of KCL, KVL
with algebraic expressions (if connected)
non-linear ordinary differential equations
first order
\{ \text{P-cells} \} \quad \text{Paramekrisi and Coda}
folded factor
\begin{align*}
\text{design rule checking (DRC)} \\
\text{layout via schematic LV5} \\
\text{simulation} \\
\text{place & route} \\
\text{synthesis of layout} \\
\text{scenarios editor} \\
\text{drawing/pedogos}
\end{align*}

\text{CAD tools}
enough another with no policy
or didn't happen
- overlap: this should happen
- the case
- lies the reason
DEC cicles for
concentrated
LVN might just have missed
I'm out, since our tasks should
be listed here you didn't
Dinability vertices you didn't miss
Analyses drives does
and arbitrary limitations
Design is about picking solutions

v(x)
∂r
∂t > 0
∂E
∂x = 0 (laplace)

4. process file (c[p](w[0])(v[p]))
Pick parameters
- some may be fixed by
- turned off
- fixed
- steady state
- small signal/Bode
- solutions

3. can synthesize & place/locate

2. generate layout from p-cells

1. draw p-cells

parameters, either

once you have topology(s) (characteristic
and

Simulate extract at low level
new via all geometry (meshes) (layout)

simultaneous

Simulate at low level
p-cells - save time, minimize mistakes
- makes hierarchy & re-use easier

- 2D actors
- 2D swapping
- 2D actor
- gap closer
- gap closer
- gap closer
- gap even

- BALLED
- 3D visual
- 3D visual
- 3D visual
- 3D visual