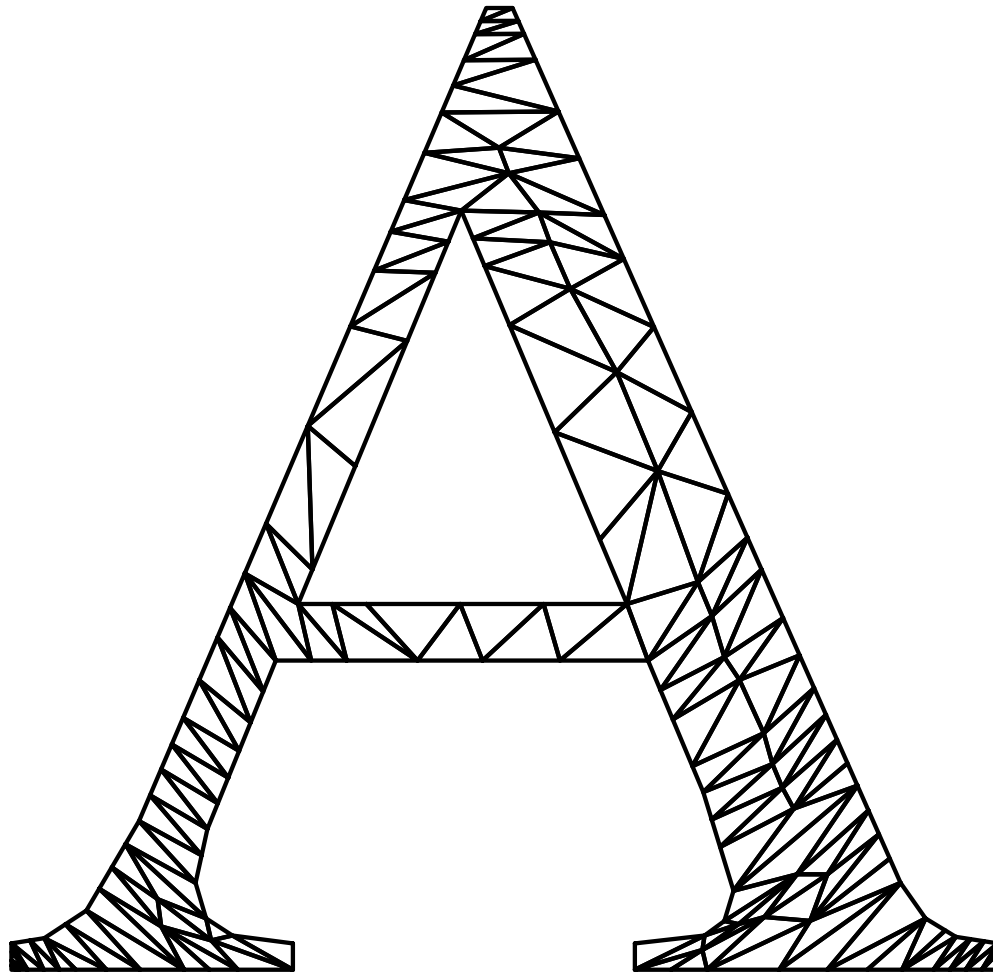


# **Anisotropic Voronoi Diagrams and Guaranteed-Quality Anisotropic Mesh Generation**

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# I. Anisotropic Meshes

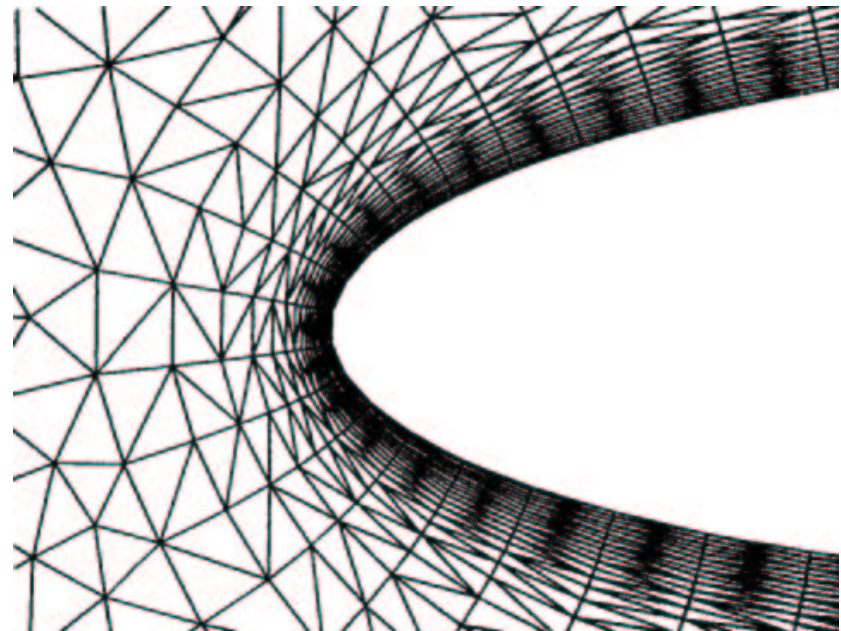


# What Are Anisotropic Meshes?

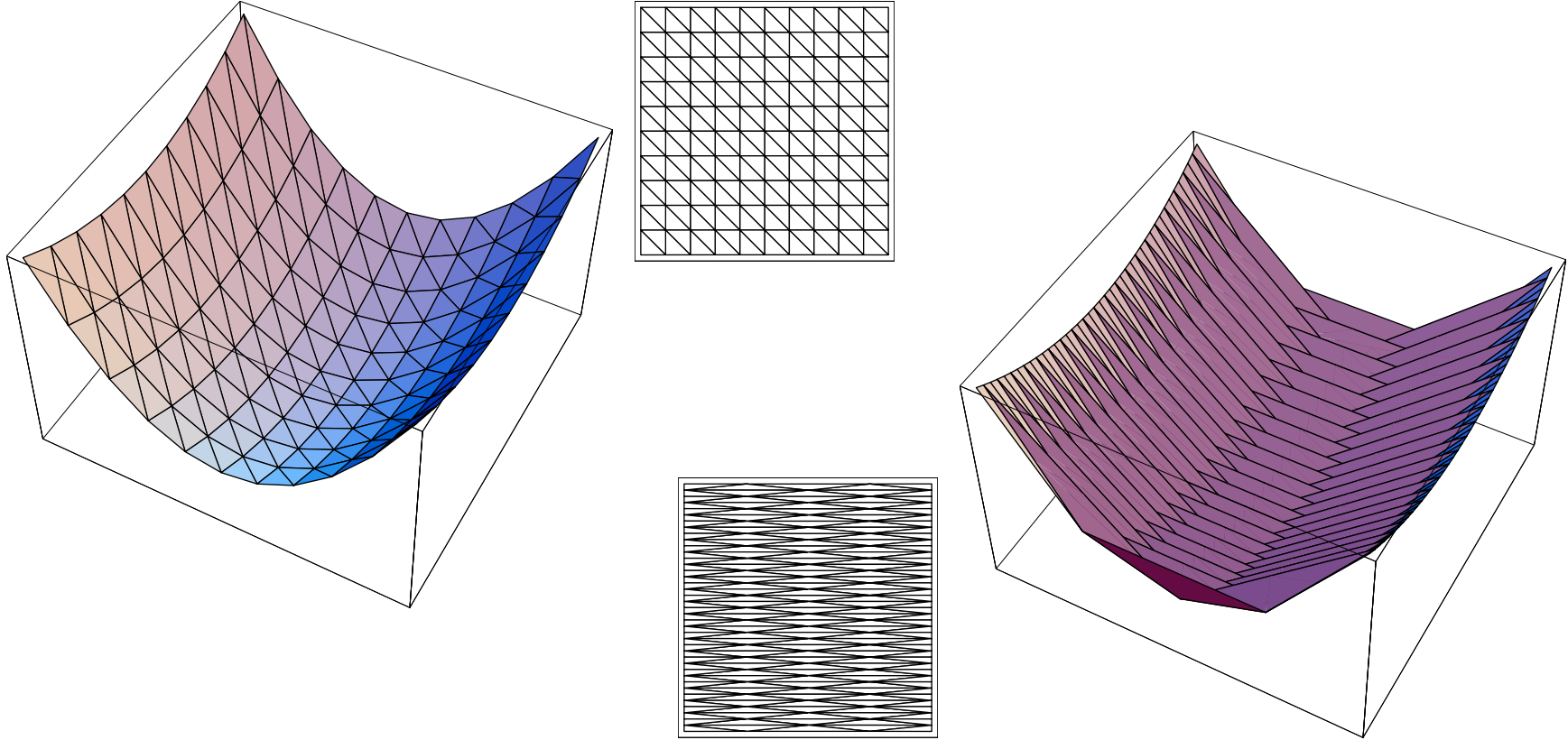
Meshes with long, skinny triangles (in the right places).

## Why Are They Important?

- Often provide better interpolation of multivariate functions with fewer triangles.
- Used in finite element methods to resolve boundary layers and shocks.



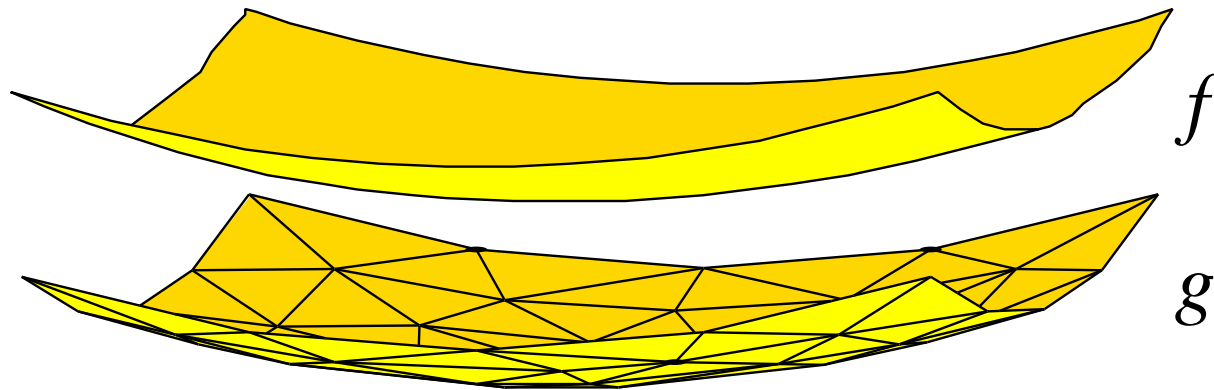
Source: "Grid Generation by the Delaunay Triangulation," Nigel P. Weatherill, 1994.



Triangle shape is critical for

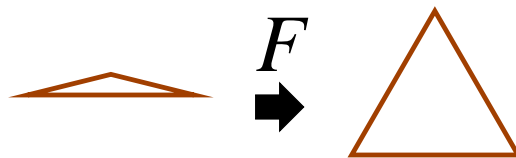
- surface triangulations in graphics;
- finite element meshes in physical modeling;
- triangulations in interpolation.

# Interpolation of Functions with Anisotropic Curvature



$H = \text{Hessian of } f$ . Let  $F^2 = H$  with  $F$  symmetric pos-def.

You can judge the quality of a triangle  $t$  by checking if  $Ft$  is “round.”

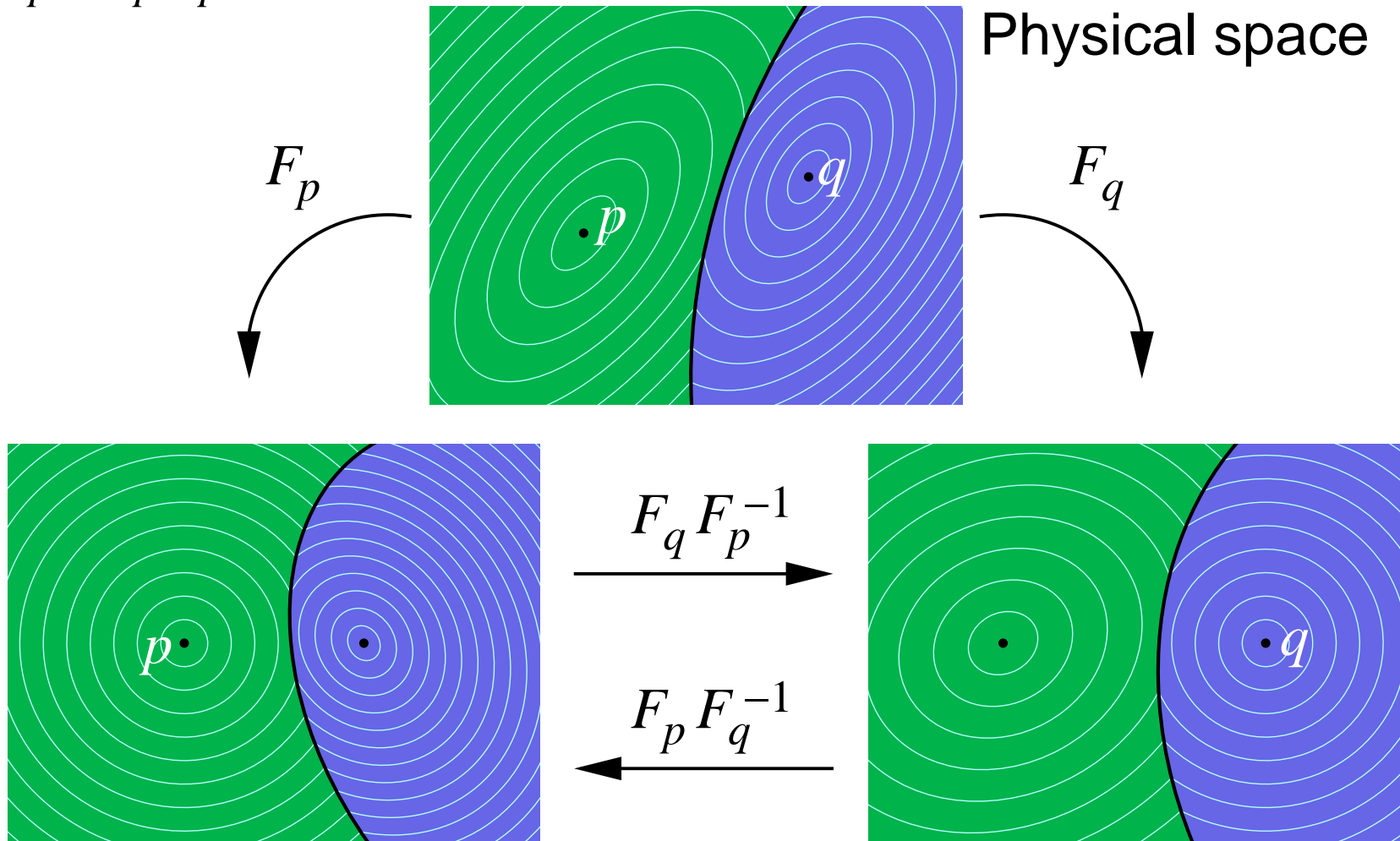


# Distance Measures

Metric tensor  $M_p$ : distances & angles measured by  $p$ .

Deformation tensor  $F_p$ : maps physical to rectified space.

