for "catch me"!

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path. Matrix:

row for each routing: r

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path. Matrix:

row for each routing: r

column for each edge: e

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix:

row for each routing: r

column for each edge: e

A[r, e] is congestion on edge e by routing r

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix:

row for each routing: r

column for each edge: e

A[r, e] is congestion on edge e by routing r

```
Offense: (Best Response.)
```

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix:

row for each routing: r

column for each edge: e

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths.

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix:

row for each routing: r

column for each edge: e

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths. Toll: charge most loaded edge.

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix: row for each routing: r

column for each edge: e

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths. Toll: charge most loaded edge.

Defense: Toll: maximize shortest path under tolls.

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix: row for each routing: *r* column for each edge: *e*

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths. Toll: charge most loaded edge.

Defense: Toll: maximize shortest path under tolls. Route: minimize max loaded on any edge.
Toll/Congestion

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix: row for each routing: *r* column for each edge: *e*

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths. Toll: charge most loaded edge.

Defense: Toll: maximize shortest path under tolls. Route: minimize max loaded on any edge.

Toll/Congestion

Given: G = (V, E). Given $(s_1, t_1) \dots (s_k, t_k)$. Row: choose routing of all paths. Column: choose edge. Row pays if column chooses edge on any path.

Matrix: row for each routing: *r* column for each edge: *e*

A[r, e] is congestion on edge e by routing r

Offense: (Best Response.)

Router: route along shortest paths. Toll: charge most loaded edge.

Defense: Toll: maximize shortest path under tolls. Route: minimize max loaded on any edge.

Again: exponential number of paths for route player.



You should now know about



You should now know about

Games



You should now know about

Games Nash Equilibrium

You should now know about

Games Nash Equilibrium Pure Strategies

You should now know about

Games Nash Equilibrium Pure Strategies Zero Sum Two Person Games

You should now know about

Games Nash Equilibrium Pure Strategies Zero Sum Two Person Games Mixed Strategies.

You should now know about

Games Nash Equilibrium Pure Strategies Zero Sum Two Person Games Mixed Strategies. Checking Equilibrium.

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Games Nash Equilibrium Pure Strategies Zero Sum Two Person Games Mixed Strategies. Checking Equilibrium. Best Response.

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Today





Undergraduate: saw maximum matching!



Undergraduate: saw maximum matching! (hopefully.)



Undergraduate: saw maximum matching! (hopefully.) Will review.

Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find a maximum weight matching.

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```
Blue – 3. Green - 2,
Black - 1, Non-edges - 0.
```

Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find a maximum weight matching.

A matching is a set of edges where no two share an endpoint.



```
Blue – 3. Green - 2,
Black - 1, Non-edges - 0.
```

Solution Value: 7.

Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find a maximum weight matching.

A matching is a set of edges where no two share an endpoint.



Blue – 3. Green - 2, Black - 1, Non-edges - 0. Solution Value: 7. Solution Value: 7.

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Blue – 3. Green - 2, Black - 1, Non-edges - 0. Solution Value: 7. Solution Value: 7. Solution Value: 8.

Jobs to workers.

Jobs to workers.

Teachers to classes.

Jobs to workers.

Teachers to classes.

Classes to classrooms.

Jobs to workers.

Teachers to classes.

Classes to classrooms.

"The assignment problem"

Jobs to workers.

Teachers to classes.

Classes to classrooms.

"The assignment problem"

Min Weight Matching.

Jobs to workers.

Teachers to classes.

Classes to classrooms.

"The assignment problem"

Min Weight Matching.

Negate values and find maximum weight matching.

Vertex Cover

Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find an vertex cover function of minimum total value.

Vertex Cover

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A function $p: V \rightarrow R$, where for all edges, e = (u, v), $p(u) + p(v) \ge w(e)$.
Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find an vertex cover function of minimum total value.

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Solution Value: 12.

Given a bipartite graph, G = (U, V, E), with edge weights $w : E \to R$, find an vertex cover function of minimum total value.

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Solution Value: 12.

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Solution Value: 9.

Solution Value: 8.

Feasible $p(\cdot)$,

```
Feasible p(\cdot), for edge e = (u, v), p(u) + p(v) \ge w(e).

