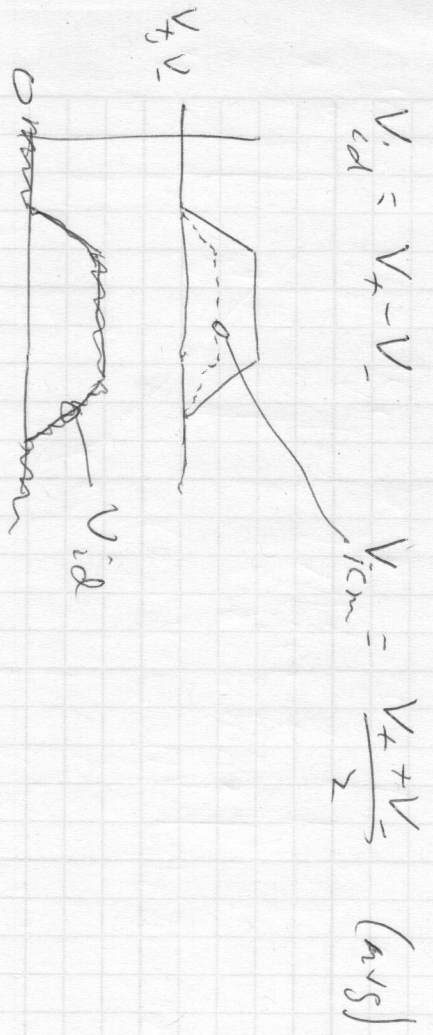


output stages - common in packaged op-amps
less common in embedded

differential & common mode signals
gain

input common mode range
output swing



$$V_{id} = V_+ - V_-$$

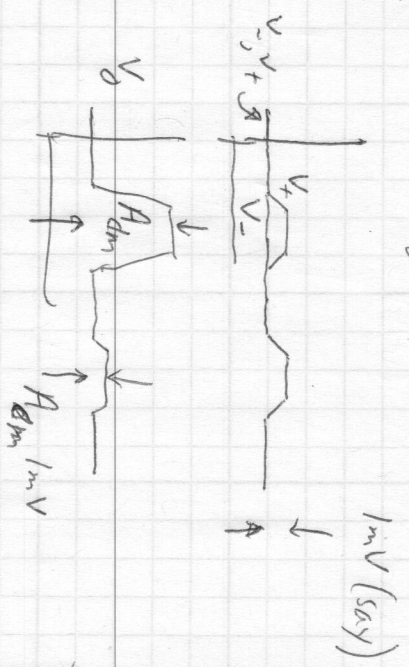
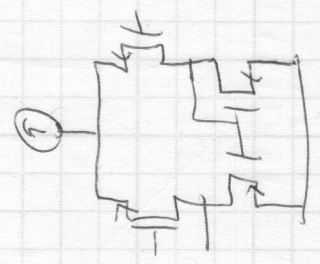
$$V_{cm} = \frac{V_+ + V_-}{2} \quad (\text{avg})$$

\$V_{tail} = V_{SI}\$ will track \$V_{ic}\$ (avg input)

So \$V_{gs1a} = V_+ - V_{tail} = \frac{V_{id}}{2}\$

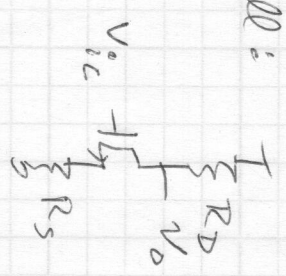
\$V_{gs1B} = -\frac{V_{id}}{2}\$

Single stage op-amp (or OTA)



What is the common mode gain?

