

Midterm Friday

OH

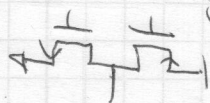
HW - self-grade

- HW4 solutions

CS design

Cascade

CS



$$|A_{vo}| = | -g_m R_d | = \frac{2I_D}{V_{ov}} \left(\frac{1}{\lambda_n I_D} + \frac{1}{\lambda_p I_D} \right)$$

$$\approx \frac{1}{\lambda V_{ov}} \quad \text{if } \lambda_n = \lambda_p$$

$$\lambda \approx \lambda_0 \frac{L_0}{L} \quad \text{roughly}$$

HW4 shows channel's

change in λ for 10x input

is $\frac{1}{\lambda I_D}$ a good model?

is V_{DSAT} a good model?

but smaller V_{ov} at fixed I_m means

larger $\frac{W}{L}$

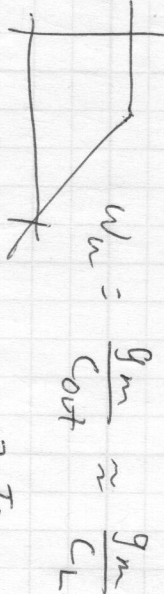
$$g_m = \text{const} = \mu_n C_{ox} \frac{W}{L} V_{ov}$$

$\Rightarrow$ more input capacitance

$\Rightarrow$ slower input pole or

higher power input driver

Specs A_{vo}



$$w_n = \frac{g_m}{C_{out}} \approx \frac{g_m}{C_L}$$

$$g_m = \frac{2I_D}{V_{ov}} = \mu_n C_{ox} \frac{W}{L} V_{ov}$$

minimum power:

smallest I_D w/ fixed $g_m = w_n C_L$

$\Rightarrow$ smallest $V_{ov} \approx 100mV$ (quadratic model)

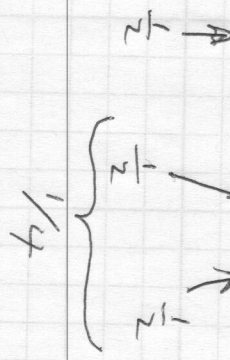
(can do a little better w/ weak inversion)
& $503-V_z$

with no gain constraint (any gain ok) then

double $V_{ov} \Rightarrow \frac{1}{2} \frac{W}{L} \Rightarrow \frac{1}{2} W$ (gm constraint)

$\Rightarrow \frac{1}{2} A_v (= \frac{1}{\lambda V_{ov}})$

$C_{in} = C_{gs} + (1-A)C_{gd}$



typically Miller C_{gd} dominated at low freq.

with gain constraint, word.

so double V_{ov} means $\frac{1}{2} \frac{W}{L}$ (unity gain const)

but $2L$, so W remains the same (gain constraint)

so $C_{in} = C_{gs} + (1-A)C_{gd}$

2x same same

low freq $C_{in} \approx$ same, a little bigger

high freq $C_{in} \approx C_{gs} = 2x$ bigger

but with a gain constraint

assume $\frac{1}{\lambda_0 V_{ov,min}} < A_{v,required}$

then must choose $L > L_0$ to sat

λ smaller to meet gain spec.

Now doubling V_{ov} means we need

λ to decrease by 2 (gain spec)

L to increase by 2 (λ model)

what if I need the lowest input cap?

big $V_{ov} - 5-10x V_{ov,min}$ (or nV_t)

5-10x C_{gs}, C_{gd} but terrible gain

options

- multiple stages
- OK, sub problems w/ coupling, power, stability
- cascode
- OK, sub problems w/ headroom (swing) and biasing