$$M_p = F_p^T F_p.$$

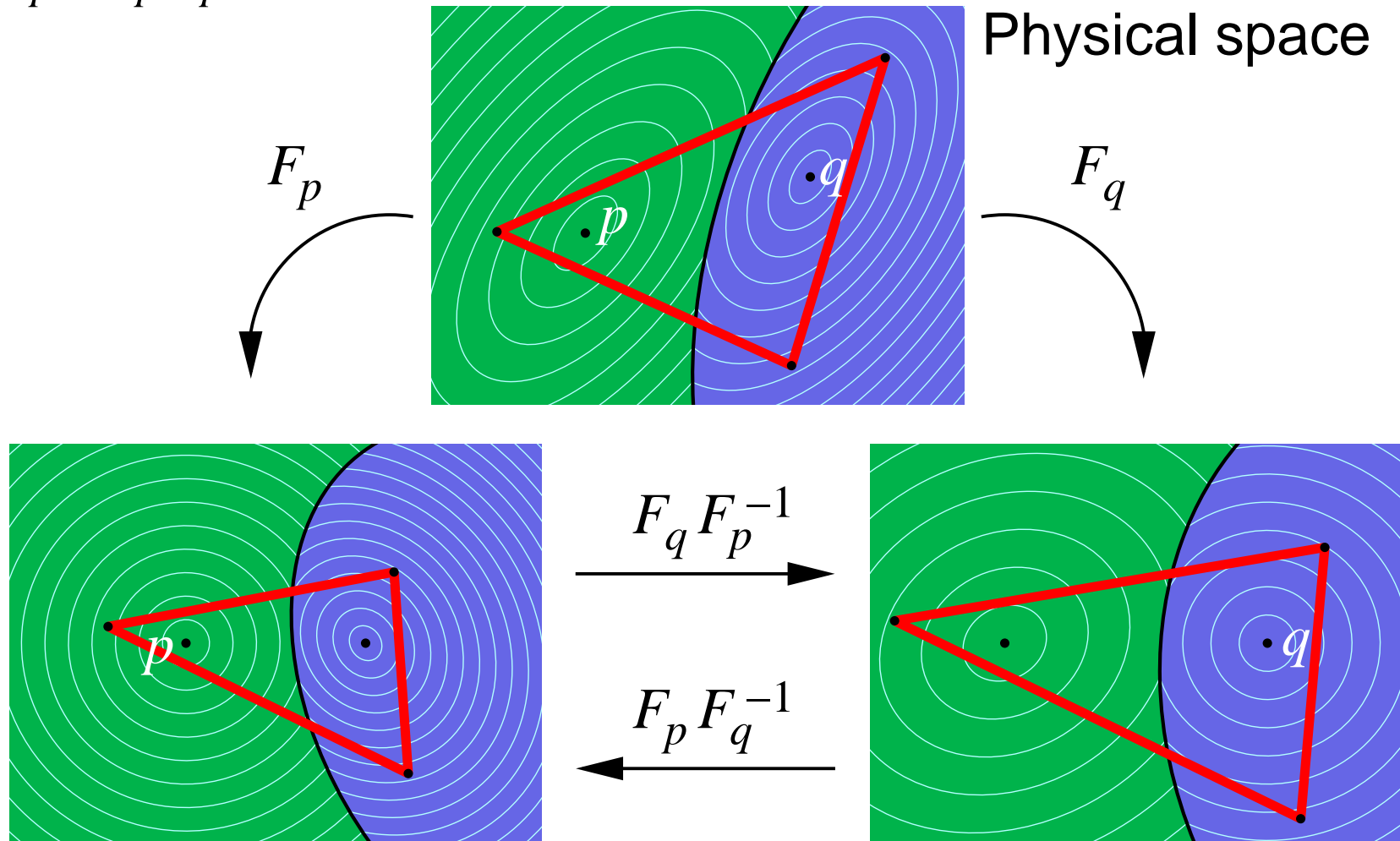


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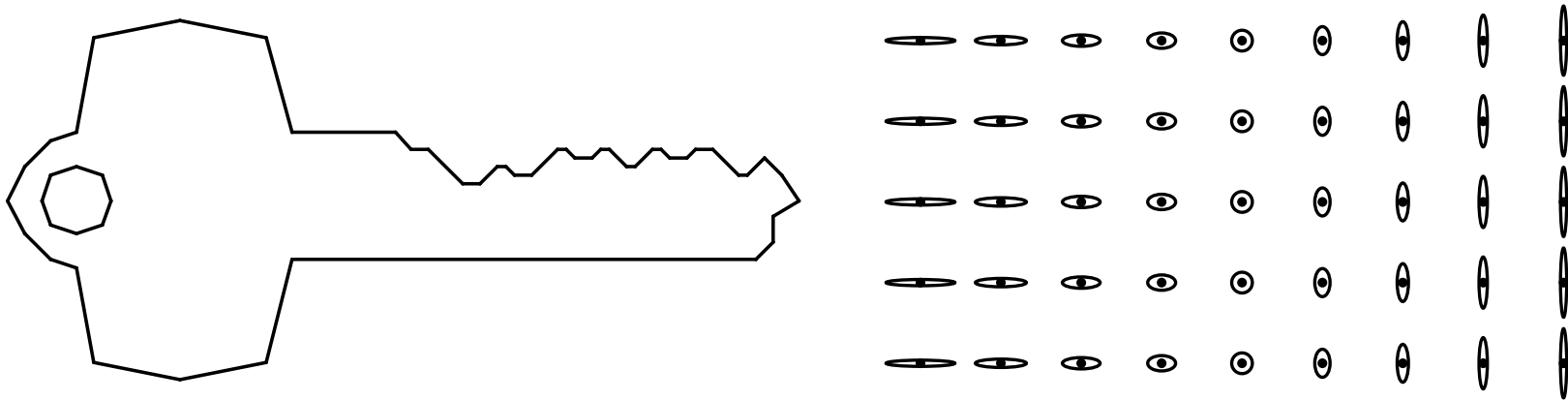
$$M_p = F_p^T F_p.$$



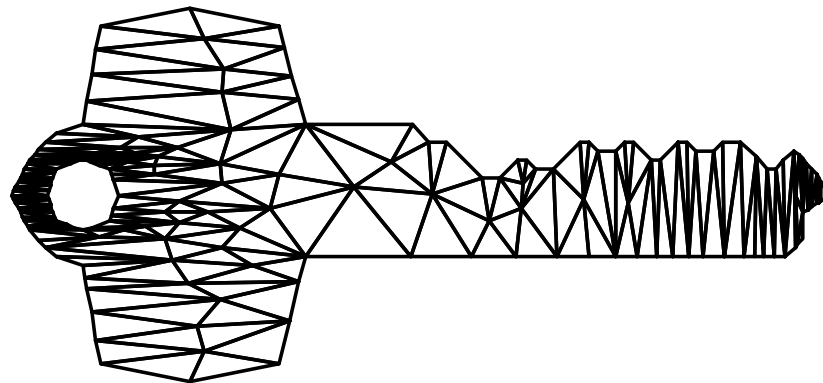
Every point wants to be in a “nice” triangle in rectified space.

# The Anisotropic Mesh Generation Problem

Given polygonal domain and metric tensor field  $M$ ,



generate anisotropic mesh.

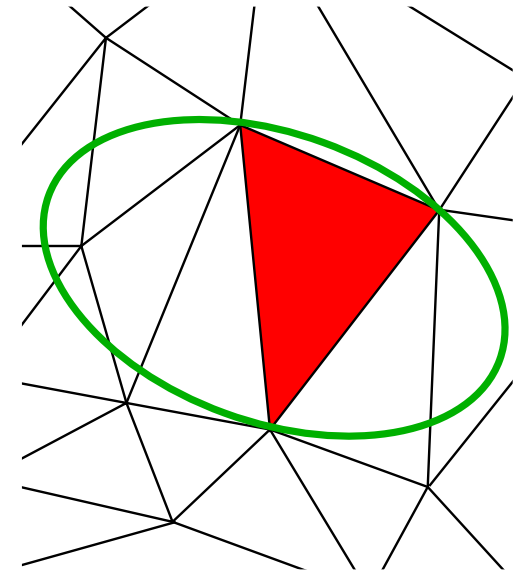
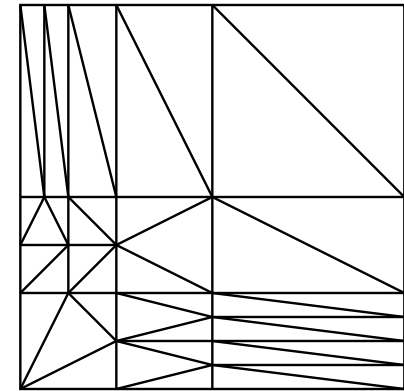




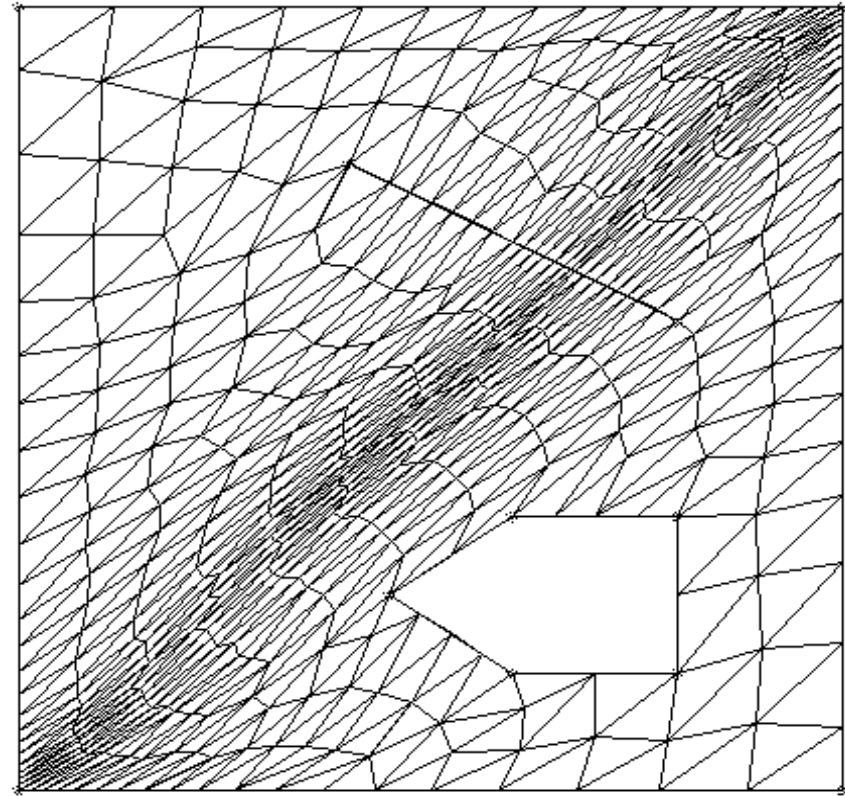
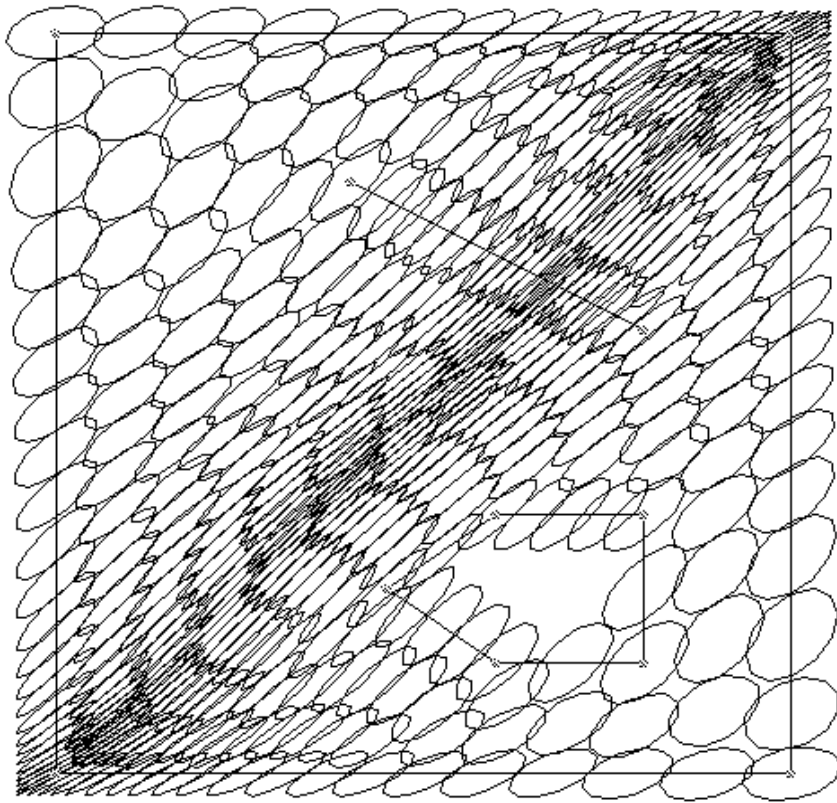
# A Hard Problem (Especially in Theory)

Common approaches to guaranteed-quality mesh generation do not adapt well to anisotropy.

- Quadtree-based methods can be adapted to horizontal and vertical stretching, but not to diagonal stretching.
- Delaunay triangulations lose their global optimality properties when adapted to anisotropy. No “empty circumellipse” property.



# Heuristic Algorithms for Generating Anisotropic Meshes



Bossen-Heckbert [1996]

Shimada-Yamada-Itoh [1997]

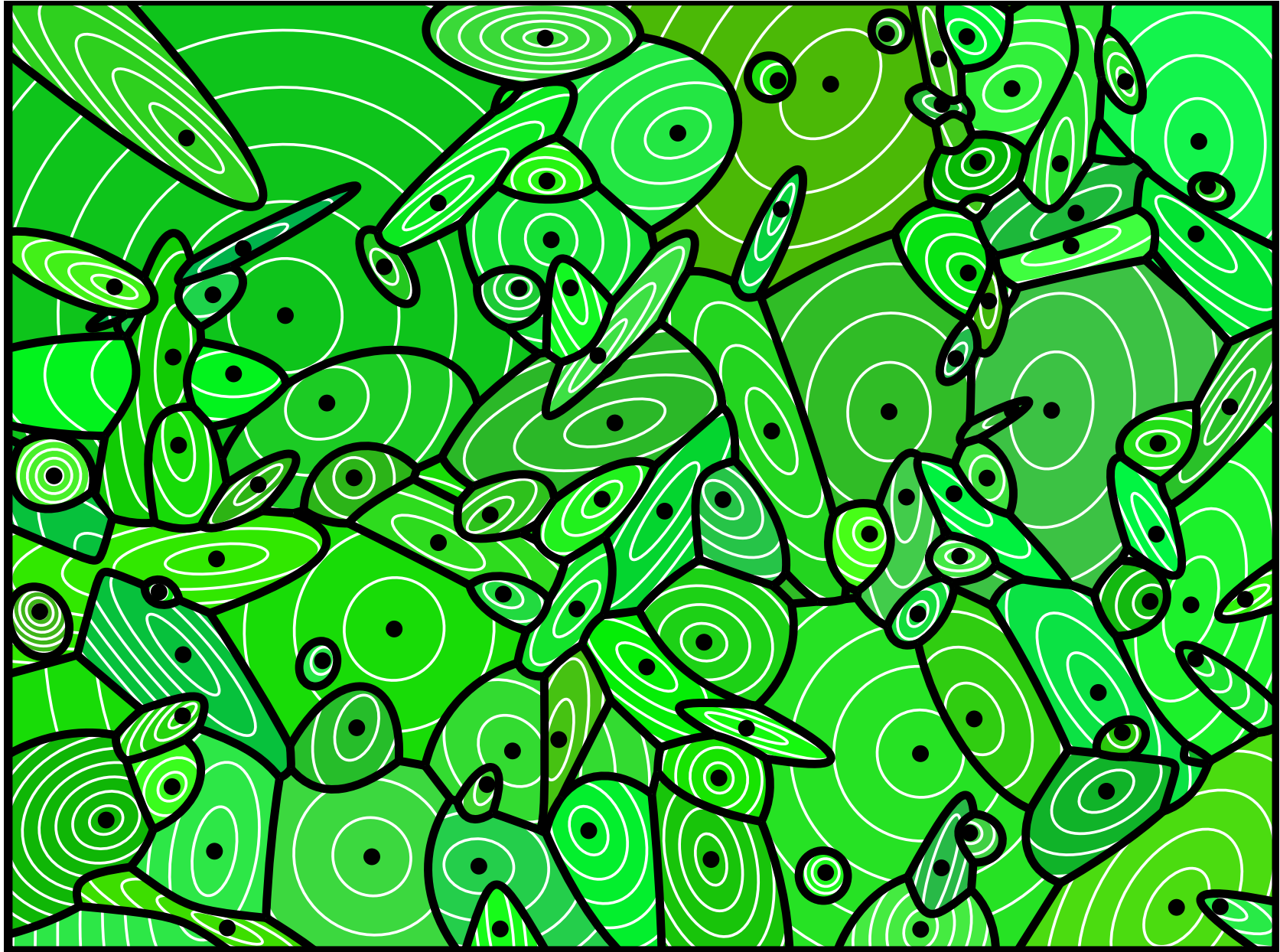
George-Borouchaki [1998]

Li-Teng-Üngör [1999]

# Our Solution

- We tried to invent an “anisotropic Delaunay triangulation” that is always well defined. We couldn’t do it. So...
- Our meshing algorithm refines a special, anisotropic kind of Voronoi diagram.
- No triangulation until the very end.

## II. Anisotropic Voronoi Diagrams



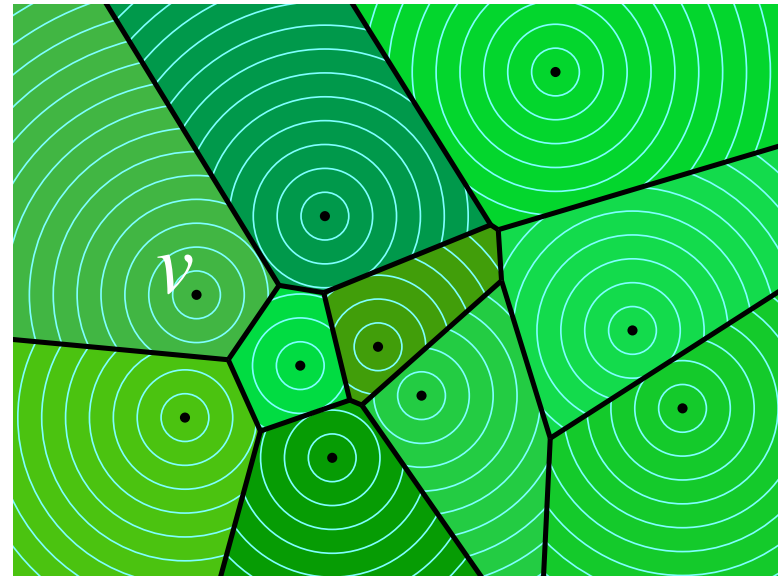
# Voronoi Diagram: Definition

Given a set  $V$  of sites in  $E^d$ , decompose  $E^d$  into cells. The cell  $\text{Vor}(v)$  is the set of points “closer” to  $v$  than to any other site in  $V$ .