Recall:



$$G_m = \frac{g_m}{1 + g_m R_s}$$

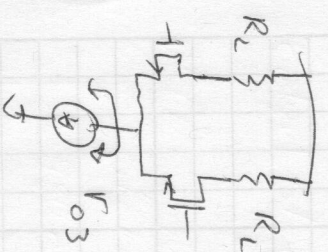
$$\approx \frac{1}{R_s} \quad \text{if } g_m R_s \gg 1$$

$$R_D = R_D \parallel ((1 + g_m r_o) R_s + r_o)$$

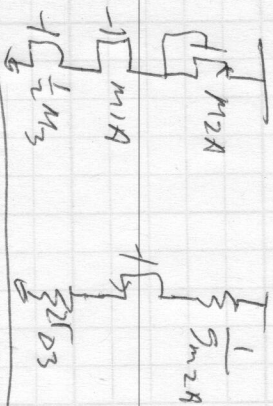
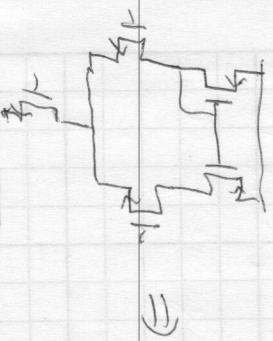
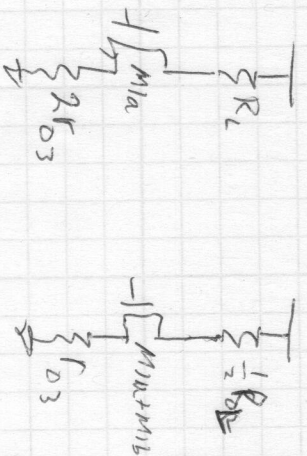
$$\approx R_D \quad \text{if } R_D \ll R_s$$

$$A_V = -G_m R_D = -\frac{R_D}{R_s}$$

What are \$R_D\$ and \$R_s\$?
(for diff amp)



1/2 circuits



$$V_{o+} = -1/g_{m1A} R_D = -g_{m1A} R_D \frac{V_{id}}{2}$$

$$V_{o-} = -1/g_{m1B} R_D = +g_{m1B} R_D \frac{V_{id}}{2}$$

$$V_o = V_{o+} - V_{o-} = -g_{m1} R_D V_{id}$$



differential in, differential out
 very useful, popular: 240B
 common mode feedback

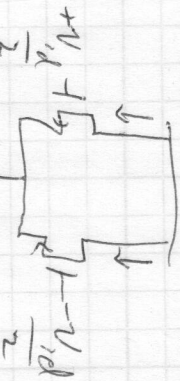
$$A_{V_{cm}} = \frac{-R_D}{R_S} = \frac{1/g_{m2A}}{2R_{D3}} = \frac{-1}{2g_{m2A} R_{D3}}$$

Common mode gain

$$V_o = A_{V_{cm}} V_{ic}$$

Differential mode gain

$$V_o = A_{V_{dm}} V_{id}$$

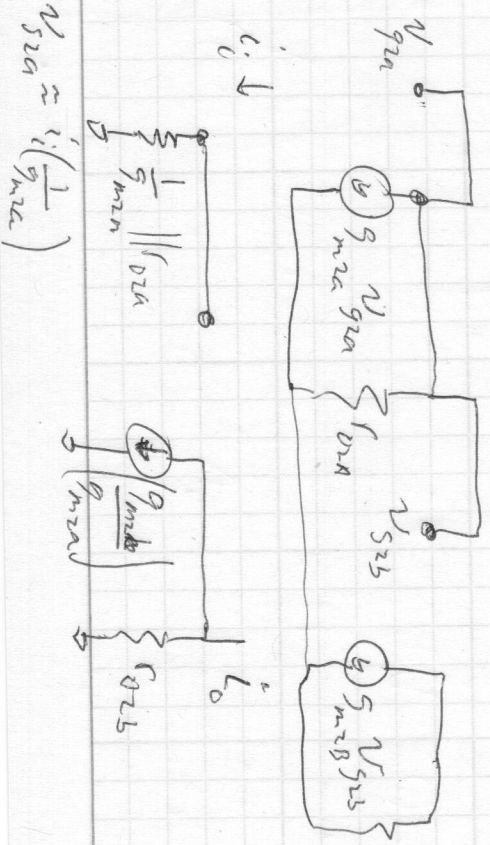
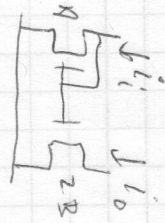
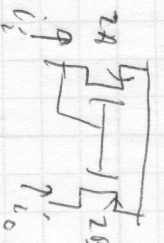


