function FIND-TRANSFORM($p_1, p_2, p_3, \mu_1, \mu_2, \mu_3$) **returns** a transform Q such that

$$Q(\mu_1) = p_1$$
$$Q(\mu_2) = p_2$$
$$Q(\mu_3) = p_3$$

inputs: p_1, p_2, p_3, image feature points
μ_1, μ_2, μ_3, model feature points