Mathematically:

$$\text{Vor}(v) = \{p \text{ in } E^d : \underbrace{d_v(p)} \leq d_w(p) \text{ for every } w \text{ in } V.\}$$

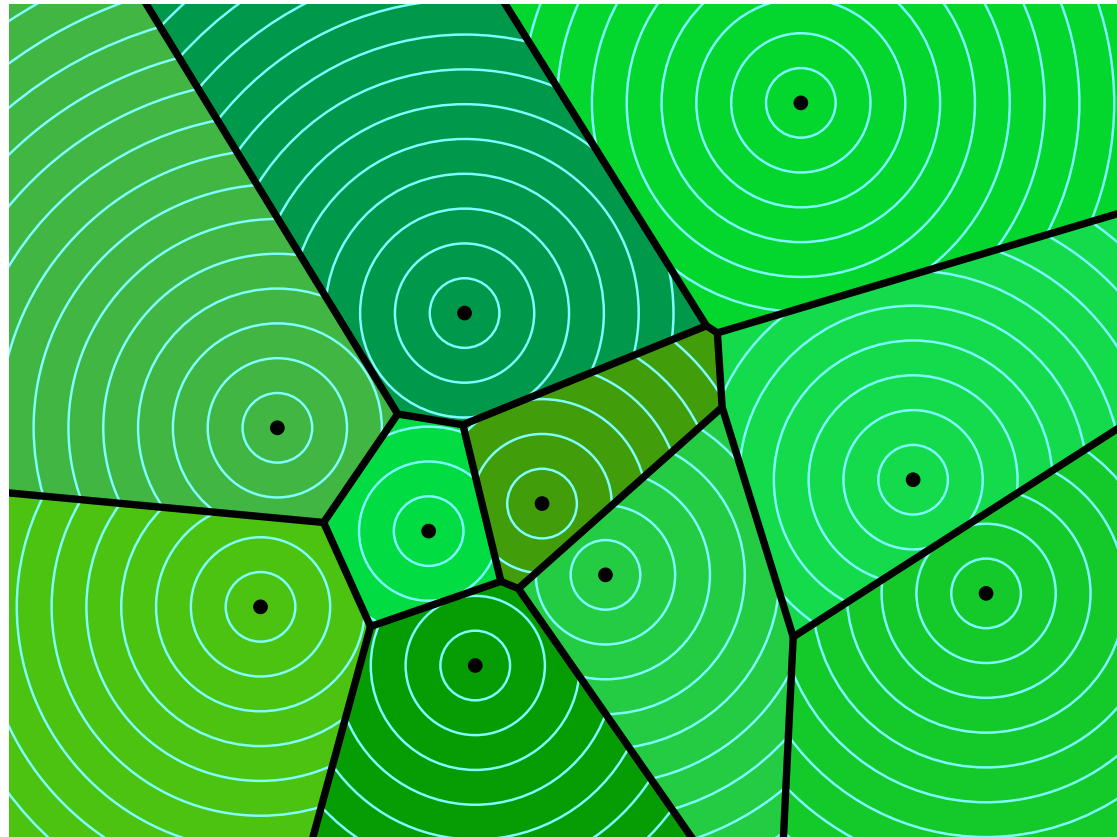
distance from  $v$  to  $p$   
as measured by  $v$



# Distance Function Examples

## 1. Standard Voronoi diagram

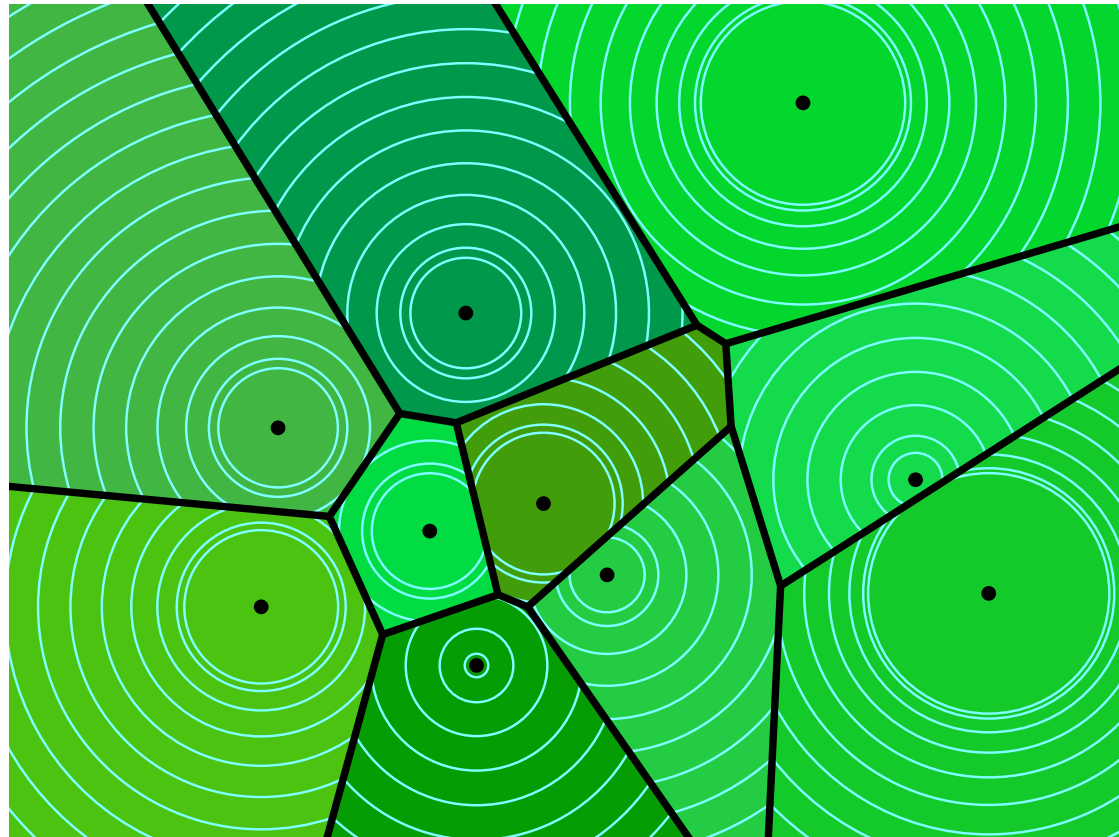
$$d_v(p) = \|p - v\|_2$$



# Distance Function Examples

## 2. Power diagram

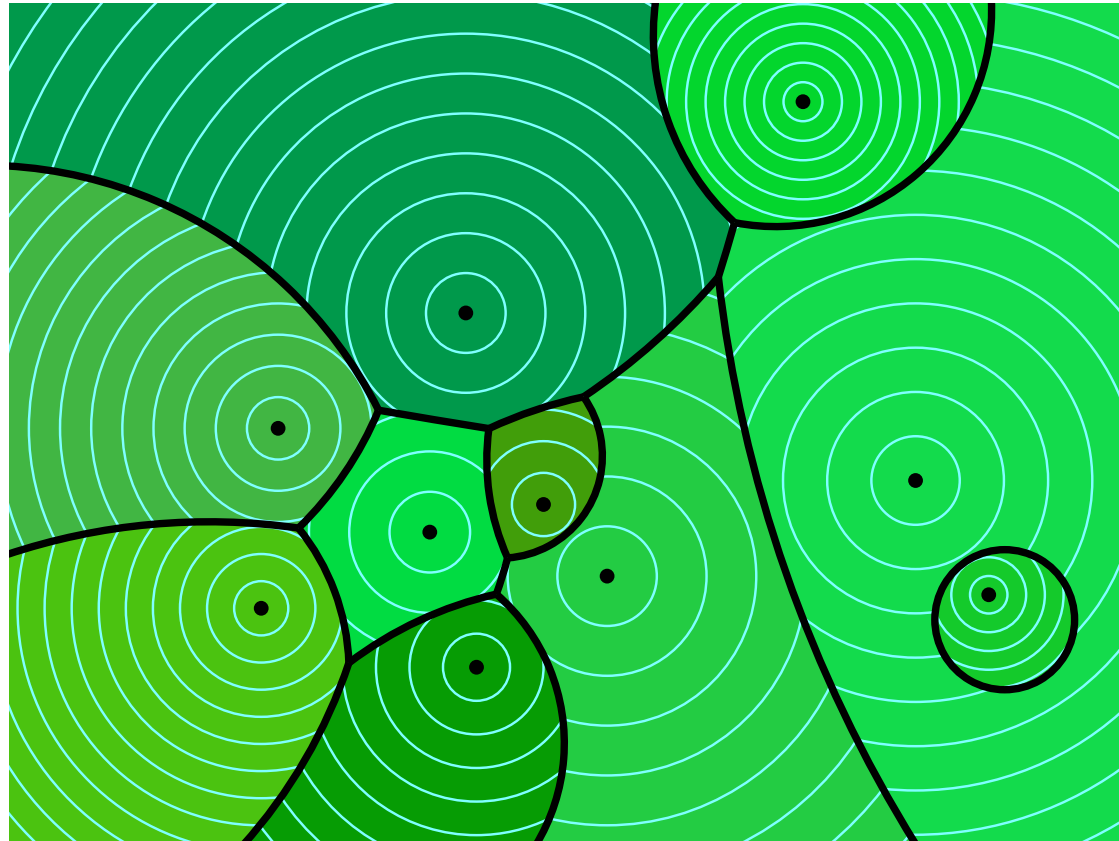
$$d_v(p) = (\|p - v\|_2^2 - c_v)^{1/2}$$



# Distance Function Examples

## 3. Multiplicatively weighted Voronoi diagram

$$d_v(p) = c_v \|p - v\|_2$$

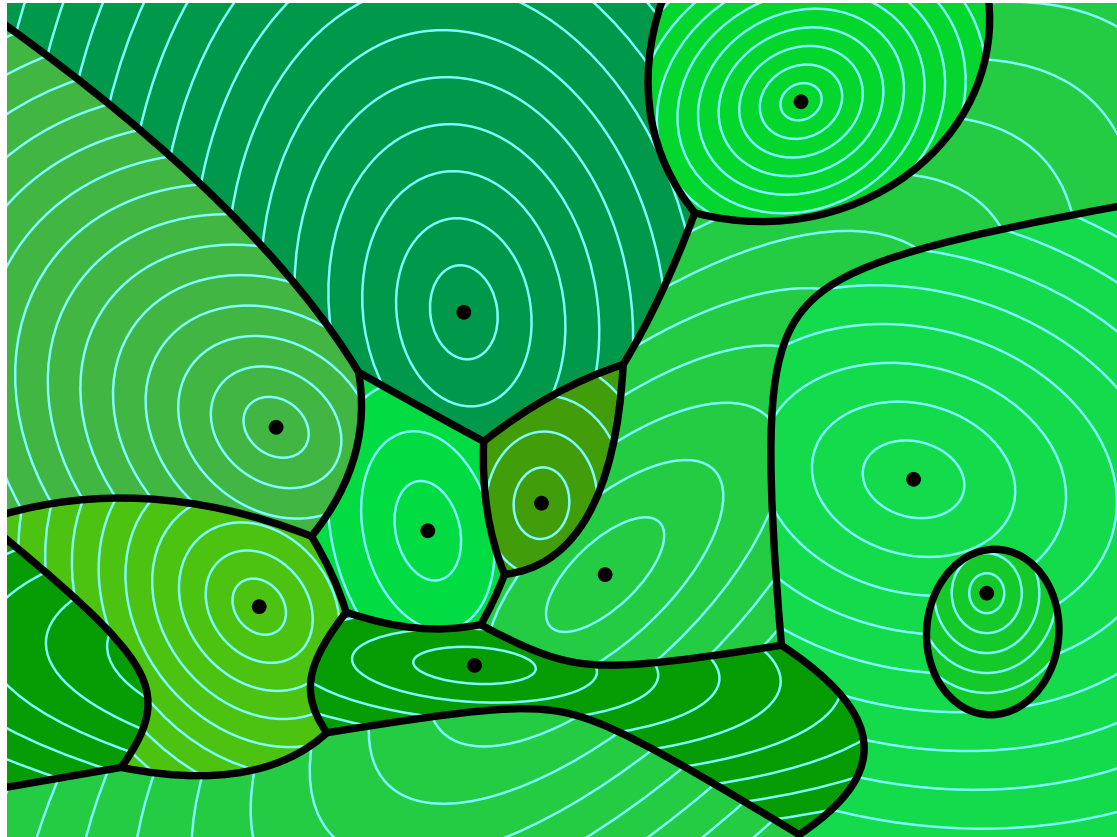




# Distance Function Examples

## 4. Anisotropic Voronoi diagram

$$d_v(p) = [(p - v)^T M_v (p - v)]^{1/2}$$



# Distance Function Examples

## 5. Riemannian Voronoi diagram

$d_v(p)$  = shortest geodesic path between  $v$  and  $p$ .

- Leibon & Letscher [2000] define Voronoi/Delaunay on Riemannian manifolds.
  - Bounded curvature + densely sampled sites  
→ well-defined Delaunay triangulation.
  - Geodesics too hard to compute in practice.
- George & Borouchaki [1998] suggest fast heuristic approximation to Riemannian Delaunay, but can't prove anything.

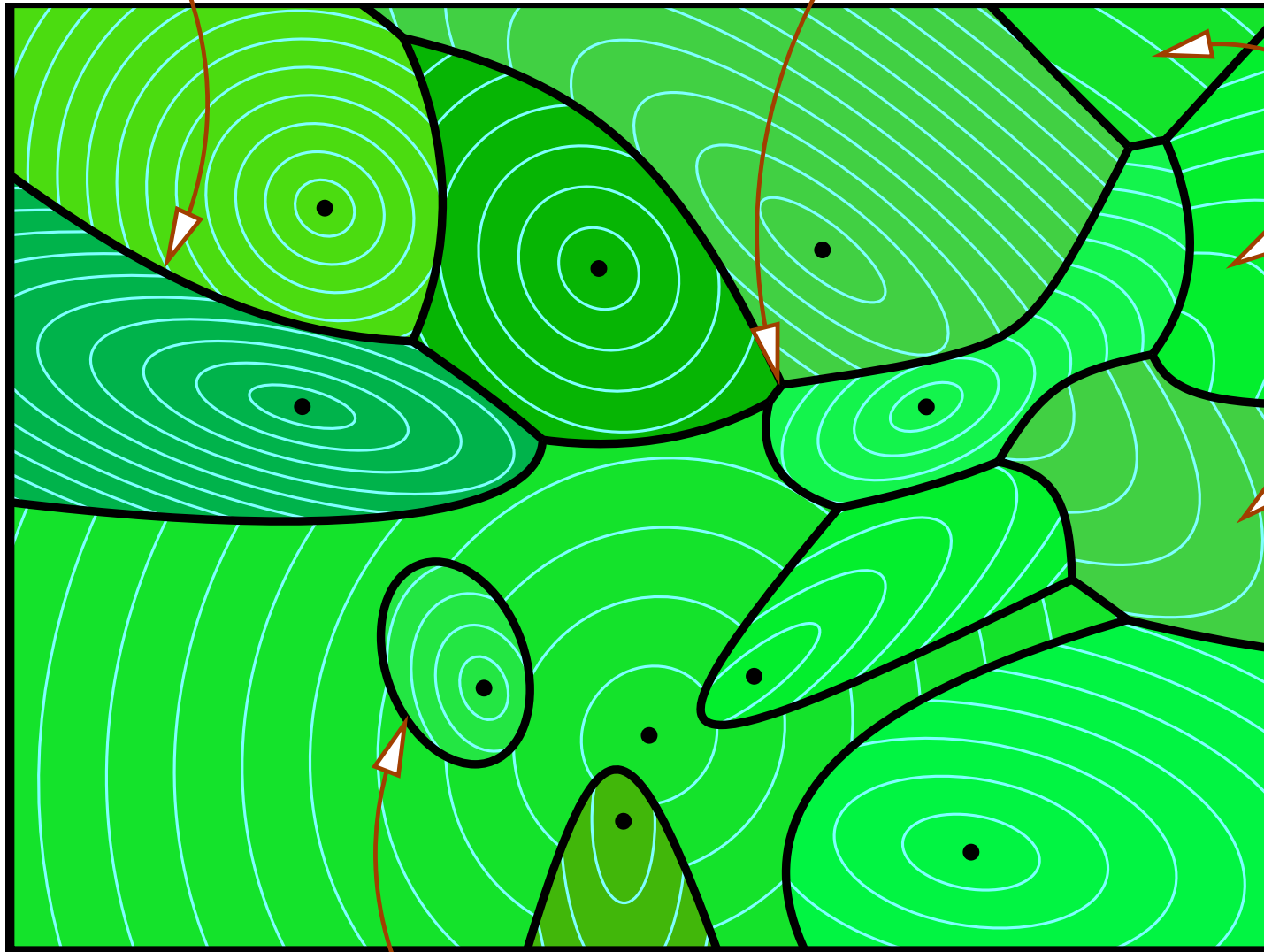


# Anisotropic Voronoi Diagram

Voronoi arc

Voronoi vertex

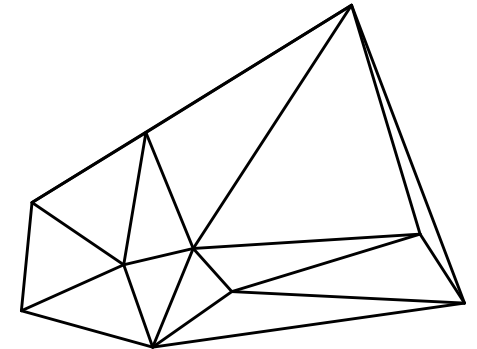
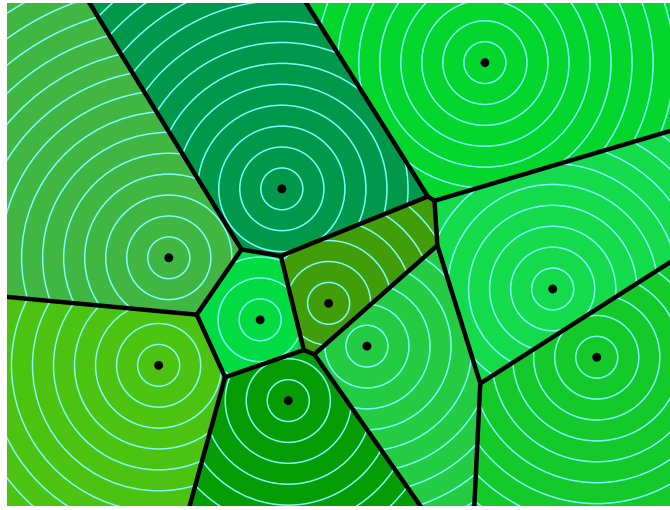
Orphans



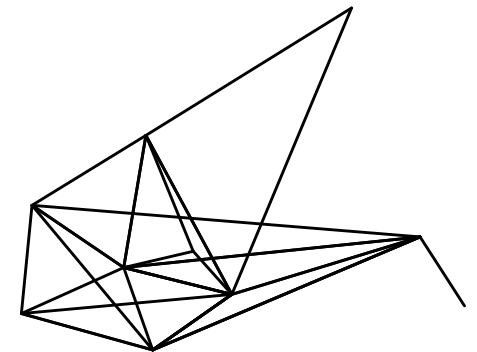
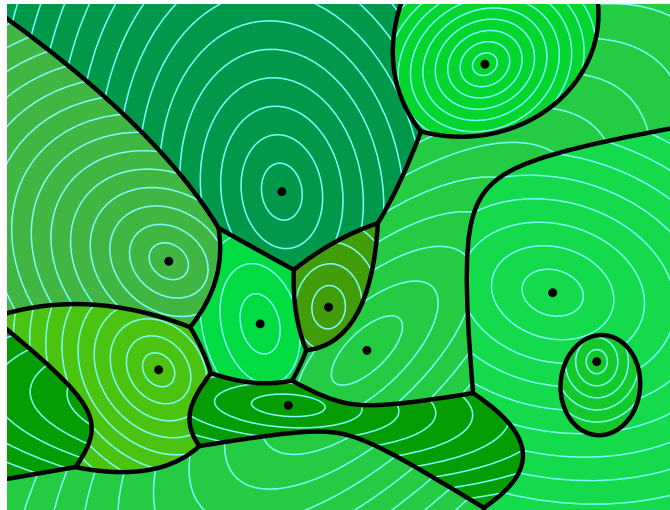
Island

# Duality

The dual of the standard Voronoi diagram is the Delaunay triangulation.

