

Pin 220, was page, 500182

Lab 1 LTSPICE

HW 1

Reading

notation convention

bias

$$V_a = V_A + v_a$$

$$I_b = I_B + i_b$$

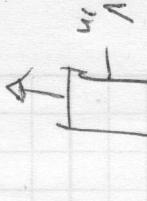
actual, total, instantaneous

small signal

BJT, MOS

I_{out}

V_{out}



weak dependence

$$V_{in} = V_{IN}$$

V_{out}

(to hundreds of volts for some.)

$$V_{in} = V_{IN} + 8V$$

$$V_{in} = V_{IN}$$

step control - 8V in millivolts

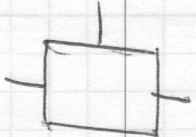
Devices

de forest 1911?

Lillienfeld 1927?

Budom, Borkman, Schockley 1947?

All have the same, properly:



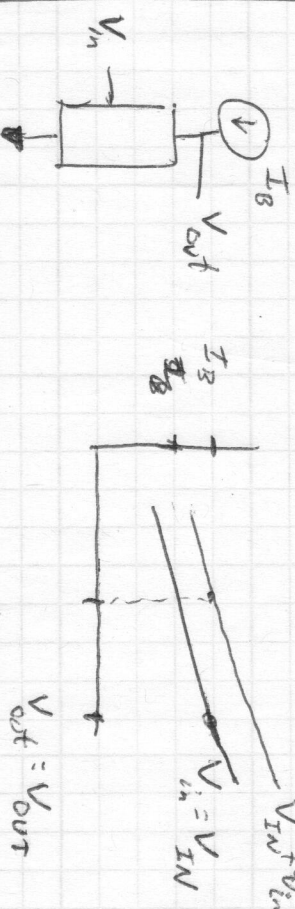
1 input has a strong influence on current in the other. I has a weak influence.

plate

grid

-15V

-15V

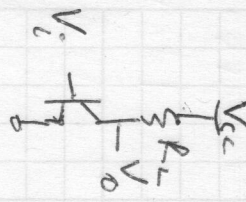


small v_{in}

bias (negative) v_{out}

steep and shallow hillsides, and contours

Linearization

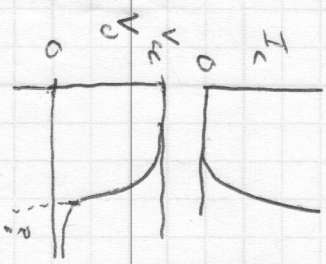


$$V = V_{cc} - I_c R_L$$

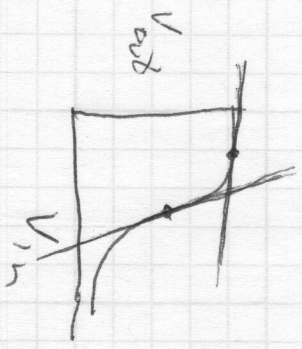
$$= V_{cc} - I_s (e^{V_{in}/V_T} - 1) (1 + \frac{V_0}{V_A}) R$$

$$\approx V_{cc} - I_s e^{V_{in}/V_T} R$$

~ Accurate nonlinear op valid in some region of opatin.



- pick a point on the curve (operating point)
- take derivative and that point
- valid linear model is some neighborhood.

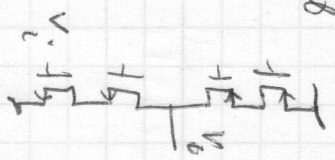
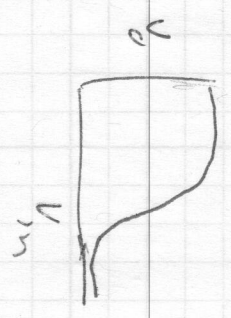
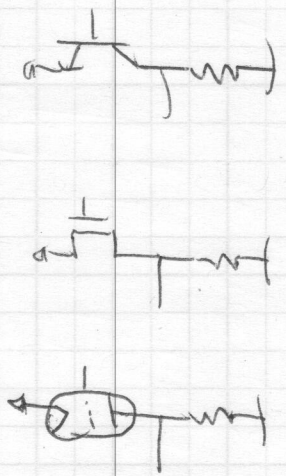


$$A_v = -G_m R_{out}$$

Why?

that one can be solved closed-form, but even very simple circuits can't.

So we linearize,



$$\left(\text{full nonlinear "correct" solution} \right) = \left(\text{single point solution} \right) + \left(\text{small signal model} \right) + \text{h.o.t.}$$

accuracy of model region of validity

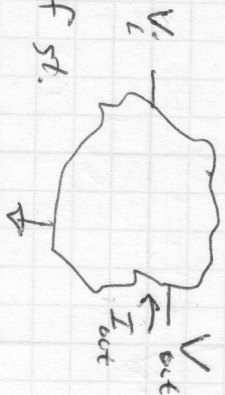
depend on

and models are not reality

but for modern CMs they're pretty close.

where did $-g_m R_{out}$ come from?

Given any circuit



there is some function f st.

$$I_{out} = f(V_i, V_{out}) \text{ in some shorthand.}$$

pick some point (V_i, V_{out}) where $I_{out} = 0$

near that point

$$I_{out} = f(V_i, V_{out}) + \frac{\partial f}{\partial V_i} \delta V_i + \frac{\partial f}{\partial V_{out}} \delta V_{out} + h.o.t.$$

g_m is effect of input voltage change on output current

g_{out} is " " output " " " "

$$R_{out} = \frac{1}{g_{out}}$$

$$I_{out} = I_{out} + i'_{out}$$

$$V_i = V_i + v'_i$$

$$V_{out} = V_{out} + v'_{out}$$

$$\delta V_i = v'_i$$

$$\delta V_{out} = v'_{out}$$

$$I_{out} + i'_{out} = 0 + \cancel{g_m} v'_i + \cancel{g_{out}} v'_{out}$$

$$\frac{v'_{out}}{v'_i} = -\frac{g_m}{g_{out}} = -g_m R_{out}$$