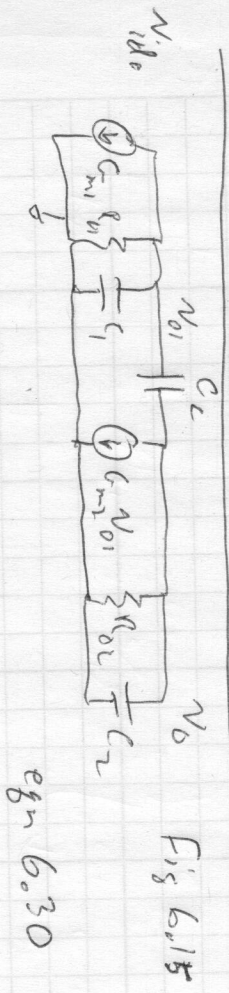


Miller Compensation  
& pole splitting

Slow rate

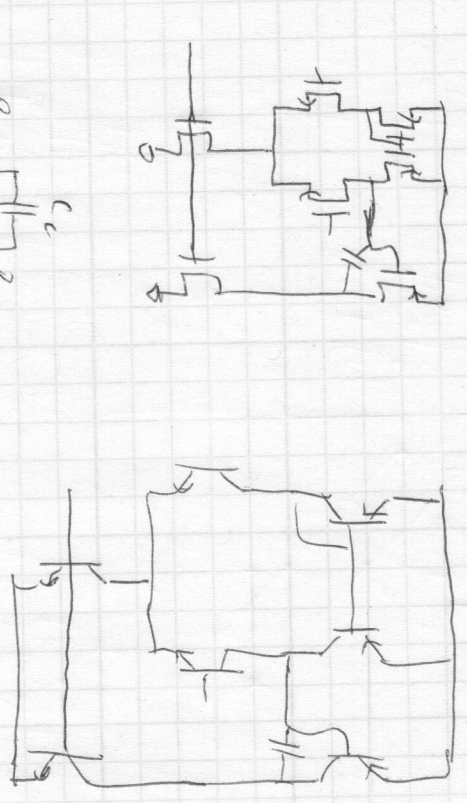


$$\frac{\omega_{p1,u}}{\omega_{p2,u}} = \frac{G_{m1} R_{o1} G_{m2} R_{o2}}{(1 + s/\omega_{p1}) (1 + s/\omega_{p2})}$$

typically before compensation ( $C_c$  small)

$$\omega_{p1,u} = \frac{1}{R_{o1} C_1}$$

$$\omega_{p2,u} = \frac{1}{R_{o2} C_2}$$



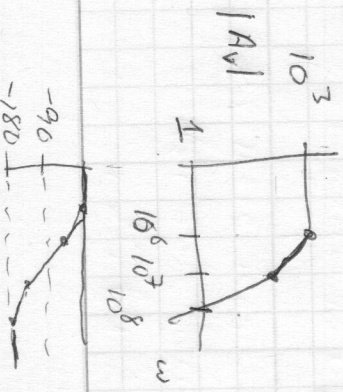
uncompensated = typically high gain w/ poles close together

⇒ Unstable in unity gain ( $f=1$ )

only stable if  $f < \frac{1}{A_0} \frac{\omega_{phys}}{\omega_{pole}}$  roughly

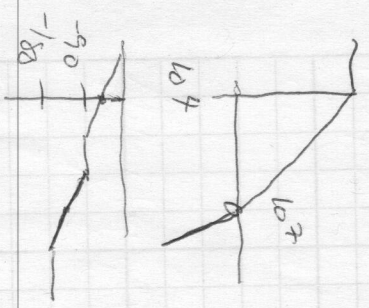
$f = 0.01$  OK ( $PM = 45^\circ$ )

what if we want a C.L. gain less than 100?

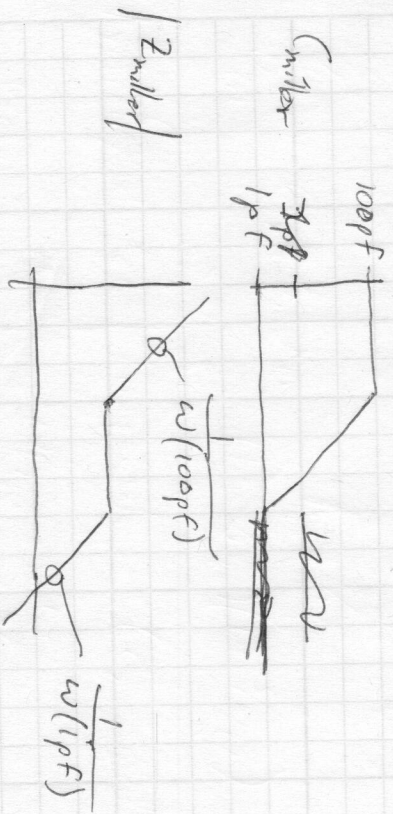
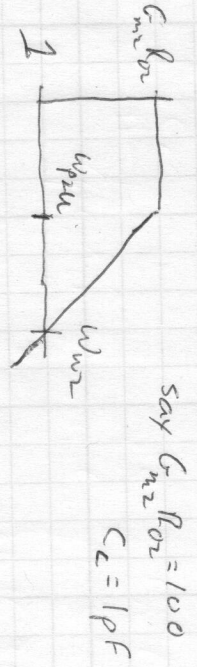