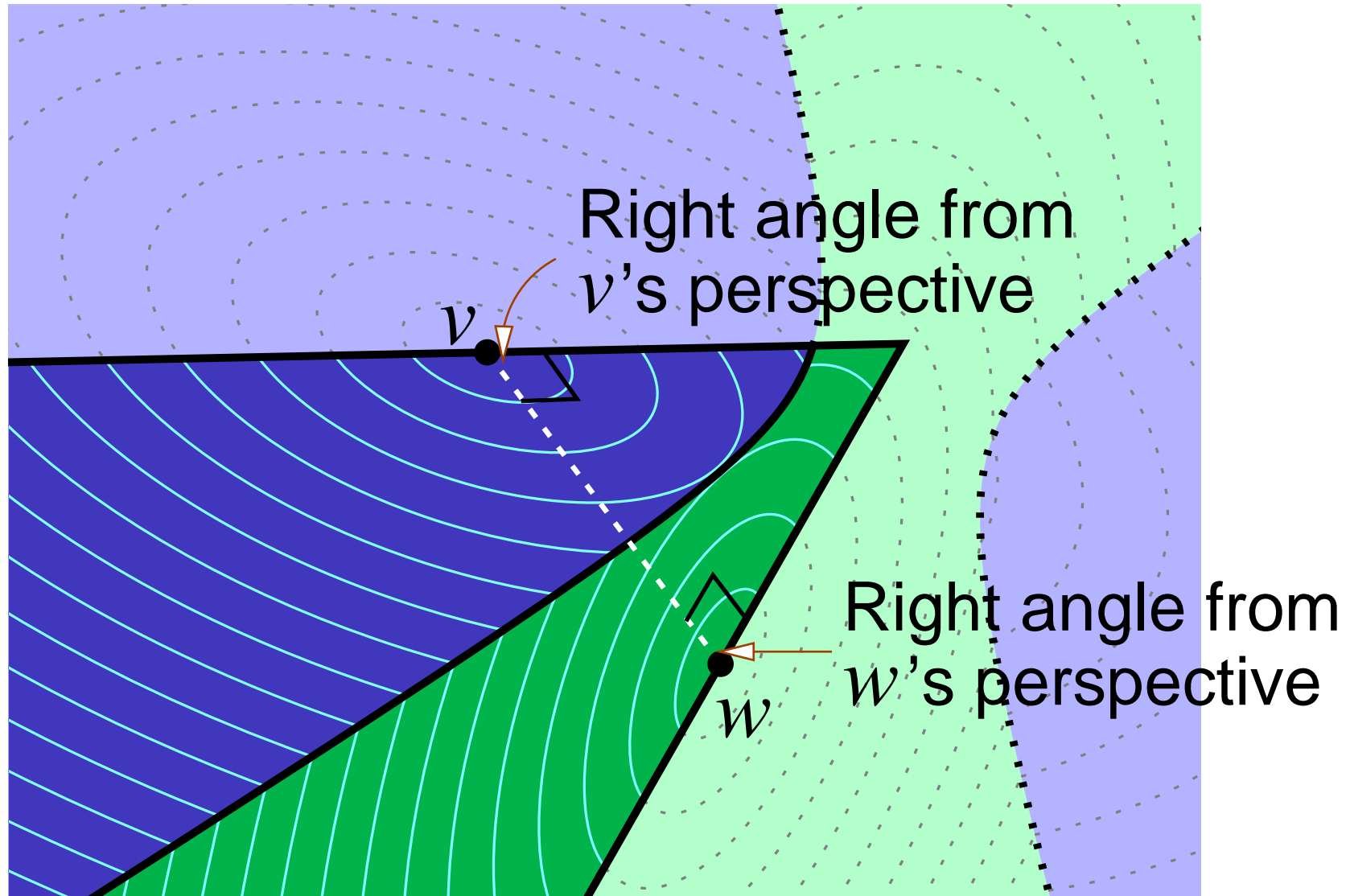


The dual of the anisotropic Voronoi diagram is not, in general, a triangulation.

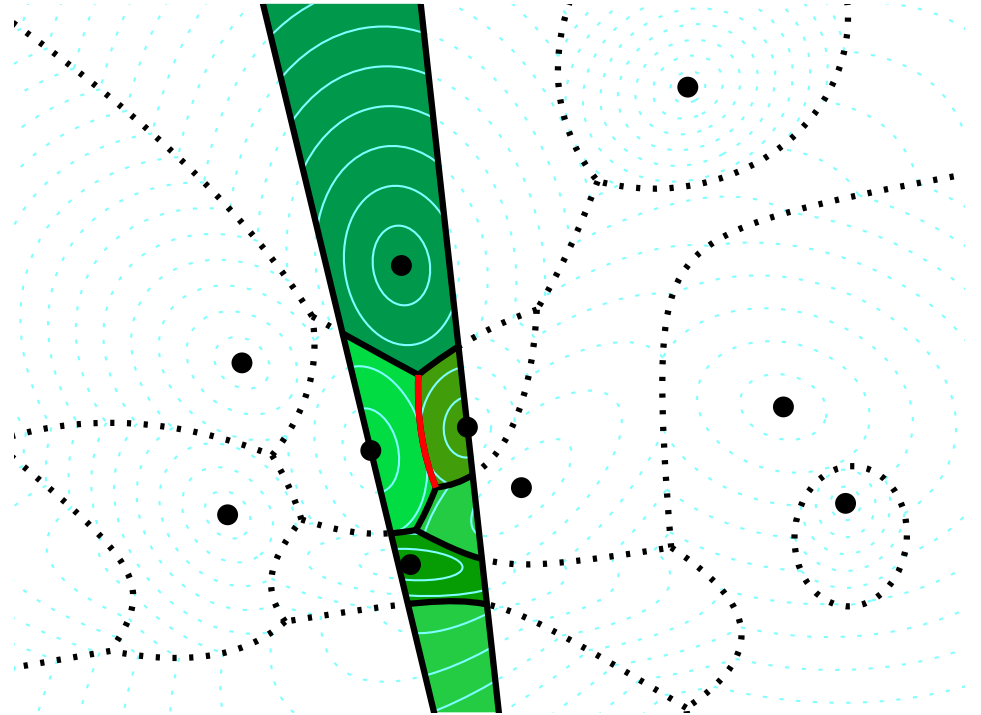


We must enforce some extra conditions.

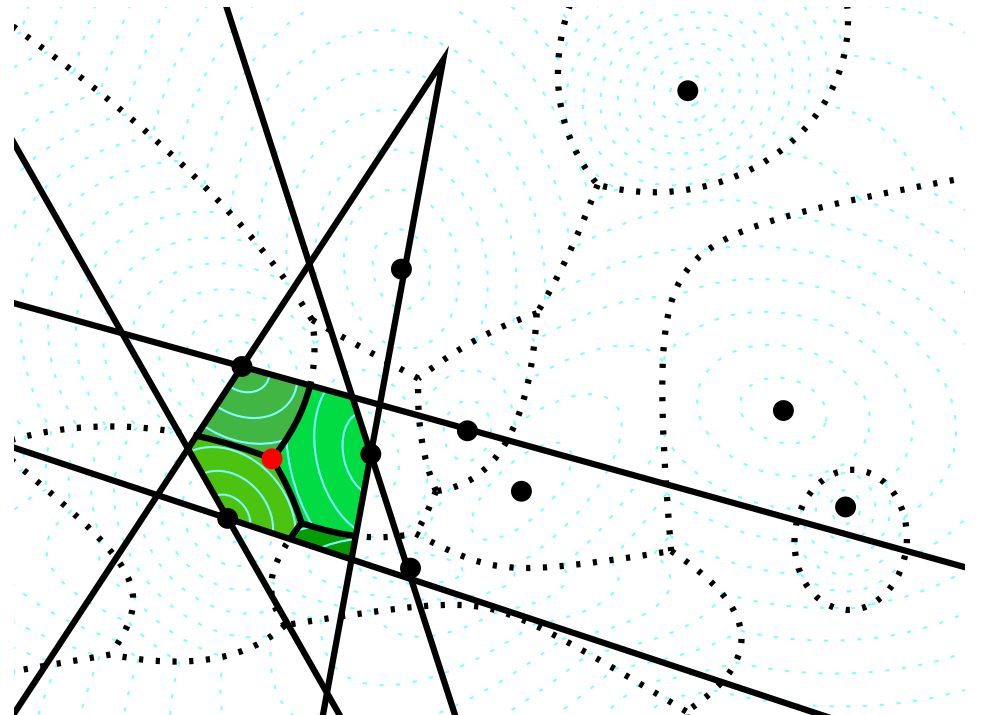
# Two Sites Define a *Wedge*



Voronoi arc is *wedged* if it's in the wedge of the sites that define it.

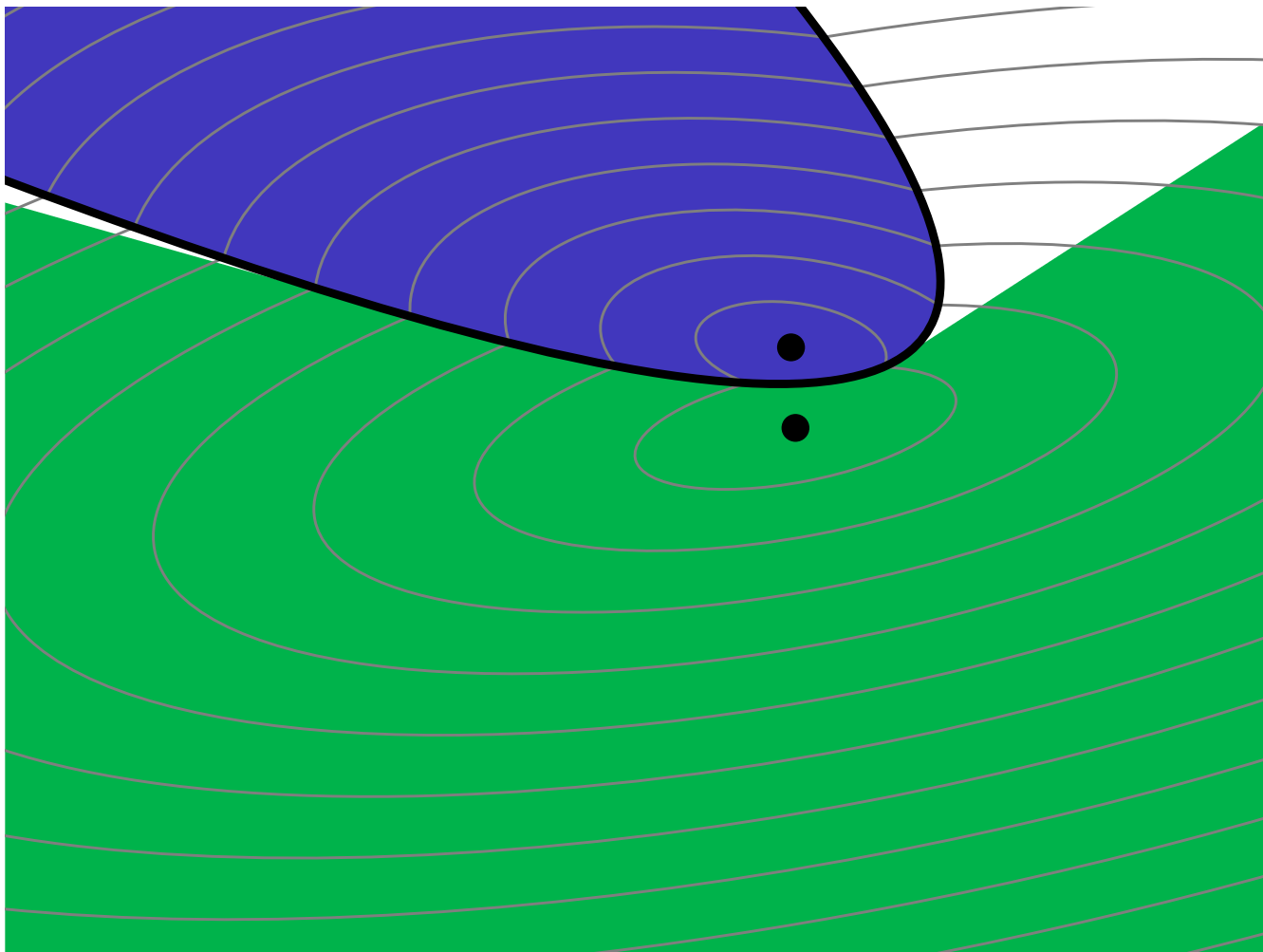


Voronoi vertex is *wedged* if it's in all 3 wedges.



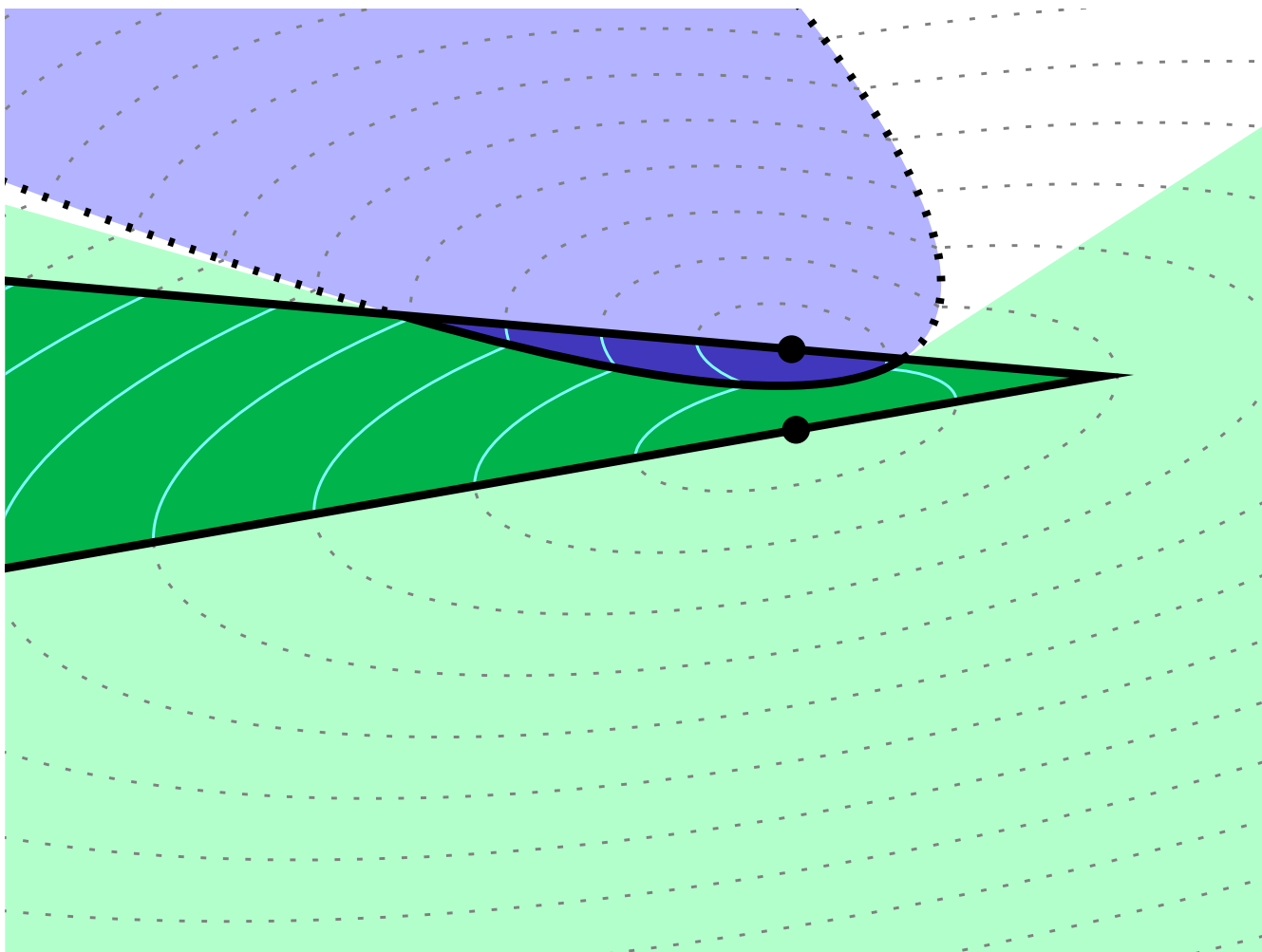
# Visibility Lemma

Inside wedge, each site sees its whole Voronoi cell.



