

Nash's Theorem

N players.

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Each player has strategy set. $\{S_1, \ldots, S_N\}$.

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Vector valued payoff function: $u(s_1,...,s_n)$ (e.g., $\in \mathfrak{R}^N$).

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Example:

2 players

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2 players

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Player 1: { Defect, Cooperate }.
Player 2: { Defect, Cooperate }.
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Example:

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```
\label{eq:powerset} \begin{array}{l} \mbox{Player 1: } \{ \mbox{ } \mbox{Defect, Cooperate } \}. \\ \mbox{Player 2: } \{ \mbox{ } \mbox{Defect, Cooperate } \}. \end{array}
```

Payoff:

```
        C
        D

        C
        (3,3)
        (0,5)

        D
        (5,0)
        (1,1)
```

Both cooperate. Payoff (3,3).

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If player 1 wants to do better, what does she do?

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Defects! Payoff (5,0)

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What is the best thing for the players to do?

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If player 1 wants to do better, what does she do?

Defects! Payoff (5,0)

What does player 2 do now?

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Stable now!

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Nash Equilibrium:

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What does player 2 do now?

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Defects! Payoff (.1,.1).
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Stable now!

Nash Equilibrium: neither player has incentive to change strategy.

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Player *i* has strategy set $\{1, \ldots, m_i\}$.

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Mixed strategy for player *i*: x_i is vector over strategy set.

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 $\forall i \forall x'_i, u_i(x_{-i}; x'_i) \leq u_i(x).$ (1)

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What is x? A vector of vectors: vector *i* is length m_i .

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What is x? A vector of vectors: vector *i* is length m_i . What is x_{-i} ; *z*?

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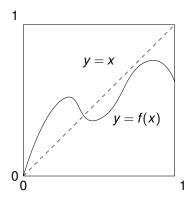
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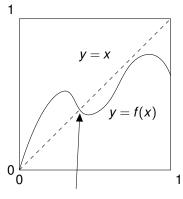
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Theorem: There is a Nash Equilibrium.

Theorem: Every continuous function from a closed compact convex (c.c.c.) set to itself has a fixed point.



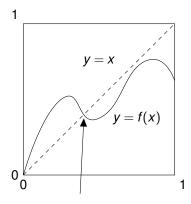
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Fixed point!

What is the closed convex set here?

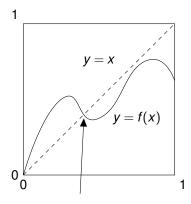
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Fixed point!

What is the closed convex set here? The unit square?

Theorem: Every continuous function from a closed compact convex (c.c.c.) set to itself has a fixed point.



Fixed point!

What is the closed convex set here? The unit square? Or the unit interval?

Brouwer implies Nash.

The set of mixed strategies *x* is closed convex set.

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That is, $x = (x_1, ..., x_n)$ where $|x_i|_1 = 1$.

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 z_i is continuous in x.

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Mixed strategy utilities is polynomial of entries of x

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Mixed strategy utilities is polynomial of entries of *x* with coefficients being payoffs in game matrix.

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Brouwer:

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Brouwer: Has a fixed point: $\phi(\hat{z}) = \hat{z}$.

Define $\phi(x_1,\ldots,x_n) = (z_1,\ldots,z_n)$

Define
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Define
$$\phi(x_1, \dots, x_n) = (z_1, \dots, z_n)$$

where $z_i = \arg \max_{z'_i} \left[u_i(x_{-i;z'_i}) - ||z_i - x_i||_2^2 \right]$.
Question: which way will it go?

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Question: which way will it go? Some pure strategy is (tied for) best response.

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Change coordinates proportional to utility differences.

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Which way will it go?

