

CS 287: Advanced Robotics

Fall 2011

Lecture 1: Introduction

Pieter Abbeel
UC Berkeley EECS

WWW

- <http://www.cs.berkeley.edu/~pabbeel/cs287-fall11>
- [Step through webpage]

Remainder of Lecture Outline

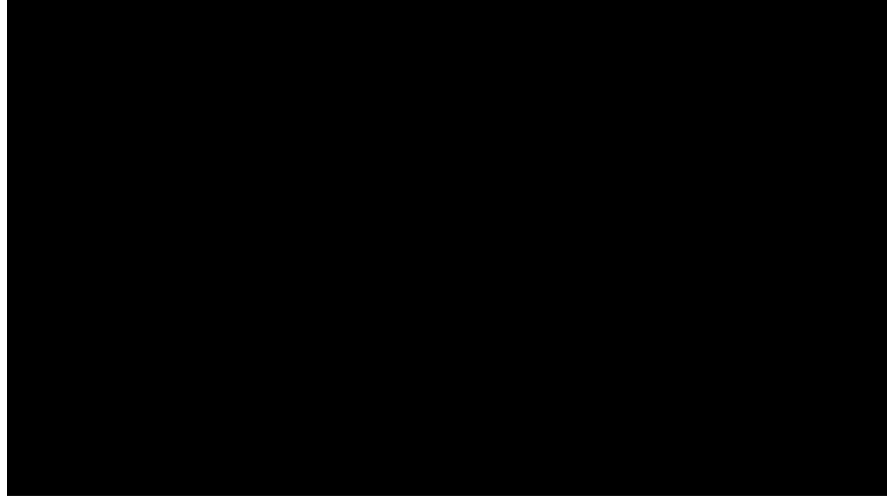
- Questions?
- A few robotic success stories

Driverless Cars

- Darpa Grand Challenge: First long-distance driverless car competition
 - 2004: CMU vehicle drove 7.36 out of 150 miles
 - 2005: 5 teams finished, Stanford team won [nova-race](#)
- Darpa Urban Challenge (2007)
 - Urban environment: other vehicles present
 - 6 teams finished (CMU won) [urban challenge](#)
- Google Autonomous Cars (2010)
 - Mountain View -> Santa Monica; >140,000 miles; Lombard, Golden Gate, Tahoe, Pacific Coast Highway
- Ernst Dickmanns / Mercedes Benz: autonomous car on European highways
 - Human in car for interventions
 - Paris highway and 1758km trip Munich -> Odense, lane changes at up to 140km/h; longest autonomous stretch: 158km (1995)
- Maneuvers: [parking](#),
Kalman filtering, LQR, mapping, terrain & object recognition

Autonomous Helicopter Flight

[Coates, Abbeel & Ng]



Kalman filtering, model-predictive control, LQR, system ID, trajectory learning

Four-legged locomotion

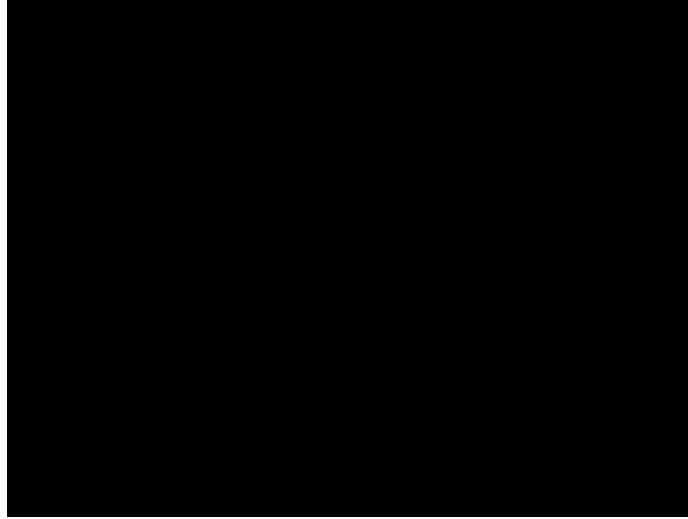
[Kolter, Abbeel & Ng]



value iteration, receding horizon control, motion planning, inverse reinforcement learning, nolearning, learned