# Visibility Lemma

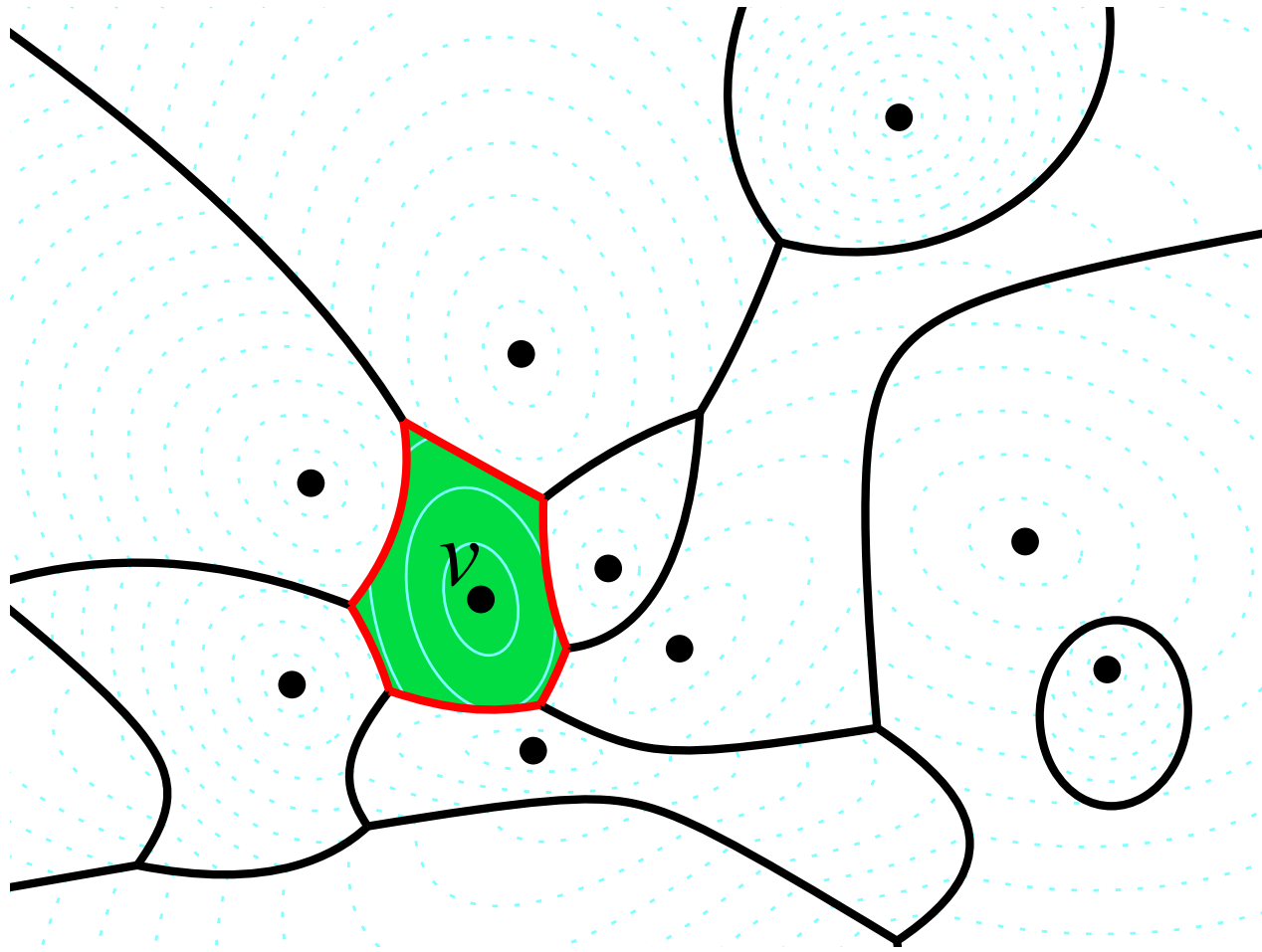
Inside wedge, each site sees its whole Voronoi cell.





# Visibility Theorem

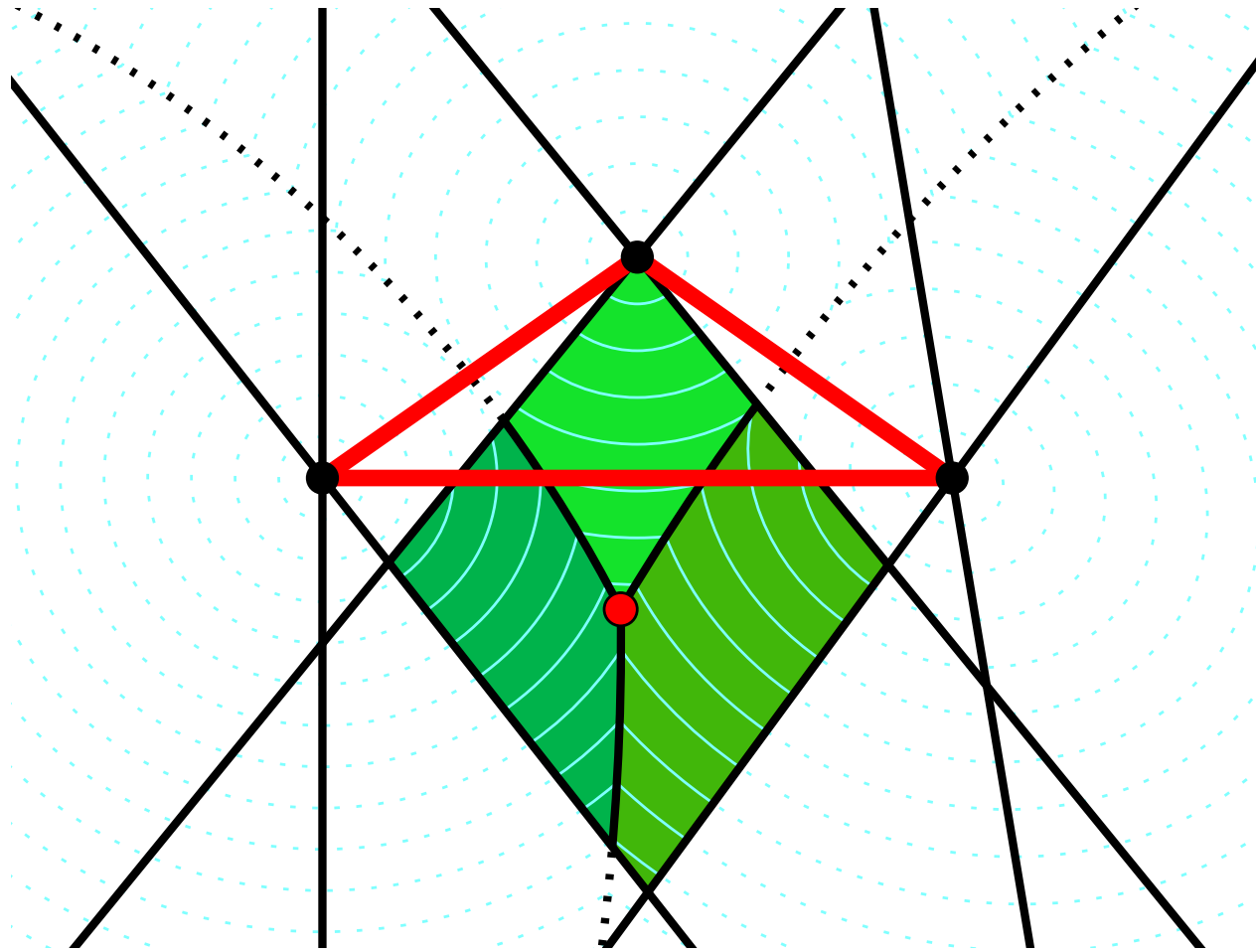
If every Voronoi arc of  $\text{Vor}(v)$  is wedged, then  $\text{Vor}(v)$  is star-shaped & visible from  $v$ .



(This generalizes to higher dimensions.)

# Triangle Orientation Lemma

If a Voronoi vertex is wedged, its dual triangle has positive orientation.

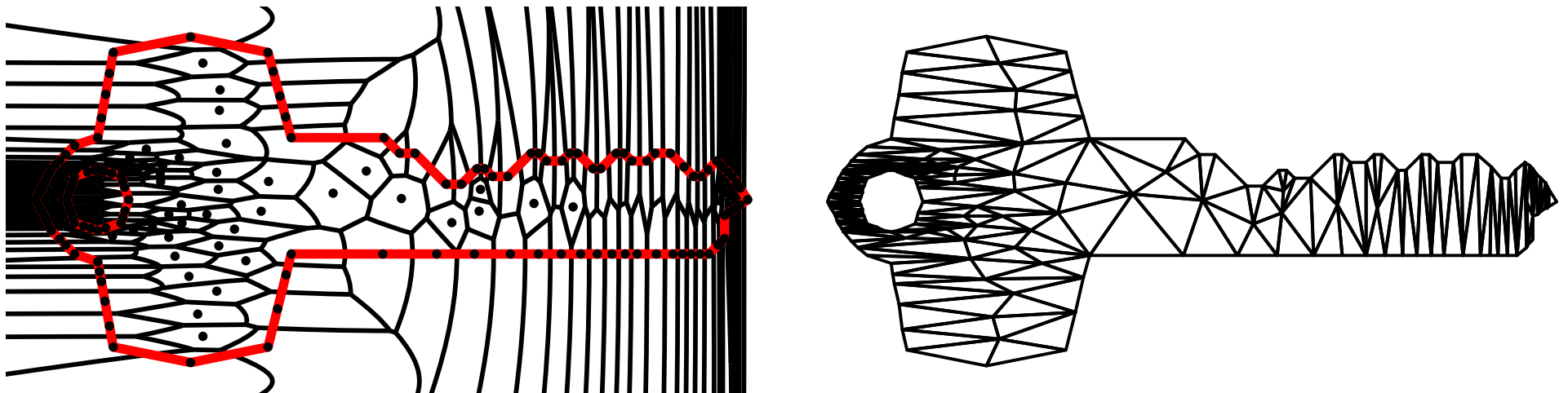


(Does not generalize above two dimensions.)

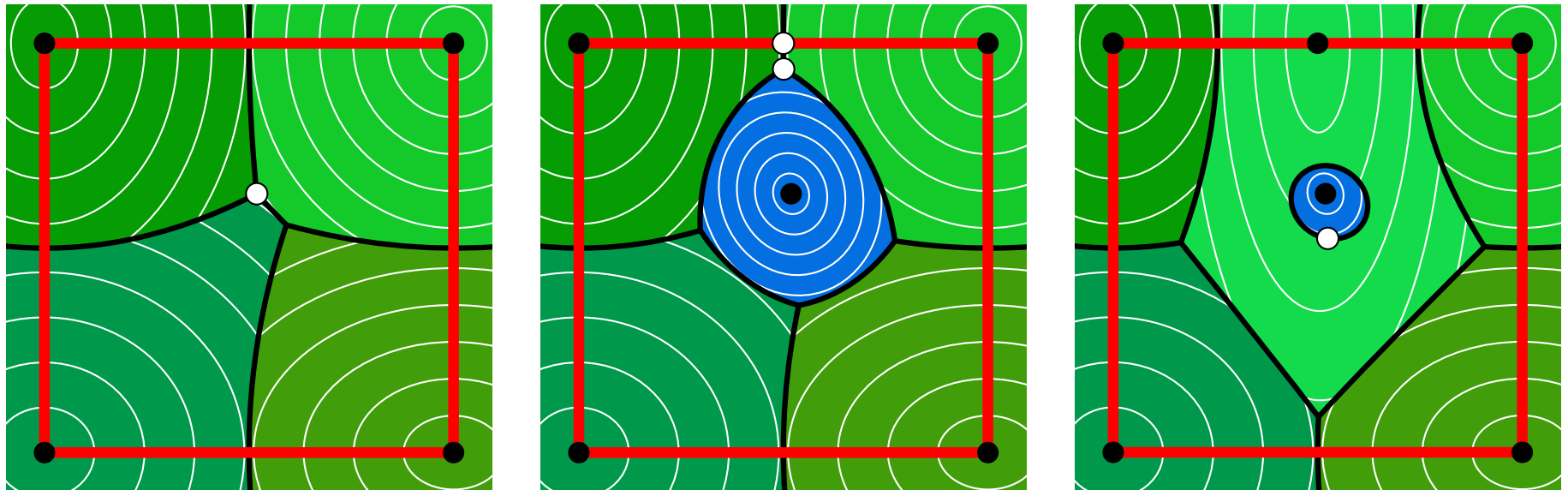
# Dual Triangulation Theorem

If all arcs & vertices are wedged, Voronoi diagram dualizes to an *anisotropic Delaunay triangulation*.

If arcs & vertices are wedged *inside a domain* (& some conditions hold at the boundary), the dual is a triangulation of the domain.

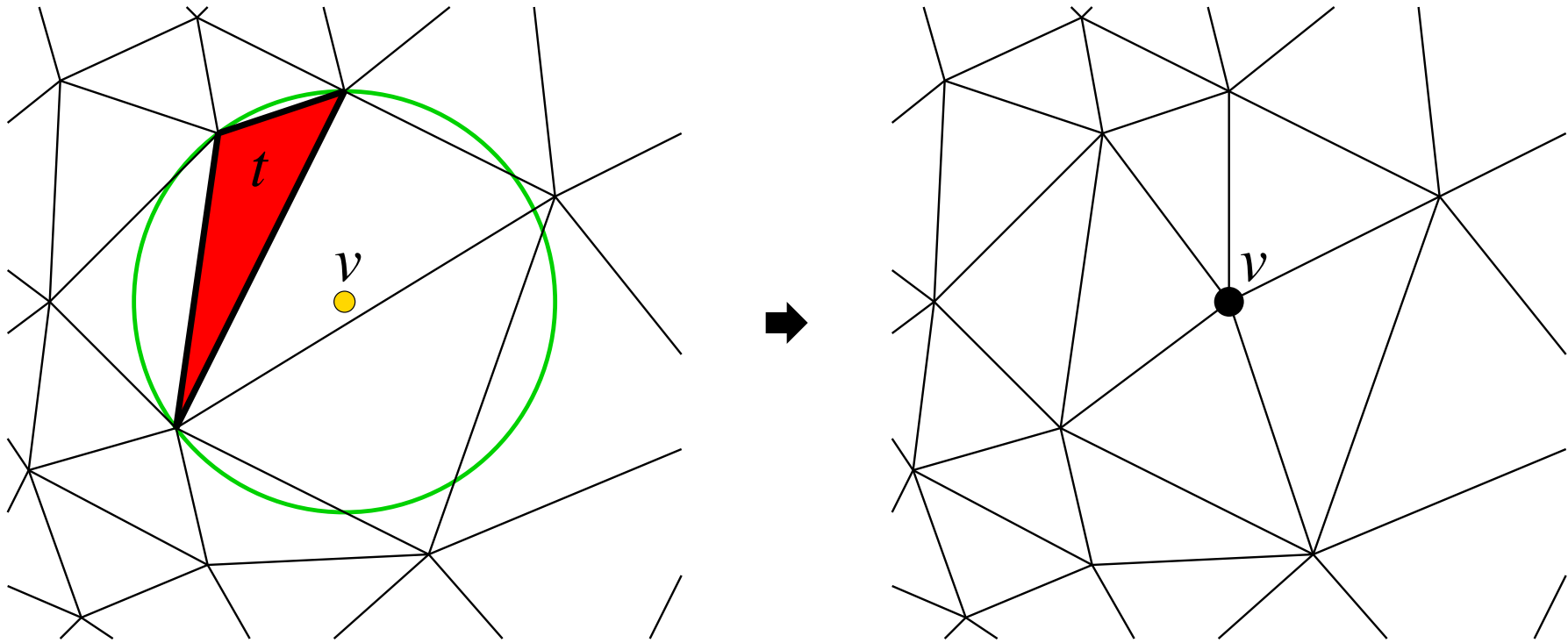


# III. Anisotropic Mesh Generation by Voronoi Refinement



# Isotropic Mesh Generation by Delaunay Refinement

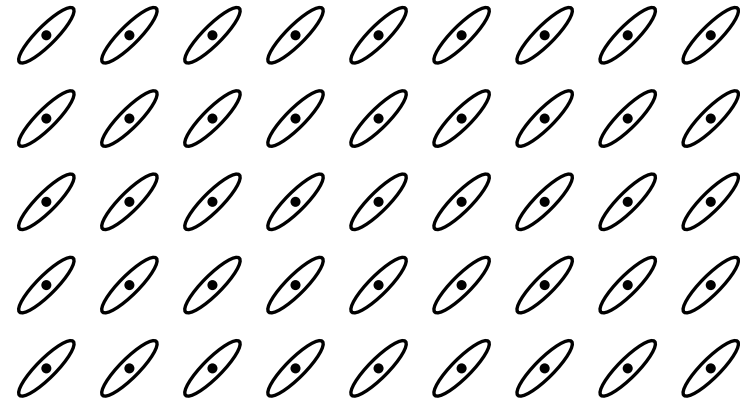
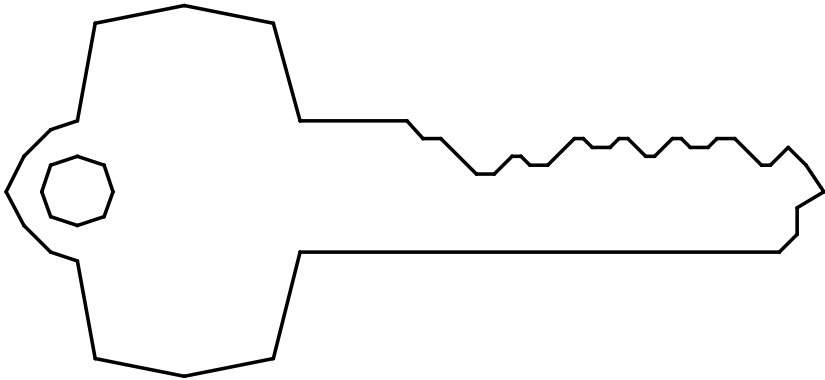
(William Frey, L. Paul Chew, Jim Ruppert)



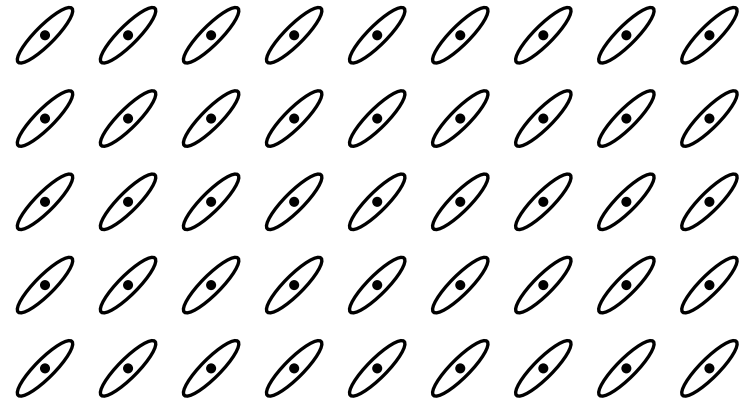
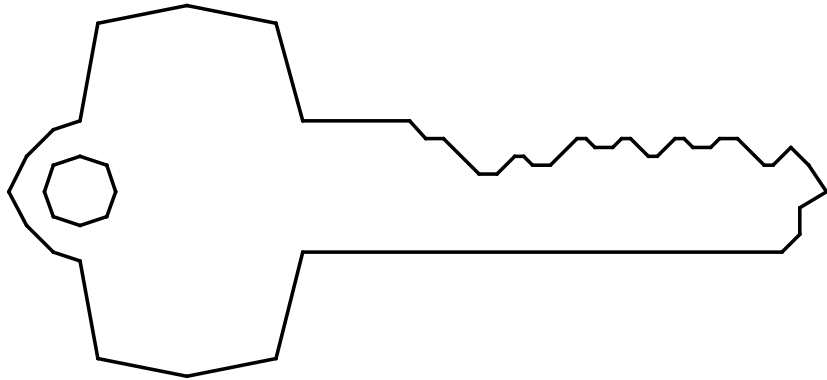
- Always maintain Delaunay triangulation.
- Eliminate any triangle with small angle ( $< 20^\circ$ ) by inserting vertex at center of circumscribing circle.
- No smaller edge is introduced  $\rightarrow$  guaranteed to terminate.