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Tradeoffs squared penalty function against benefit in utility.

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Looks like a gradient.

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This is (another) property of the quadratic "regularizer."

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Technically: need to project back to feasible set.

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This is (another) property of the quadratic "regularizer."

Technically: need to project back to feasible set. Distribution for each player.

$$\phi(x_1,...,x_n) = (z_1,...,z_n) \text{ where} \\ z_i = \arg\max_{z'_i} \left[u_i(x_{-i;z'_i}) - \|z_i - x_i\|_2^2 \right].$$

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Fixed point: $\phi(\hat{z}) = \hat{z}$

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If \hat{z} not Nash, there is i, y_i where $u_i(\hat{z}_{-i}; y_i) > u_i(\hat{z}) + \delta$.

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$$\begin{split} u_i(\hat{z}_{-i};y_i) &> u_i(\hat{z}) + \delta.\\ \text{Consider } \hat{y}_i &= (1-\alpha)\hat{z}_i + \alpha(y_i - \hat{z}_i).\\ (1-\alpha)u_i(\hat{z}_{-i};\hat{y}_i) + \|\hat{z}_i - \hat{y}_i\|^2?\\ (1-\alpha)u_i(\hat{z}) + \alpha(u_i(\hat{z}) + \delta) - \alpha^2 \|\hat{z}_i - y_i\|^2 \end{split}$$

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 $= u_{i}(\hat{z}) + \alpha\delta - \alpha^{2}\|y_{i} - \hat{z}_{i}\|^{2} > u_{i}(\hat{z}).$

$$\phi(x_1,...,x_n) = (z_1,...,z_n) \text{ where} \\ z_i = \arg\max_{z'_i} \left[u_i(x_{-i;z'_i}) - \|z_i - x_i\|_2^2 \right].$$

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Fixed point: $\phi(\hat{z}) = \hat{z}$

If \hat{z} not Nash, there is i, y_i where

$$\begin{split} u_i(\hat{z}_{-i};y_i) &> u_i(\hat{z}) + \delta.\\ \text{Consider } \hat{y}_i &= (1-\alpha)\hat{z}_i + \alpha(y_i - \hat{z}_i).\\ (1-\alpha)u_i(\hat{z}_{-i};\hat{y}_i) + \|\hat{z}_i - \hat{y}_i\|^2?\\ &\quad (1-\alpha)u_i(\hat{z}) + \alpha(u_i(\hat{z}) + \delta) - \alpha^2 \|\hat{z}_i - y_i\|^2\\ &\quad = u_i(\hat{z}) + \alpha\delta - \alpha^2 \|y_i - \hat{z}_i\|^2 > u_i(\hat{z}). \end{split}$$

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Proof of Brouwer: outline.

Sperner: any subdivision of a simplex and "proper" coloring of its vertices

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By induction!

One dimension:

One dimension: Subdivision of [0,1].

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Endpoints colored differently. Odd number of multicolored edges.

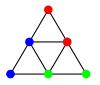
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Two dimensions.



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> Two dimensions. Consider (r,g) edges. Separates two regions.



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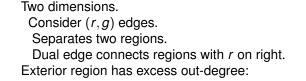
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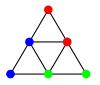
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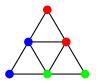
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Two dimensions. Consider (r,g) edges. Separates two regions. Dual edge connects regions with *r* on right. Exterior region has excess out-degree: one more (r,g) than (g,r).

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Two dimensions. Consider (r,g) edges. Separates two regions. Dual edge connects regions with r on right. Exterior region has excess out-degree: one more (r,g) than (g,r). There exist a region with excess in-degree.

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Proof of Sperner's.

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Assign smallest *i* with $f(x)_i < x_i$.

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Gives upper bound on α . $O(\log n)$ approximation.

Dual linear program.

Toll problem.

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Assign d(e) for edge $e \in E$ with $\sum_{e} d(e) = 1$, to maximize $\sum_{i,j} d(i,j)$.

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Theorem: The value of the dual is $O(\frac{\log n}{\alpha})$.

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Problem is that it is not "balanced."

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Claim: Exists a cut, *S*, where $d(S_{\ell}) \ge D_i$ and $E(S, |S|) \le \frac{2D_i \log n}{\Delta}$

Region Growing.