u - w(e) - v

p(u) - p(v)
```

Feasible
$$p(\cdot)$$
, for edge $e = (u, v)$, $p(u) + p(v) \ge w(e)$.
 $u - w(e) - v$
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$$\sum_{e=(u,v)\in M} w(e)$$

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Feasible p(\cdot), for edge e = (u, v), p(u) + p(v) \ge w(e).

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p(u) - p(v)
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$$\sum_{\boldsymbol{e}=(u,v)\in M} w(\boldsymbol{e}) \leq \sum_{\boldsymbol{e}=(u,v)\in M} (p(u)+p(v))$$

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 $u - w(e) - v$
 $p(u) - p(v)$

$$\sum_{e=(u,v)\in M} w(e) \leq \sum_{e=(u,v)\in M} (p(u)+p(v)) \leq \sum_{u\in U} p(u) + \sum_{v\in V} p(v)$$

Feasible
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For a matching M, each u is the endpoint of at most one edge in M.

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Holds with equality if

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Holds with equality if

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Holds with equality if

for $e \in M$, w(e) = p(u) + p(v) (Defn: tight edge.) and perfect matching.



Blue edge -2, Others -1.



Blue edge – 2, Others – 1. Using max incident edge. Value: 3.





Blue edge – 2, Others – 1.
Using max incident edge.
Value: 3.
Using max incident edge.
Value: 2.
Same as optimal matching!
Proof of optimality.



Blue edge – 2, Others – 1.
Using max incident edge.
Value: 3.
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Proof of optimality.

 $\begin{array}{c} 0 \quad a \quad x \quad 1 \\ 1 \quad b \quad y \quad 0 \\ \text{Matching and cover are optimal,} \end{array}$



0 (a

1 (b

Blue edge – 2, Others – 1.

Using max incident edge.

Value: 3. Using max incident edge.

Value: 2. Same as optimal matching!

Proof of optimality.

Matching and cover are optimal,

0

x) 1

edges in matching have w(e) = p(u) + p(v). Tight edge.



х

0 (a

1 (b

Blue edge – 2, Others – 1.

Using max incident edge.

Value: 3. Using max incident edge.

Value: 2. Same as optimal matching!

Proof of optimality.

Matching and cover are optimal, edges in matching have w(e) = p(u) + p(v). Tight edge. all nodes are matched.

0

Given a bipartite graph, G = (U, V, E), find a maximum sized matching.

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Key Idea: Augmenting Alternating Paths.

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Example:



Start at unmatched node(s), follow unmatched edge(s), follow matched. Repeat until an unmatched node.

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Example:



Start at unmatched node(s), follow unmatched edge(s), follow matched. Repeat until an unmatched node.



Can't increase matching size. No alternating path from (a) to (y).



Can't increase matching size. No alternating path from (a) to (y).

Cut!



Can't increase matching size. No alternating path from (a) to (y).

Cut!

Still no augmenting path. Still Cut?


Algorithm:

Can't increase matching size. No alternating path from (a) to (y).

Cut!

Still no augmenting path. Still Cut?

Use directed graph! Cut in this graph.



Algorithm: Given matching. Can't increase matching size. No alternating path from (a) to (y).

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Can't increase matching size. No alternating path from (a) to (y).

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Algorithm: Given matching. Direct unmatched edges *U* to *V*, matched *V* to *U*.



Can't increase matching size. No alternating path from (a) to (y).

Cut!

Still no augmenting path. Still Cut?

Use directed graph! Cut in this graph.

Algorithm: Given matching. Direct unmatched edges *U* to *V*, matched *V* to *U*. Find path between unmatched nodes on left to right. (BFS, DFS).



Can't increase matching size. No alternating path from (a) to (y).

Cut!

Still no augmenting path. Still Cut?

Use directed graph! Cut in this graph.

Algorithm: Given matching. Direct unmatched edges *U* to *V*, matched *V* to *U*. Find path between unmatched nodes on left to right. (BFS, DFS). Until everything matched



Can't increase matching size. No alternating path from (a) to (y).

Cut!

Still no augmenting path. Still Cut?

Use directed graph! Cut in this graph.

Algorithm: Given matching. Direct unmatched edges *U* to *V*, matched *V* to *U*. Find path between unmatched nodes on left to right. (BFS, DFS). Until everything matched ... or output a cut.

Want vertex cover (price function) $p(\cdot)$ and matching where.

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Optimal solutions to both if for $e \in M$, w(e) = p(u) + p(v) (Defn: tight edge.) and

Want vertex cover (price function) $p(\cdot)$ and matching where.

Optimal solutions to both if for $e \in M$, w(e) = p(u) + p(v) (Defn: tight edge.) and perfect matching.

Goal: perfect matching on tight edges.

Goal: perfect matching on tight edges. Algorithm

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Init: empty matching, feasible cover function $(p(\cdot))$

Goal: perfect matching on tight edges. Algorithm

Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching.

Goal: perfect matching on tight edges. Algorithm

Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges.

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Goal: perfect matching on tight edges. Algorithm



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Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

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Goal: perfect matching on tight edges. Algorithm



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Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U ,

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V ,

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V , all explored edges still tight, matched edges still tight

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V , all explored edges still tight, matched edges still tight ... and get new tight edge!

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function $(p(\cdot))$

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V , all explored edges still tight, matched edges still tight ... and get new tight edge! What's delta?

Goal: perfect matching on tight edges. Algorithm



Init: empty matching, feasible cover function ($p(\cdot)$)

Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

No augmenting path.

Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V , all explored edges still tight, matched edges still tight ... and get new tight edge! What's delta? $w(e) < p(u) + p(v) \rightarrow$

Goal: perfect matching on tight edges. Algorithm



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Add tight edges to matching. Use alt./aug. paths of tight edges. "maximum matching algorithm."

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Cut, (S, T), in directed graph of tight edges!

All edges across cut are not tight. (loose?)

Nontight edges leaving cut, go from S_U , T_V .

Lower prices in S_U , raise prices in S_V , all explored edges still tight, matched edges still tight ... and get new tight edge! What's delta? $w(e) < p(u) + p(v) \rightarrow \delta = \min_{e \in (S_U \times T_V)} p(u) + p(v) - w(e)$.

Add 0 value edges, so that optimal solution contains perfect matching.

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Add 0 value edges, so that optimal solution contains perfect matching.