This solves the isotropic case,  $M = \text{identity}$ .

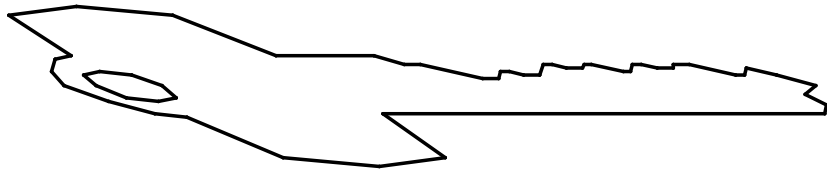
# Easy Case: $M = \text{constant}$



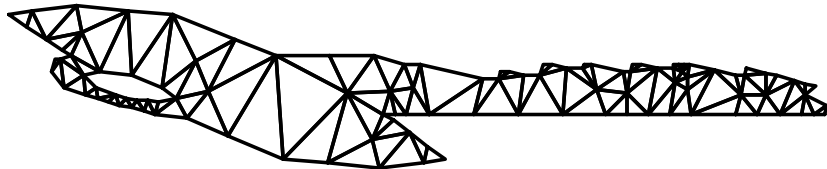
# Easy Case: $M = \text{constant}$



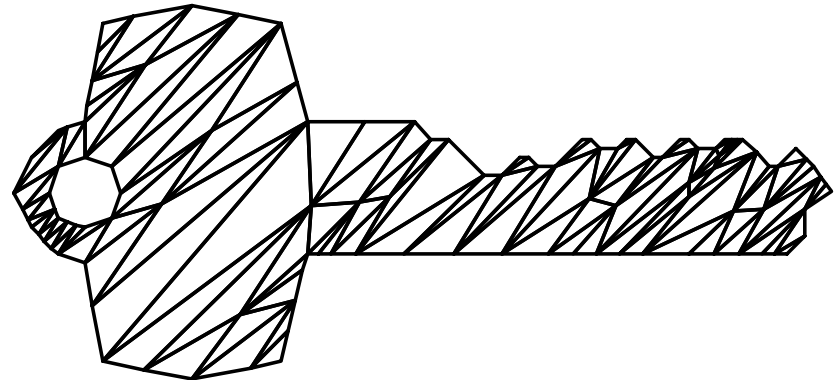
1. Apply  $F$  to the domain



2. Isotropic meshing

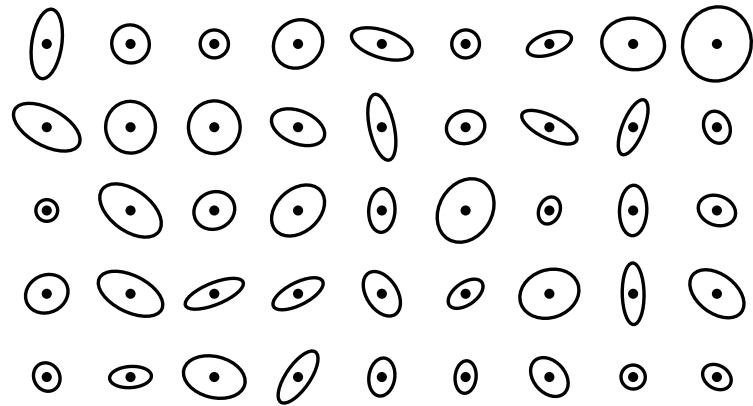


3. Apply  $F^{-1}$



# Remarks on Anisotropy

- Large distortion isn't a problem.
- *Rapid variation* in the metric tensor field is a problem.

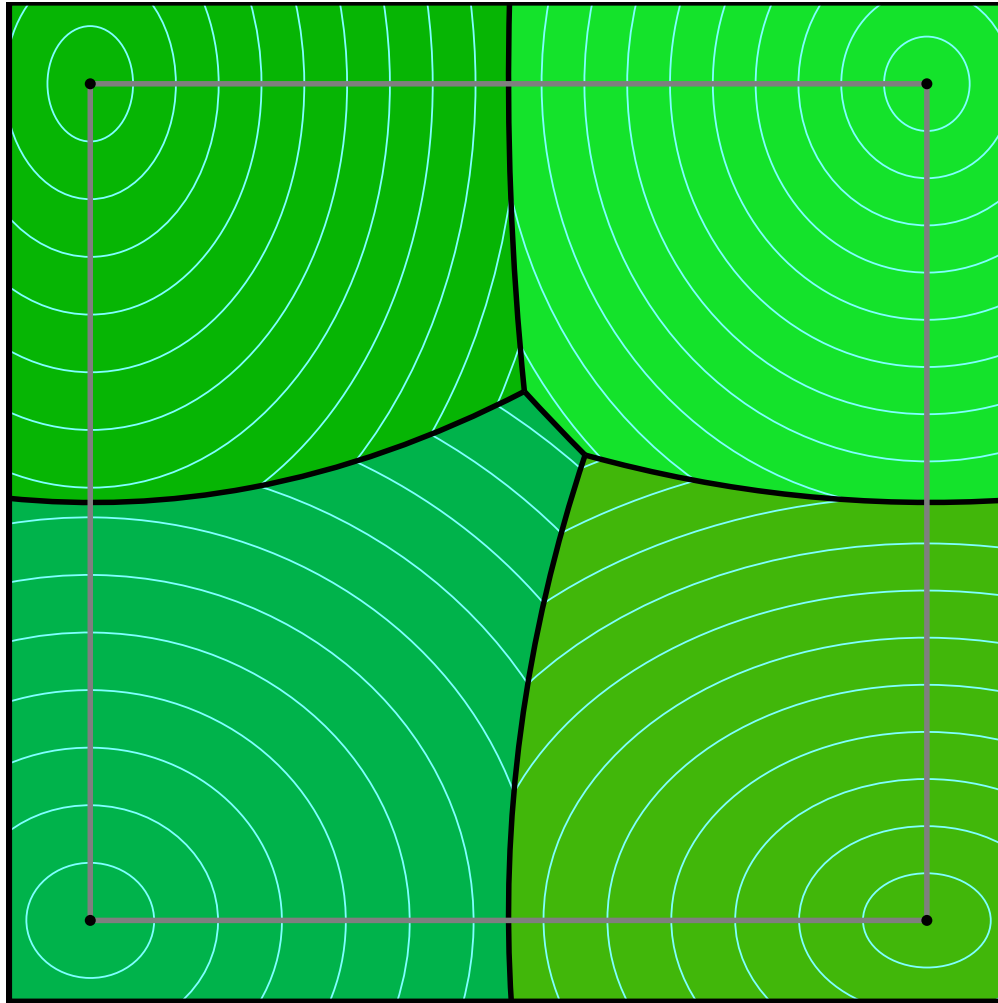


## About our Algorithm

- First algorithm for *guaranteed-quality* anisotropic meshing.
- Reduces to standard Delaunay refinement when  $M$  is constant.
- We can quantify how much refinement is caused by variation in  $M$ .

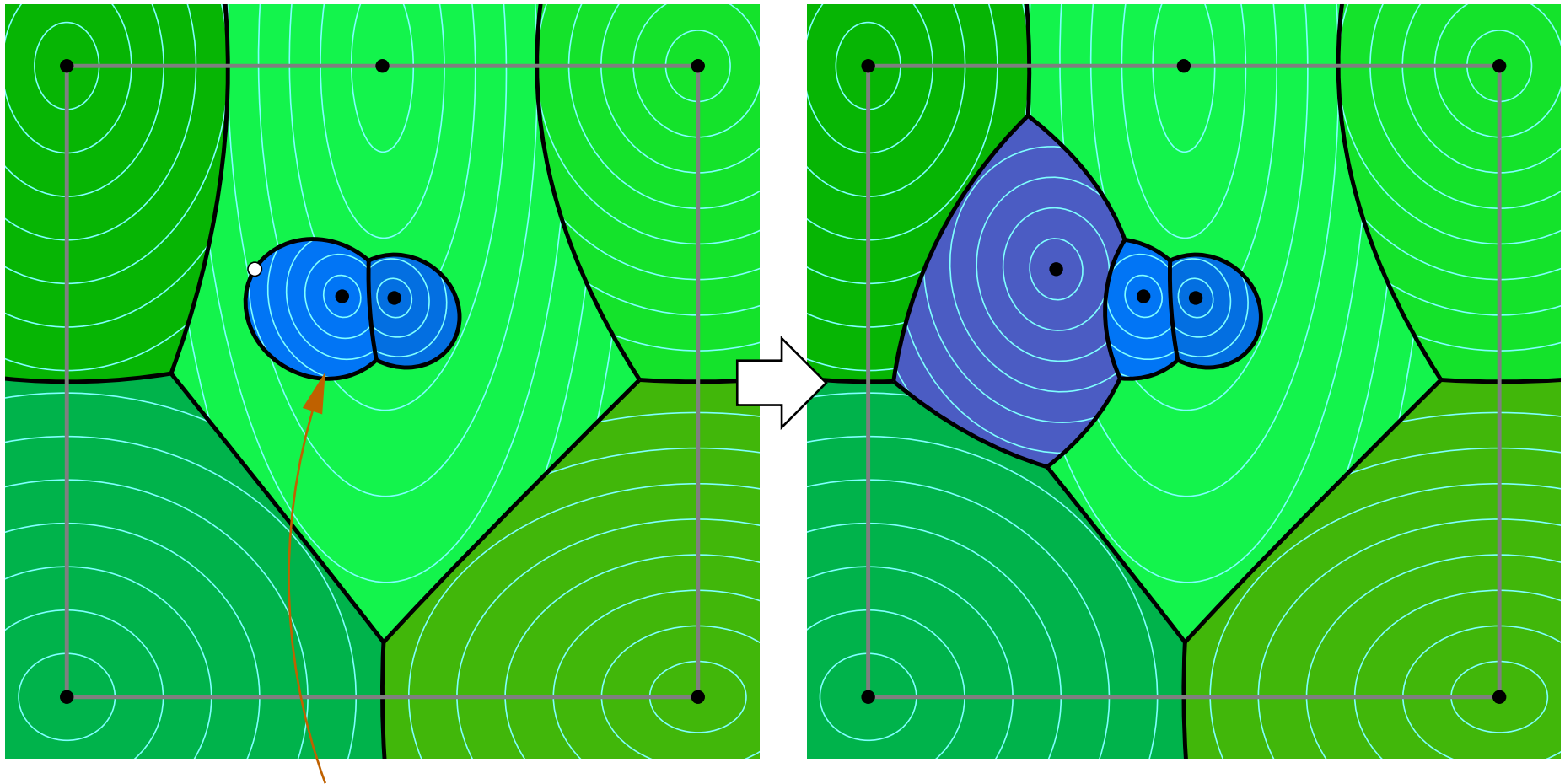


# Voronoi Refinement Algorithm



Begin with the anisotropic Voronoi diagram of the vertices of the domain.

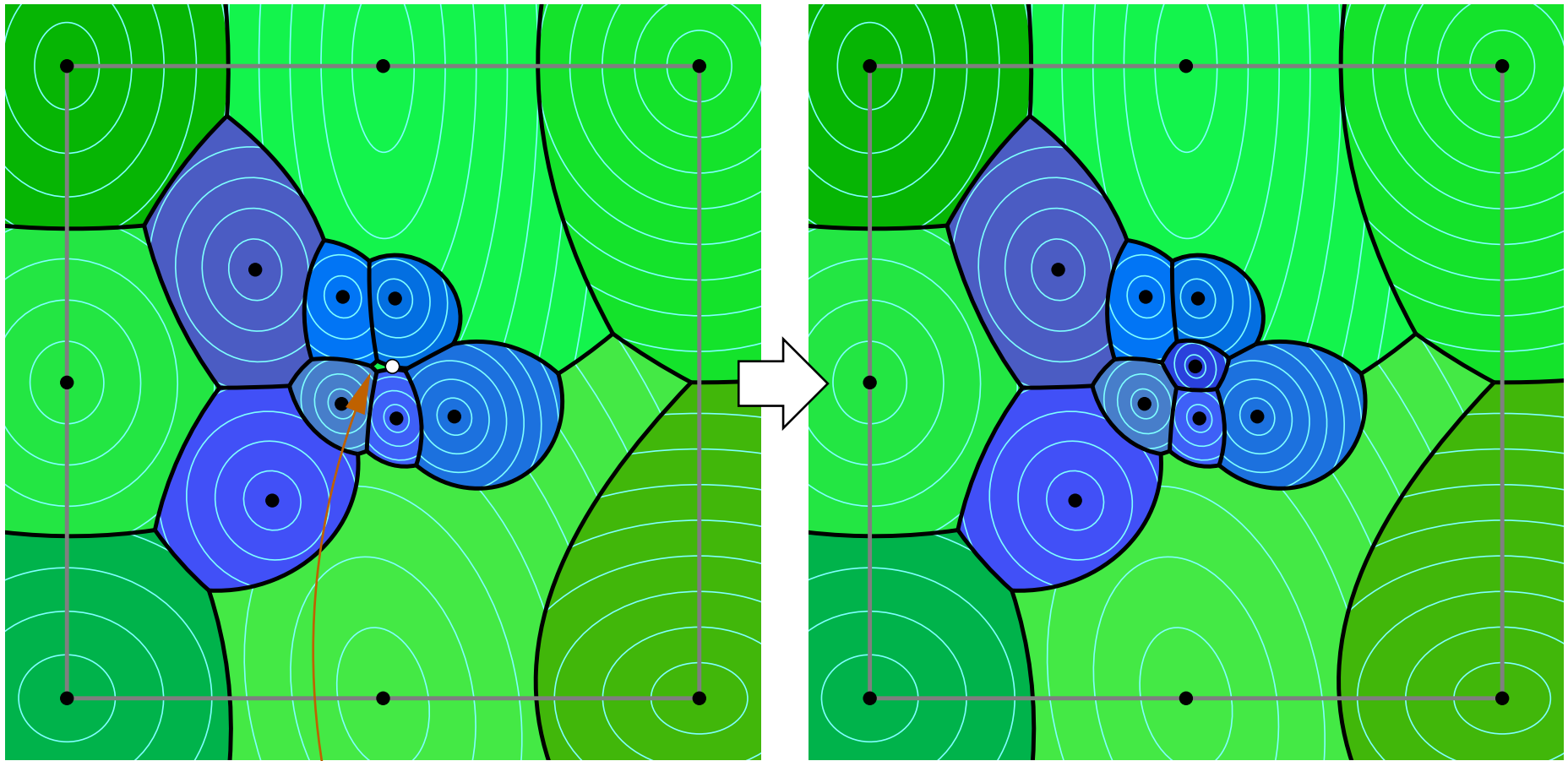
# Voronoi Refinement Algorithm



Islands

Insert new sites on unwedged portions of arcs.