Compensation by lowering lowest pole

move  $\omega_{p1}$  left 2 decades

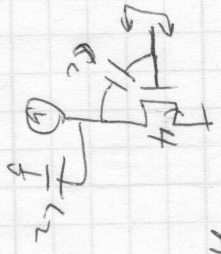


$f = 1 \Rightarrow PM = 45^\circ$   
 $BW \approx 10^7$   
 $\tau \approx 100ns$



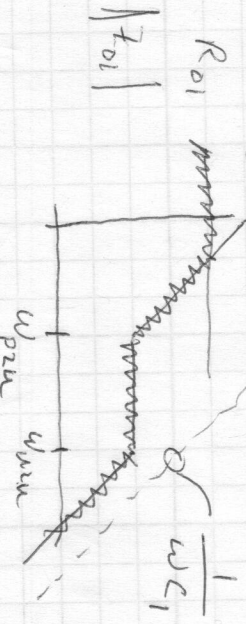
Better compensation by splitting the poles

push one down, push the other up



$A_{v2} = \frac{v_o}{v_i} = \frac{-g_m R_{o2}}{1 + s/\omega_{p2}}$   
 (also a RHP zero  $\omega_z = -\frac{g_m R_{o2}}{C_k}$ )  
 $\omega_{p2} \approx \frac{1}{R_{o2}(C_k + C_c)}$

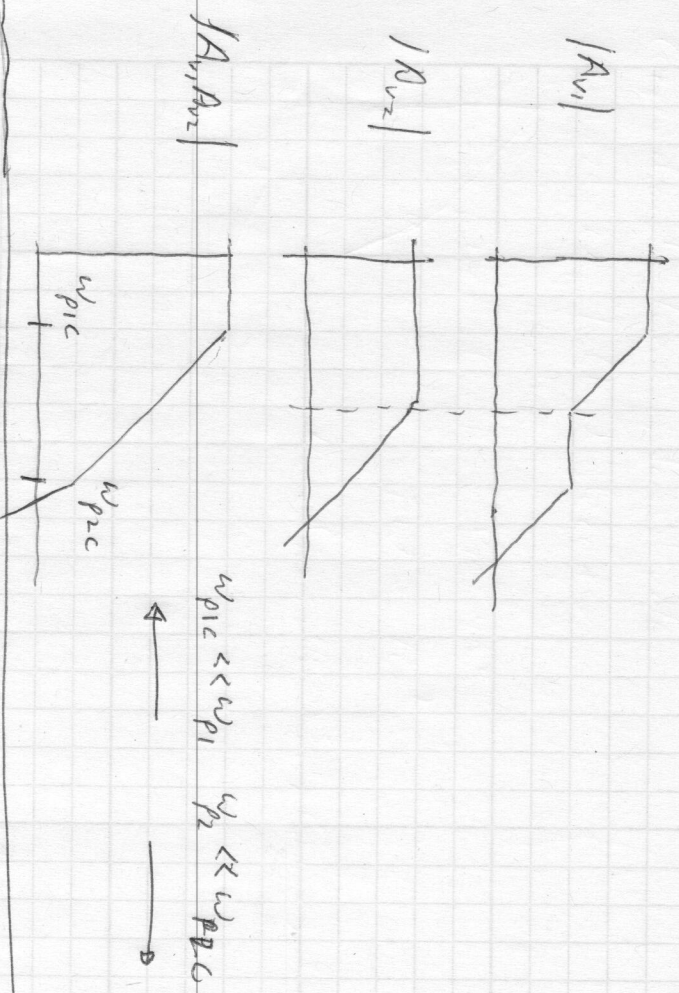
1st stage gain =  $-g_{m1} Z_{o1}$



4 regions:  $R_{o1}$ ,  $C_{miller}$ , transition,  $C_c$

pole, zero, pole

$\frac{1}{R_{o1} C_{miller}}$   
 $\omega_{pole}$   $\omega_{zero}$   $\omega_{pole}$



Slew rate non-linear effect, we model it as  $\omega_{p1} \omega_{p2}$

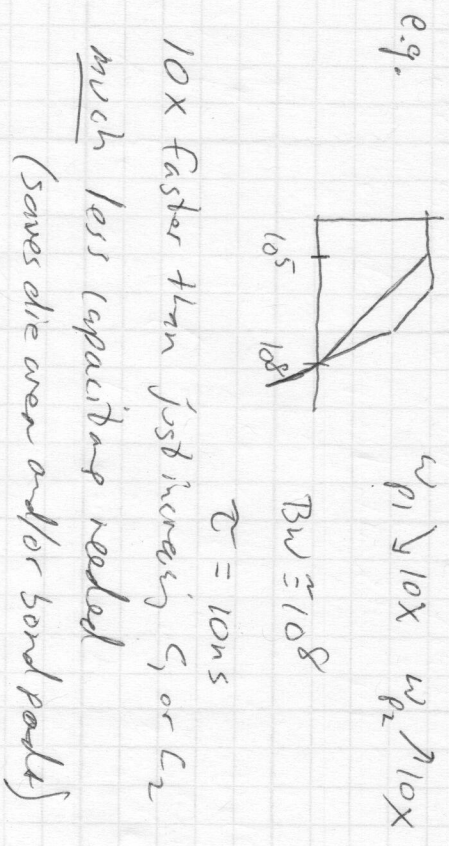
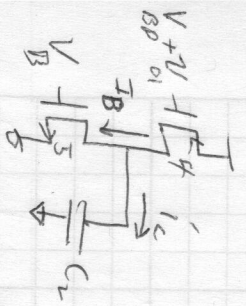
What if  $V_{DS}$  is so big that turns off?

$$\frac{dV_D}{dt} = \frac{i_C}{C_2}$$

if M4 turns off

$i_C = -I_B$  (bias current in M5)  $\approx$  const

$$\frac{dV_D}{dt} = -\frac{I_B}{C_2}$$



2 stage w/  $C_1$

