1. A single-pole amplifier has a low frequency gain of 10,000, and a gain of 5 at 1GHz. What are the pole frequency and unity gain frequency in Hz? What is the gain at 10MHz?
2. Write down a table of settling error vs. time for a single-pole system with $t/t_\tau=\{1, 3, 5, 7\}$. Use a calculator for this one. Memorize the table to one significant digit, for the rest of your life.
3. The parameters for a particular 0.5um CMOS process are $C_{ox}=5fF/\mu m^2$, $C'_{ol}=0.5fF/\mu m$, $\mu_nC_{ox}=200\mu A/V^2$, $\mu_pC_{ox}=100\mu A/V^2$, $\lambda=1/(10V)$ for $L=0.5\mu m$, $-V_{pp}=V_{in}=0.5V$, $V_{DD}=2V$. You are designing an NMOS-input common source amplifier with a PMOS load. The input capacitance of the next stage is 1pF. Assume that sub-threshold and inversion currents are equal when the overdrive voltage is 10mV.
   a. If $(W/L)_n=100/0.5$ and $(W/L)_p=200/0.5$ and $V_{IN}=0.7V$
      i. Using the quadratic model, carefully plot $I_{DS}$ vs. $V_{OUT}$ from 0 to VDD. Label the axes. Draw a dot to clearly separate the triode region from the saturation region. Is the quadratic model a good fit for this device and bias condition? Explain why or why not.
      ii. Calculate the PMOS gate bias such that the output bias point is at mid-rail (1V in this case). What are $V_{ovn}$ and $V_{ovp}$? Are they different? Why or why not?
      iii. Plot $|I_{DS}|$ vs. $V_{OUT}$ on the same plot as you used for the NMOS. Estimate the output voltage swing (the output voltage range over which both devices remain in saturation).
   b. For the same amplifier, if $V_{IN}=0.42V$, and the PMOS gate bias is set so that the output bias is at mid-rail
      i. What model should be used for the transistors?
      ii. Calculate the PMOS gate bias such that the output bias point is at mid-rail
      iii. Roughly what drain current will flow? (you can assume room temperature, and $n=1.5$)
      iv. Calculate $G_m$, $R_o$, $\omega_p$, and $\omega_h$ (assuming the input capacitance of the next stage dominates the output pole).
      v. Calculate $C_{gs}$, $C_{gd}$, and $C_{in}$ (don’t forget Miller) for this amplifier
      vi. If the amplifier were driven by another copy of itself, calculate the input pole frequency
   c. For the same amplifier, if $V_{IN}=1.5V$, output biased mid-rail
      i. What model should be used for the transistors?
      ii. Calculate the PMOS gate bias such that the output bias point is at mid-rail
      iii. What drain current will flow?
      iv. Calculate $G_m$, $R_o$, $\omega_p$, and $\omega_h$
      v. Calculate $C_{in}$
      vi. If the amplifier were driven by another copy of itself, calculate the input pole frequency
   d. Comment on the gain, bandwidth, and power consumption of these three operating points
4. An RC low pass filter with a time constant of 1$\mu$s is driven with a 0–1V square wave. Sketch the first full cycle of the input and output when the square wave is first turned on, and
   a. If the frequency of the square wave is 1kHz
   b. If the frequency of the square wave is 1MHz
   c. If the frequency of the square wave is 1GHz
5. A common source FET amplifier has a resistive load and $\lambda=1/(20V)$. If the output is biased at 5V, the transistor is in saturation, and the resistive load has the same impedance as the output resistance of the transistor. What is the supply voltage? (Draw a plot with the transistor drain current vs. output voltage near the output bias point, and the resistor load line to prove your point).
6. [not graded] Fill in the following table without a calculator (this will be on the midterm)

---

**Homework Assignment #3**

Due by online submission Thursday 2/13/2020 (Friday 9am)
7. [not graded] For a quadratic model MOSFET, sketch the following curves. No axis labels needed, but try to get the shape right, and label with something like “goes as \sqrt{X}” or “linear in X”, and label any axis intercept, e.g. "0" or "Vt". In each case, also sketch how the third variable of the set \{V_{GS}, W/L, I_D\} is changing as well.
   a. \(g_m\) vs. \(V_{GS}\) with \(W/L\) constant
   b. \(g_m\) vs. \(V_{GS}\) with \(I_D\) constant.
   c. \(g_m\) vs. \(I_D\) with \(W/L\) constant
   d. \(g_m\) vs. \(I_D\) with \(V_{GS}\) constant
   e. \(g_m\) vs \(W/L\) with \(I_D\) constant
   f. \(g_m\) vs. \(W/L\) with \(V_{GS}\) constant

<table>
<thead>
<tr>
<th>(A_{V0})</th>
<th>(\omega_p)</th>
<th>(\omega_u)</th>
<th>(g_m)</th>
<th>(r_o)</th>
<th>(C_L)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1000</td>
<td>1M</td>
<td></td>
<td></td>
<td></td>
<td>1p</td>
</tr>
<tr>
<td>1M</td>
<td>0.1G</td>
<td></td>
<td></td>
<td>100k</td>
<td></td>
</tr>
<tr>
<td></td>
<td>10G</td>
<td>1M</td>
<td>1M</td>
<td>20f</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>10M</td>
<td></td>
<td></td>
<td></td>
<td>10p</td>
</tr>
</tbody>
</table>