Lemma: $\exists x, y \ d(x, y) \ge \Delta \implies \text{cut}, S$, where $|E(S, \overline{S})| \le O(\frac{d(S)\log n}{n})$. Extend, $d(\cdot)$ to vertices: $d(v) = \frac{\sum_e d(e)}{n}$. Let S_{ℓ} be v where $d(x, v) \leq \ell$. Define $D(x, \ell)$ to be the sum of: (1) d(v) for $v \in S_{\ell}$. (2) For e = (u, v), d(e) where $u, v \in S_{\ell}$ (3) For e = (u, v), $u \in S_{\ell}$, $v \notin S_{\ell}$, $\ell - d(u)$. W.L.O.G. $D(x, \Delta/2) < \frac{2\sum_e d(e)}{2}$. Ball contains < half the weight. Let $D_i = D(x, i \frac{\Delta}{(2 \log n)})$. Claim: Exists *i* such that $D_{i+1} \leq 2D_i$.

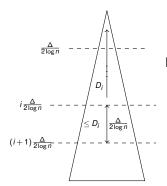
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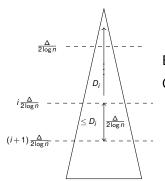
Region Growing.

Lemma: $\exists x, y \ d(x, y) \ge \Delta \implies \text{cut}, S$, where $|E(S, \overline{S})| \le O(\frac{d(S)\log n}{n})$. Extend, $d(\cdot)$ to vertices: $d(v) = \frac{\sum_e d(e)}{n}$. Let S_{ℓ} be v where $d(x, v) \leq \ell$. Define $D(x, \ell)$ to be the sum of: (1) d(v) for $v \in S_{\ell}$. (2) For e = (u, v), d(e) where $u, v \in S_{\ell}$ (3) For e = (u, v), $u \in S_{\ell}$, $v \notin S_{\ell}$, $\ell - d(u)$. W.L.O.G. $D(x, \Delta/2) < \frac{2\sum_e d(e)}{2}$. Ball contains < half the weight. Let $D_i = D(x, i \frac{\Delta}{(2 \log n)})$. Claim: Exists *i* such that $D_{i+1} \leq 2D_i$. Proof: Can't double more than log *n* times. Claim: Exists a cut, *S*, where $d(S_{\ell}) \ge D_i$ and $E(S, |S|) < \frac{2D_i \log n}{r}$

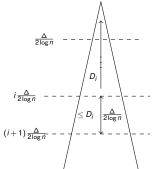
Proof: Interval *i*: has length $\frac{\Delta}{2\log n}$ and area $\leq D_i$ Width $\frac{2D_i \log n}{2}$.



Claim: Exists cut, *S*, such that $E(S, \overline{(S)}) \leq \frac{2D(S)\log n}{\Lambda}$



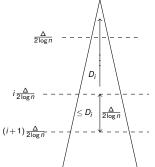
Claim: Exists cut, *S*, such that $E(S, \overline{(S)}) \leq \frac{2D(S)\log n}{\Delta}$ Call d(e) weight.



Claim:

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Exists some *i*, where weight, $D_{i+1} - D_i \le D_i$.

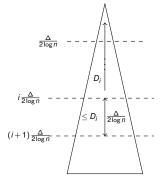


Claim:

Exists cut, *S*, such that $E(S, \overline{(S)}) \leq \frac{2D(S)\log n}{\Delta}$

Call d(e) weight.

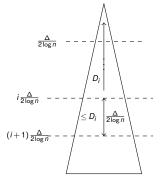
Exists some *i*, where weight, $D_{i+1} - D_i \le D_i$. Weight is like Area: Cut-size × length.



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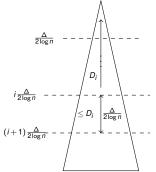
Cut-size \leq Area/length $= \frac{D_i}{\Delta/2 \log n}$



Claim:

Exists cut, *S*, such that $E(S, \overline{(S)}) \leq \frac{2D(S)\log n}{\Delta}$ Call d(e) weight. Exists some *i*, where weight, $D_{i+1} - D_i \leq D_i$. Weight is like Area: Cut-size × length.

Cut-size \leq Area/length $= \frac{D_i}{\Delta/2\log n} = \frac{2D_i}{\log n}$



Claim:

Exists cut, *S*, such that $E(S, \overline{(S)}) \leq \frac{2D(S)\log n}{\Delta}$

Call d(e) weight.

Exists some *i*, where weight, $D_{i+1} - D_i \le D_i$. Weight is like Area: Cut-size × length. Cut-size \le Area/length $= \frac{D_i}{\Delta/2\log n} = \frac{2D_i}{\log n}$

Done.

Claim:
$$\frac{E(S,\overline{S})}{D(S)} \leq \frac{2\log n}{\Delta}$$
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Claim:
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Linear program value: $\sum_{i,j} d(i,j) \ge \alpha = \min_{S} \frac{E(S,S)}{|S||S|}$. There exists vertex *i*,*j*, where $d(i,j) = \Delta = \ge \alpha/n^2$.

$$\implies \frac{E(S,\overline{S})}{n^2 D(S)} \leq \frac{2\log n}{\alpha}.$$

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Scenario: $D(S) = \Omega(1)$ and $|S| = \Omega(n)$. Finds cut of sparsity $O(\log n/\alpha)$.

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 $O(\log n)$ approximation.

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Linear program value: $\sum_{i,j} d(i,j) \ge \alpha = \min_{S} \frac{E(S,S)}{|S||S|}$.

There exists vertex *i*,*j*, where $d(i,j) = \Delta = \ge \alpha/n^2$.

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Scenario: $D(S) = \Omega(1)$ and $|S| = \Omega(n)$. Finds cut of sparsity $O(\log n/\alpha)$. Optimal is $\geq \frac{1}{\alpha}$.

 $O(\log n)$ approximation.

Do some averaging to get real result.

Low diameter decomposition.

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Procedure produces cluster of Diameter $O(\Delta)$.

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 $O(\frac{\log n}{\Delta})$ fraction of edges in between.

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Repeat until every vertex in a cluster.

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Repeat until every vertex in a cluster.

Produces:

Decompositon into low-diameter clusters: $O(\Delta)$.

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Edges between "Small": $\tilde{O}(\frac{1}{\Delta})$.

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 $\tilde{O}(\cdot)$ hides log factors.