```
Beginning "Matcher" Solution: M = \{\}.
```

```
Feasible! Value = 0.
```

```
Beginning "Coverer" Solution:
p(u) = maximum incident edge for u \in U,
```

Add 0 value edges, so that optimal solution contains perfect matching. Beginning "Matcher" Solution: $M = \{\}$.

Feasible! Value = 0.

Beginning "Coverer" Solution: p(u) = maximum incident edge for $u \in U$, 0 otherwise.

Add 0 value edges, so that optimal solution contains perfect matching.

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Beginning "Matcher" Solution: M = \{\}.
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Beginning "Coverer" Solution:

p(u) = maximum incident edge for u \in U, 0 otherwise.

Main Work:
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Beginning "Matcher" Solution: M = \{\}.
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Beginning "Coverer" Solution: p(u) = maximum incident edge for $u \in U$, 0 otherwise.

Main Work:

breadth first search from unmatched nodes finds cut.
Add 0 value edges, so that optimal solution contains perfect matching.

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Beginning "Matcher" Solution: M = \{\}.
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Beginning "Coverer" Solution: p(u) =maximum incident edge for $u \in U$, 0 otherwise.

Main Work:

breadth first search from unmatched nodes finds cut. Update prices (find minimum delta.)

Add 0 value edges, so that optimal solution contains perfect matching.

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Beginning "Matcher" Solution: M = \{\}.
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Main Work:

breadth first search from unmatched nodes finds cut. Update prices (find minimum delta.)

Simple Implementation:

Each bfs either augments or adds node to S in next cut.

Add 0 value edges, so that optimal solution contains perfect matching.

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breadth first search from unmatched nodes finds cut. Update prices (find minimum delta.)

Simple Implementation:

Each bfs either augments or adds node to S in next cut.

O(n) iterations per augmentation.

Add 0 value edges, so that optimal solution contains perfect matching.

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breadth first search from unmatched nodes finds cut. Update prices (find minimum delta.)

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O(n) iterations per augmentation.

O(n) augmentations.

 $O(n^2m)$ time.

Weight legend: black 1, green 2, blue 3





Weight legend: black 1, green 2, blue 3 Tight edges for inital prices.



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched.



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight!



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges.



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$

а

b

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d





Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight.





Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge.





Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...





Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...



All matched edges tight.

Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...



All matched edges tight. Perfect matching. Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...



All matched edges tight. Perfect matching. Feasible price function. Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...



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.. and finally: a perfect matching.

All matched edges tight. Perfect matching. Feasible price function. Values the same.



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...

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.. and finally: a perfect matching.

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Perfect matching. Feasible price function. Values the same. Optimal! Notice:



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...

.. and finally: a perfect matching.

All matched edges tight.

Perfect matching. Feasible price function. Values the same. Optimal!

Notice:

no weights on the right problem.



Weight legend: black 1, green 2, blue 3 Tight edges for inital prices. Max matching in tight edges. dashed means matched. No augmenting path \rightarrow reachable: $S = \{u, v\}$ Blue edge on right soon to be tight! Adjust prices... $\delta = 1$ new tight edges. Still no augmenting path. Reachable $S = \{v, w, x, a\}$ Blue edges minimally non-tight. Adjust prices. Some more tight edges. And X shows a "new" nontight edge. .. and another augmentation ...

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no weights on the right problem.

retain previous matching through price changes.

retains edges in failed search through price changes.

Unweighted matching algorithm to weighted.

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How?

Unweighted matching algorithm to weighted.

How?

Use duality.

Unweighted matching algorithm to weighted.

How?

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In this case:

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How?

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In this case:

Dual feasible.

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How?

Use duality.

In this case: Dual feasible. Primal infeasible.

Unweighted matching algorithm to weighted.

How?

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Primal only "plays" tight constraints.

Unweighted matching algorithm to weighted.

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In this case:

Dual feasible.

Primal infeasible.

Primal only "plays" tight constraints. Best offense. Terminate when perfect matching.

Unweighted matching algorithm to weighted.

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 \rightarrow Dual only plays tight constraints.

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How?

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Dual's best offense.
Some thoughts..

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Unweighted matching algorithm to weighted.

How?

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Primal only "plays" tight constraints. Best offense. Terminate when perfect matching.

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Dual's best offense.

Equilibrium.

...see you on Tuesday