Two-legged locomotion

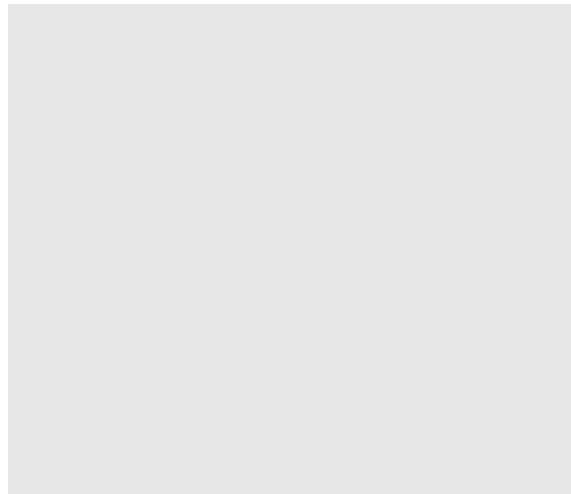
[Tedrake +al.]



Policy gradient

Mapping

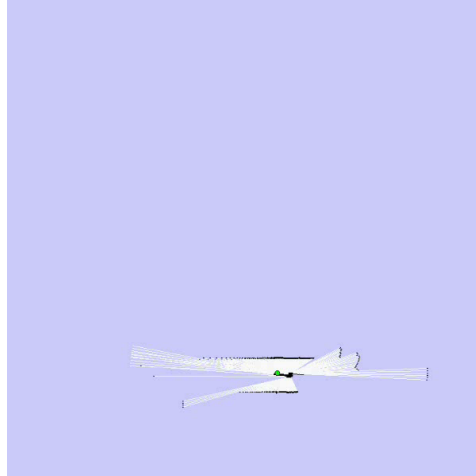
[Video from W. Burgard and D. Haehnel]



"baseline" : Raw odometry data + laser range finder scans

Mapping

[Video from W. Burgard and D. Haehnel]



FastSLAM: particle filter + occupancy grid mapping

Mobile Manipulation

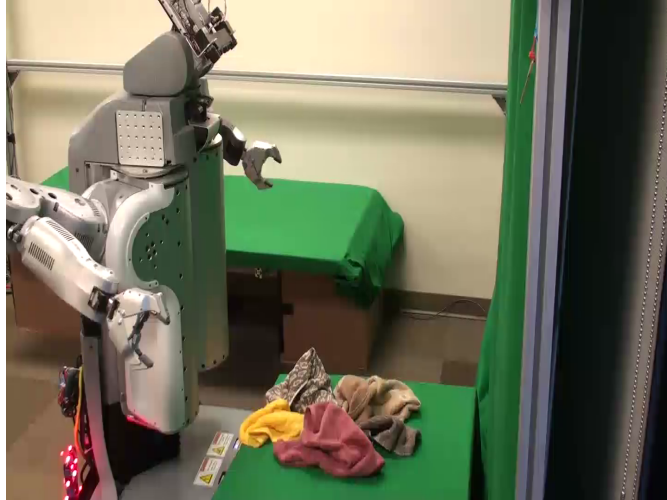
[Quigley, Gould, Saxena, Ng + al.]



SLAM, localization, motion planning for navigation and grasping, grasp point selection, visual category recognition (speech recognition and synthesis)

Mobile Manipulation

[Maitin-Shepard, Cusumano-Towner, Lei, Abbeel, 2010]



localization, motion planning for navigation and grasping, grasp point selection, visual recognition

Why a Great Time to Study CS287 Advanced Robotics?

- Robotic hardware is getting in great shape, expertise in algorithms+math+programming are limiting factors
- So many different robotic systems, yet a few core techniques, which I believe can be learned through the course of this semester, are (near-)sufficient to rule them all
 - Probabilistic Reasoning
 - Optimization
- Applicability of these techniques extends well beyond robotics

That's it for today

- Starting probabilistic reasoning on Tuesday
- Check out the webpage!
- Sign up on piazza!

- Come talk to me now about any lingering questions you might have