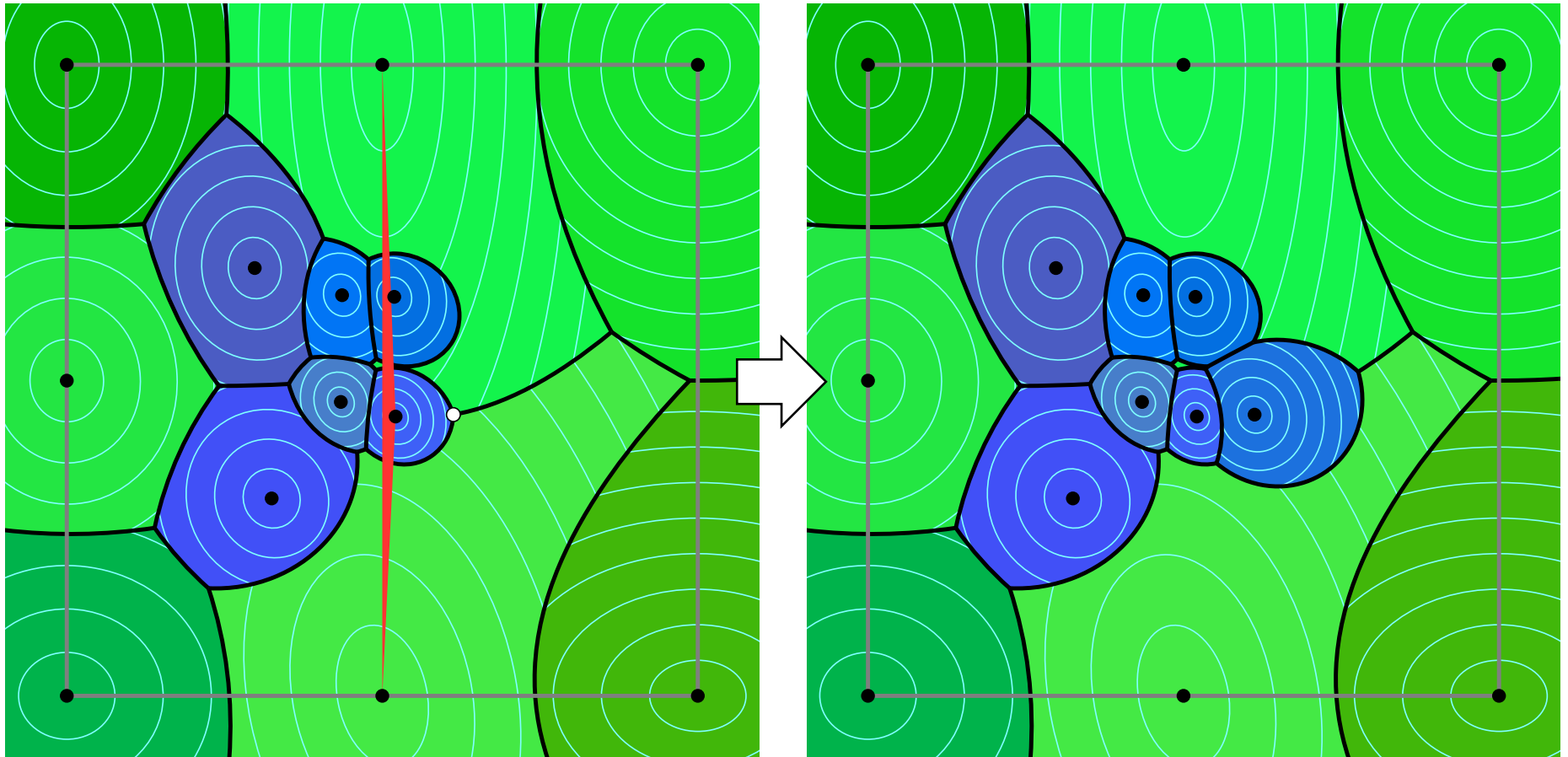
# Voronoi Refinement Algorithm



Orphan

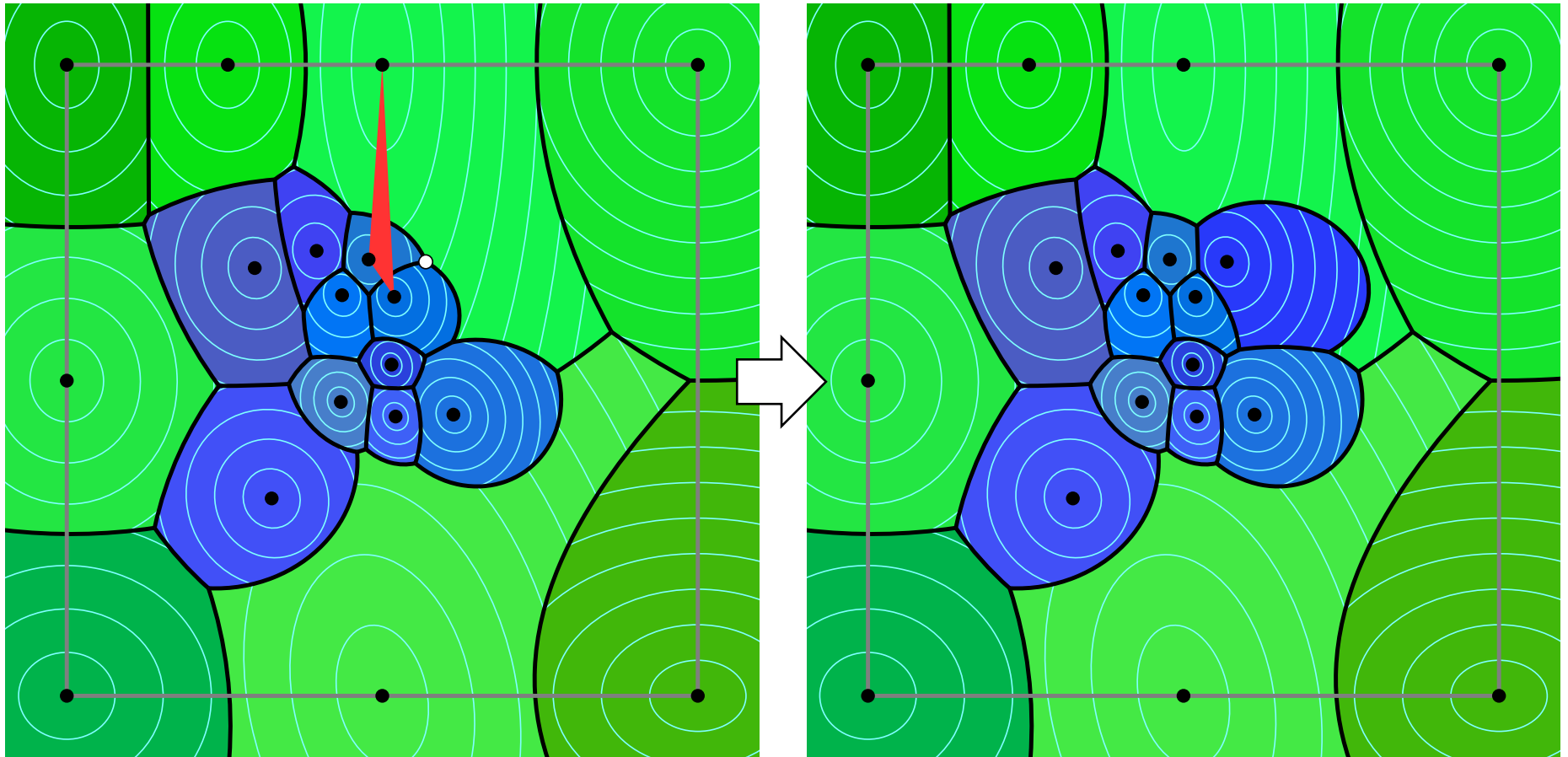
Insert new sites on unwedged portions of arcs.

# Voronoi Refinement Algorithm



Insert new sites at Voronoi vertices that dualize to inverted triangles.

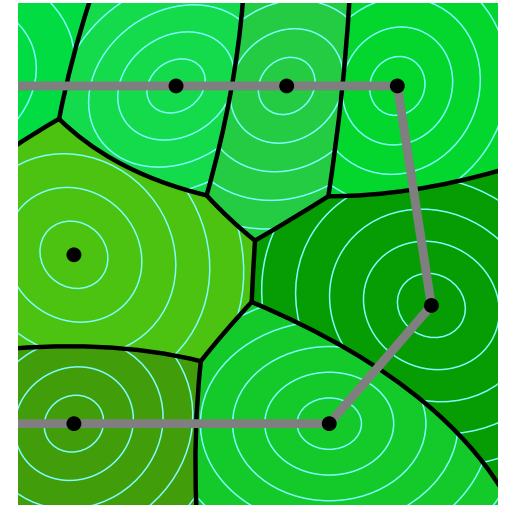
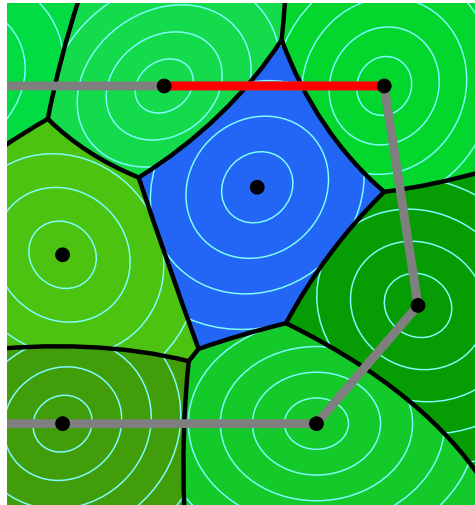
# Voronoi Refinement Algorithm



Insert new sites at Voronoi vertices that dualize to poor-quality triangles.

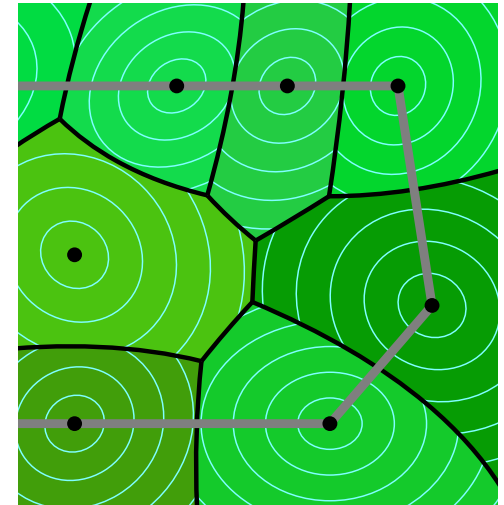
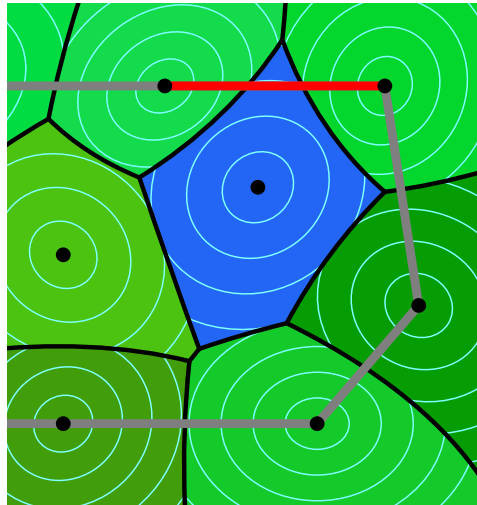
# Special Rules for the Boundary

Encroachment:  
a segment is split  
if it intersects  
a cell not  
belonging to  
an endpoint.

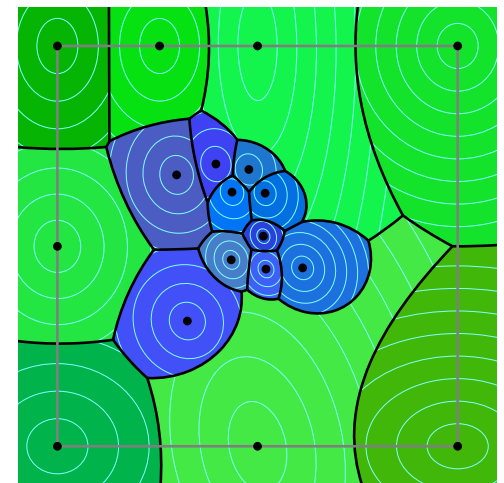
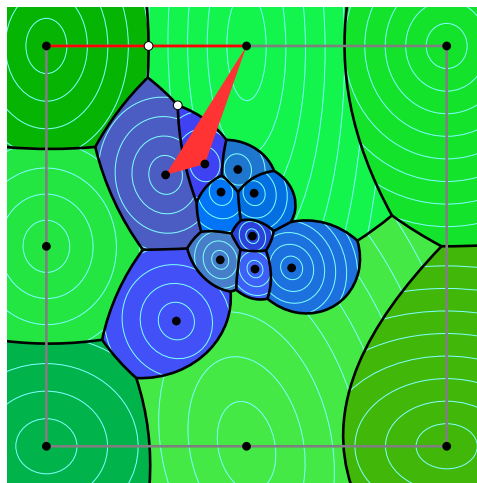


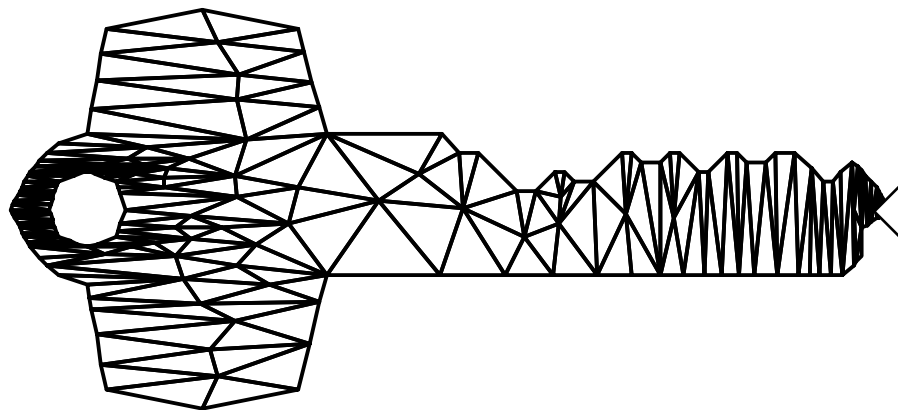
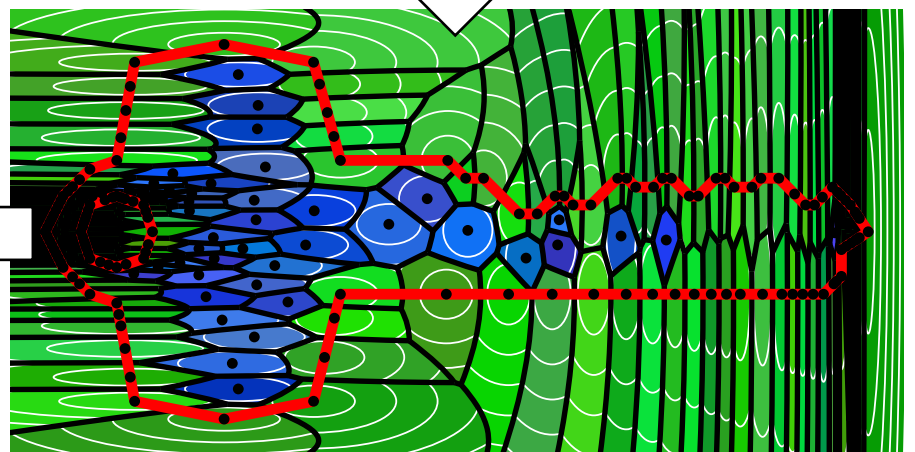
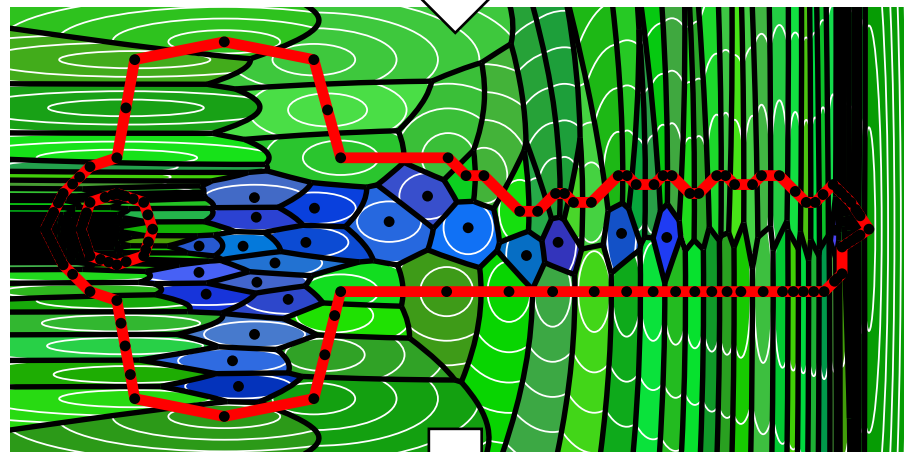
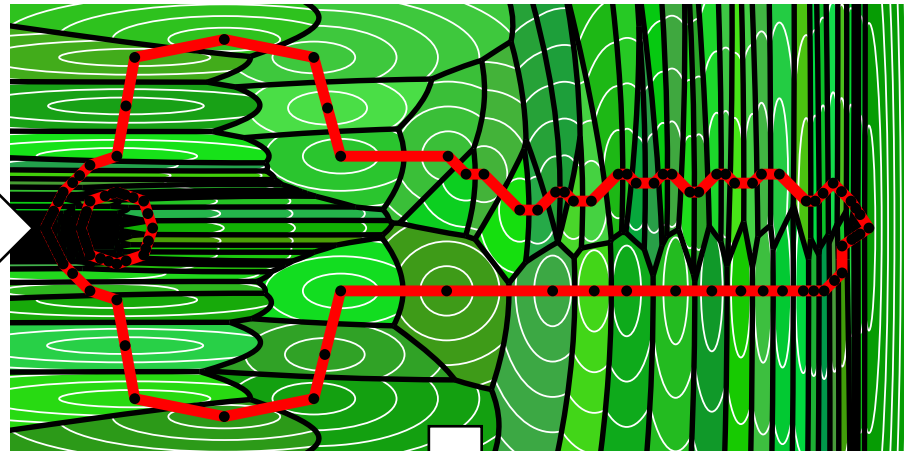
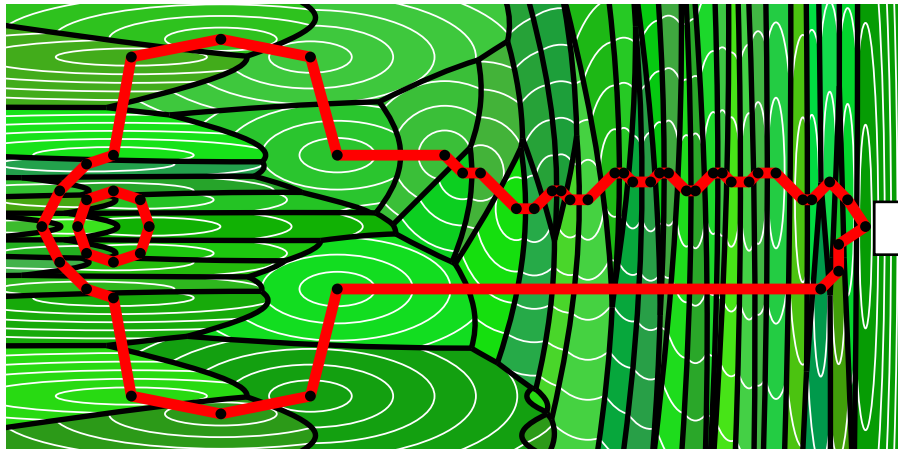
# Special Rules for the Boundary

Encroachment:  
a segment is split  
if it intersects  
a cell not  
belonging to  
an endpoint.