$$I_{d1A} = g_{m1A} (v_{id}/2)$$

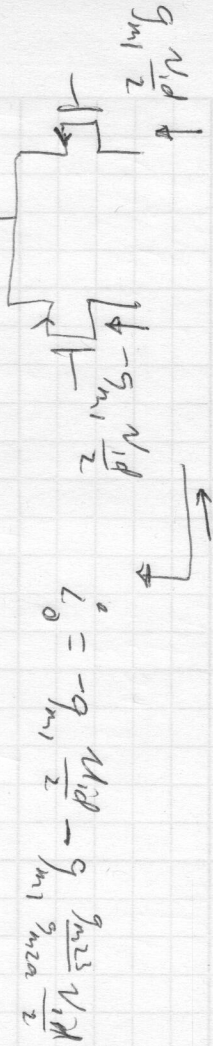
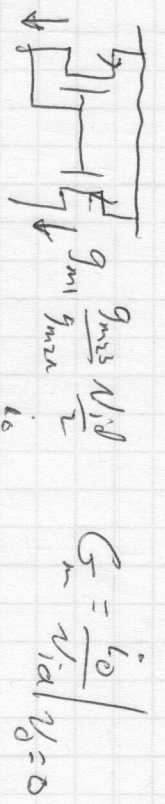
$$I_{d1B} = g_{m1B} (-v_{id}/2)$$

$$V_{tail} = 0$$

What about common mode level?



$$V_{S2A} \approx i_{ic} \left(\frac{1}{g_{m2A}} \right)$$



$$G_m = \frac{i_o}{v_{id}} \Big|_{v_o=0}$$

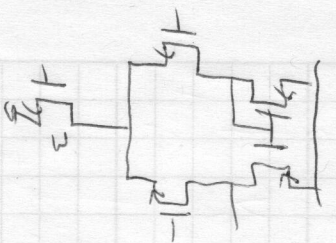
$$i_o = -g_{m1} \frac{v_{id}}{2} - g_{m2} \frac{v_{id}}{2}$$

$$\approx -g_{m1} v_{id}$$

$$G_m = -g_{m1}$$

wrong, but convenient

input common mode range.



$$V_{ic, min} = V_{tail, min} = V_{ov3}$$

$$V_{ic, min} = V_{tail, min} + (V_{tn} + V_{ov1})$$

$$V_{G2} = V_{DD} - |V_{tp}| - |V_{ov2}|$$

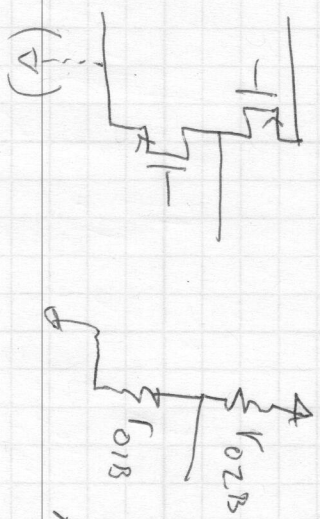
$$= V_{D1, max}$$

$$V_{ic, max} = V_{G2, max} = V_{D1, max} + V_{tn}$$

$$= V_{DD} + \underbrace{V_{tn} - |V_{tp}| - V_{ov2}}_{k_{fp} \approx 0}$$

$$R_o = \frac{v_o}{i_o} \Big|_{v_{id}=0}$$

node #1: $V_{tail} = 0$ (virtual ground-wrong)



$$R_D = r_{o2B} \parallel r_{o1B}$$

$$A_{v_{id}} = -(-g_{m1}) (r_{o1B} \parallel r_{o2B})$$

output swing

$$V_{o, max} = V_{DD} - |V_{ov2}|$$

$$V_{o, min} = V_{D1B, min}$$

$$= V_{G1B} - V_{tn}$$

$$= V_{ic} - V_{tn}$$