Insertion of  
encroaching sites  
is (usually)  
forbidden.  
Split the  
segment instead.

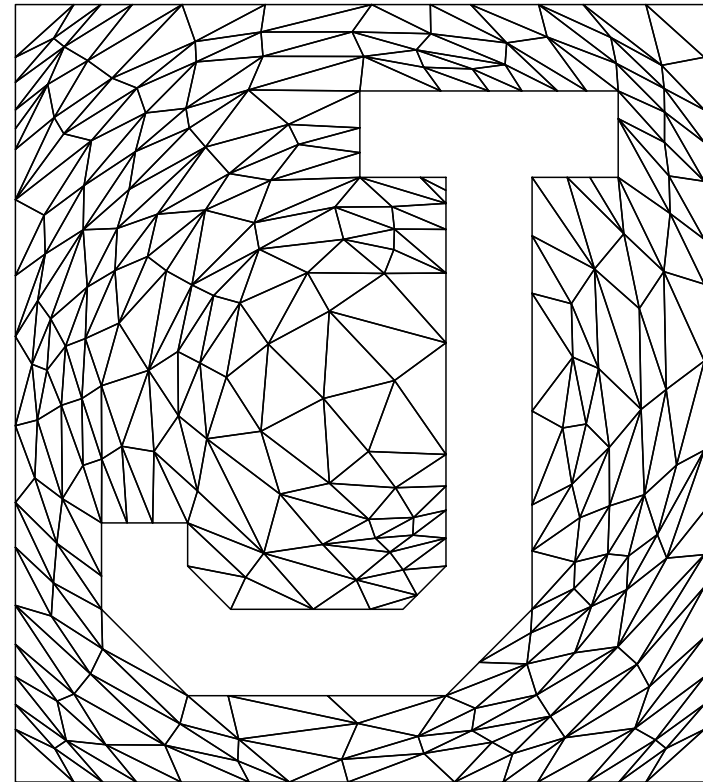
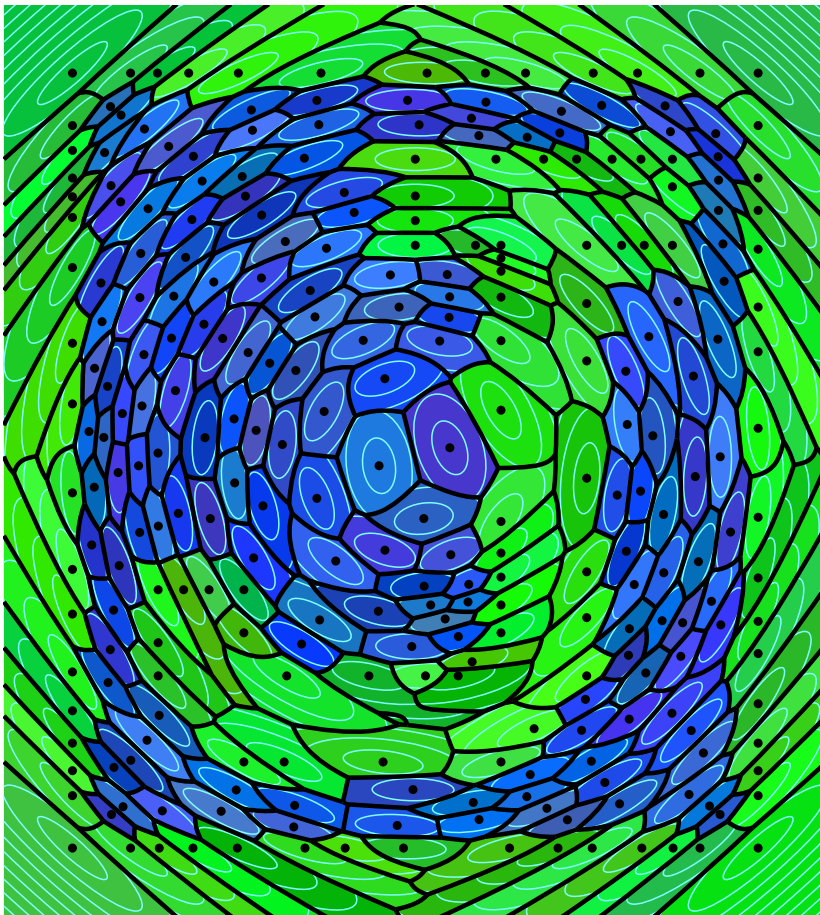






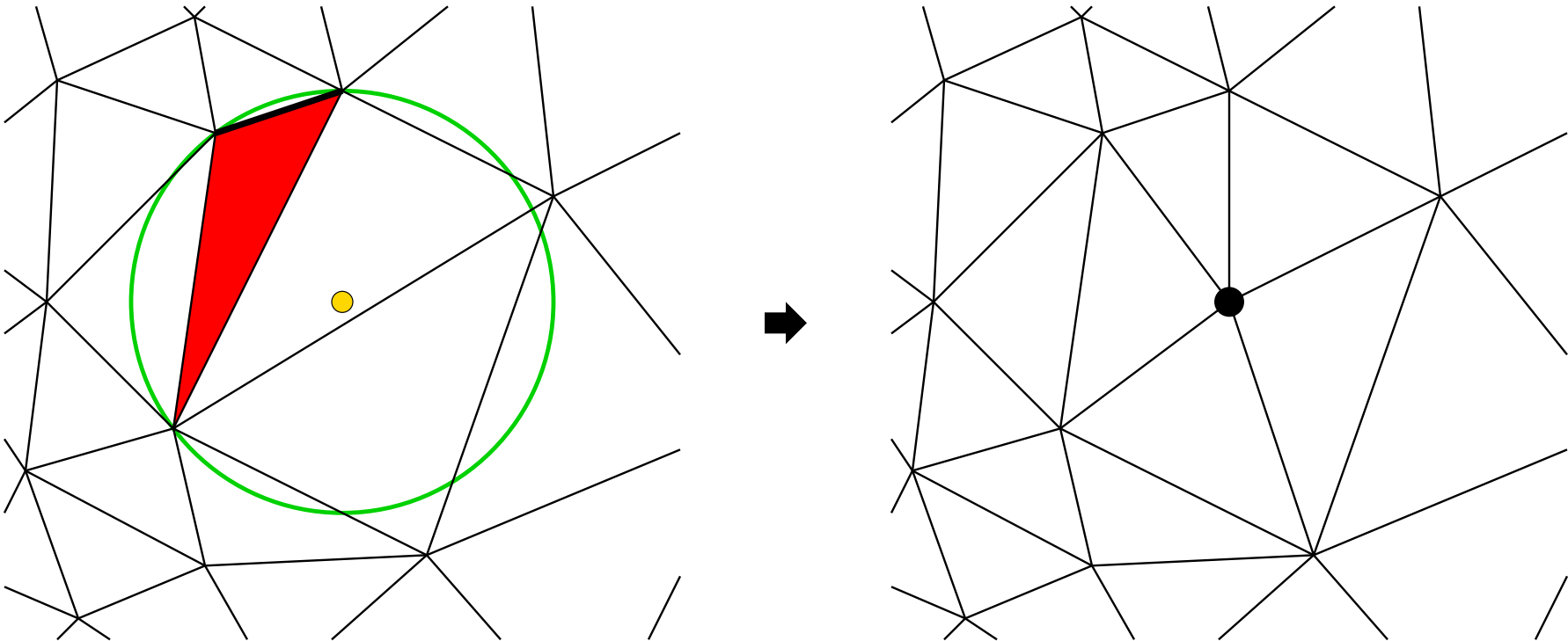
# Main Result

If metric tensor  $M$  is smooth with bounded derivatives, no triangle has angle  $< 20^\circ$  as measured by any point in the triangle.



# Why Does It Work?

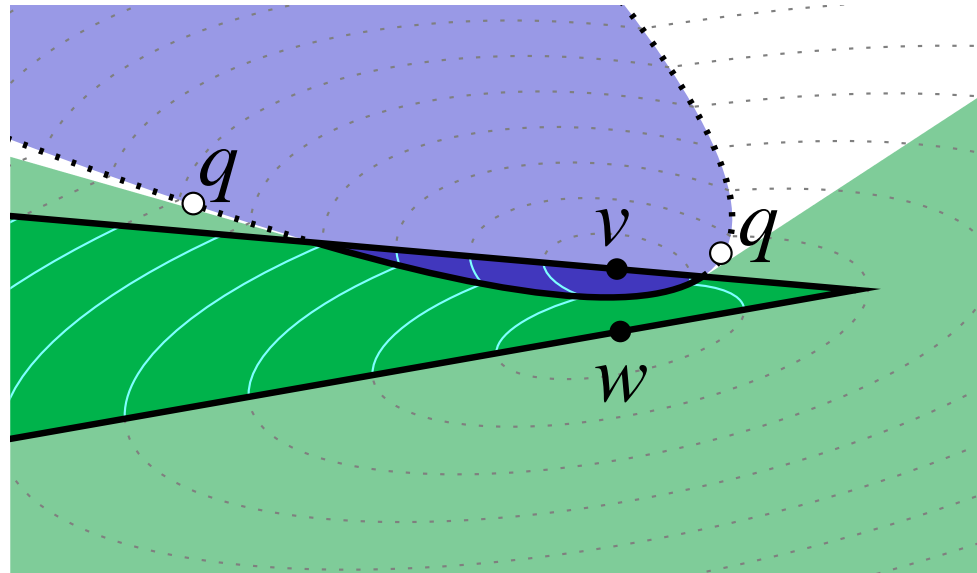
- It attacks every bad triangle and topological irregularity. Therefore, it will either succeed or refine forever.
- A bad triangle can exist only where a short edge lies beside a large gap. Filling the gap creates no shorter edges.



# Why Does It Work?

If a point  $q$  on a Voronoi arc is not wedged, then either

- $q$  is far from  $v$  and  $w$ , or
- $M_v$  and  $M_w$  are very different.

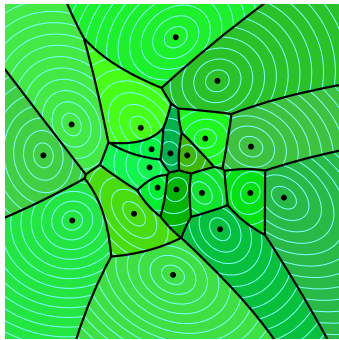


In the first condition, new edges are no shorter than the shortest existing edge.

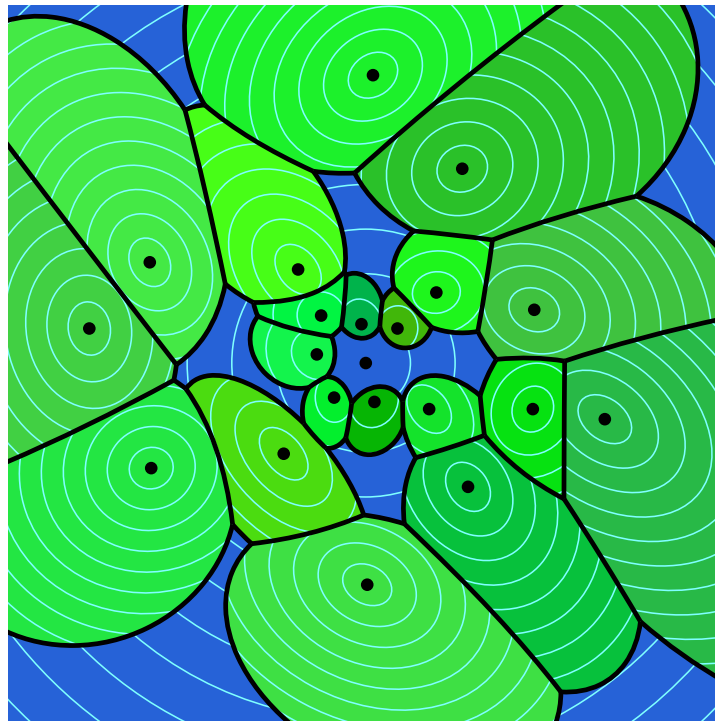
Refinement will alleviate the second condition.

# Loose Anisotropic Voronoi Diagrams

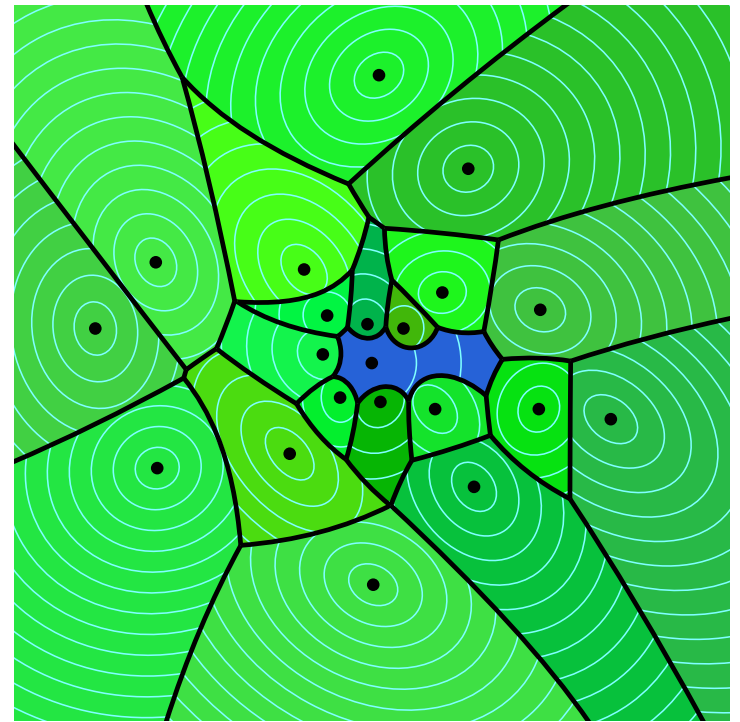
Fast local site insertion replaces  $O(n^{2+\epsilon})$  alg.



before



anisotropic  
Voronoi diagram



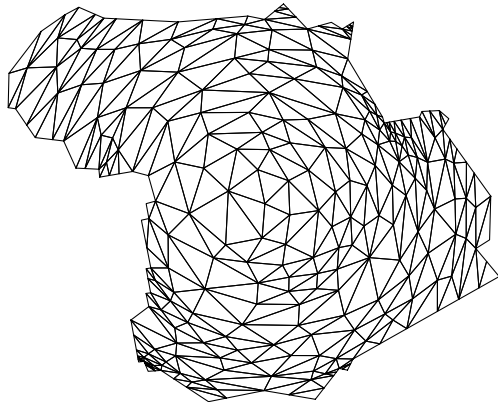
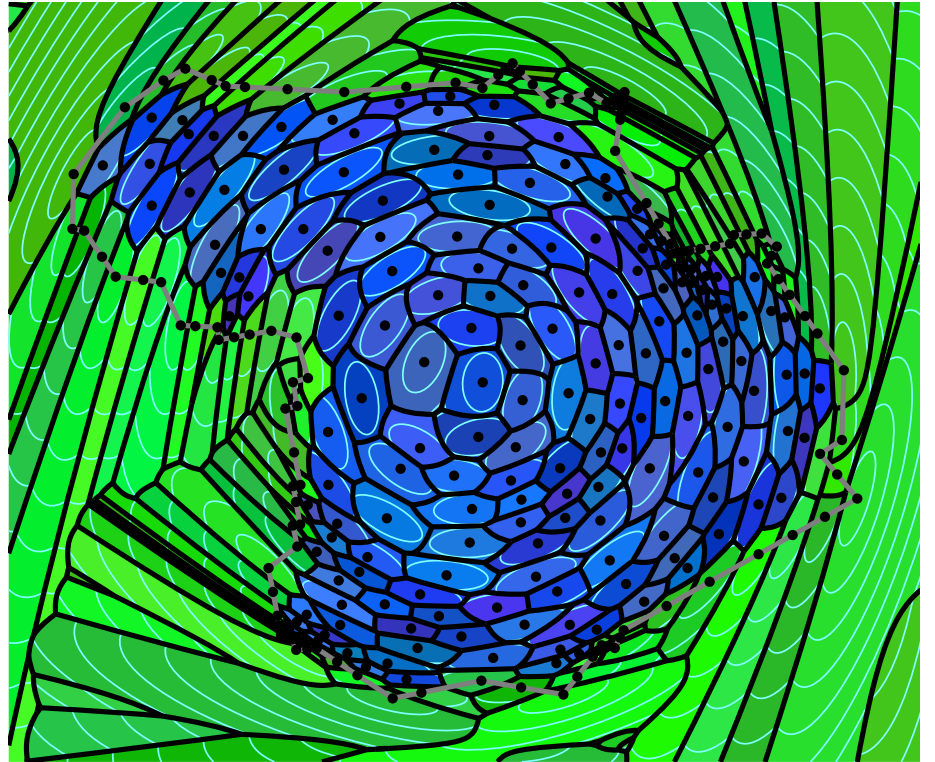
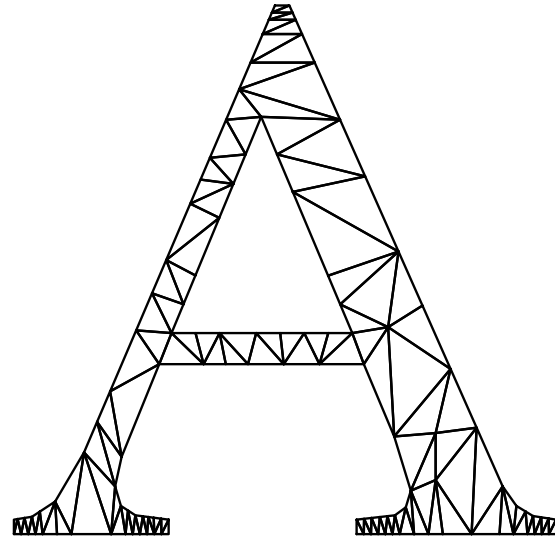
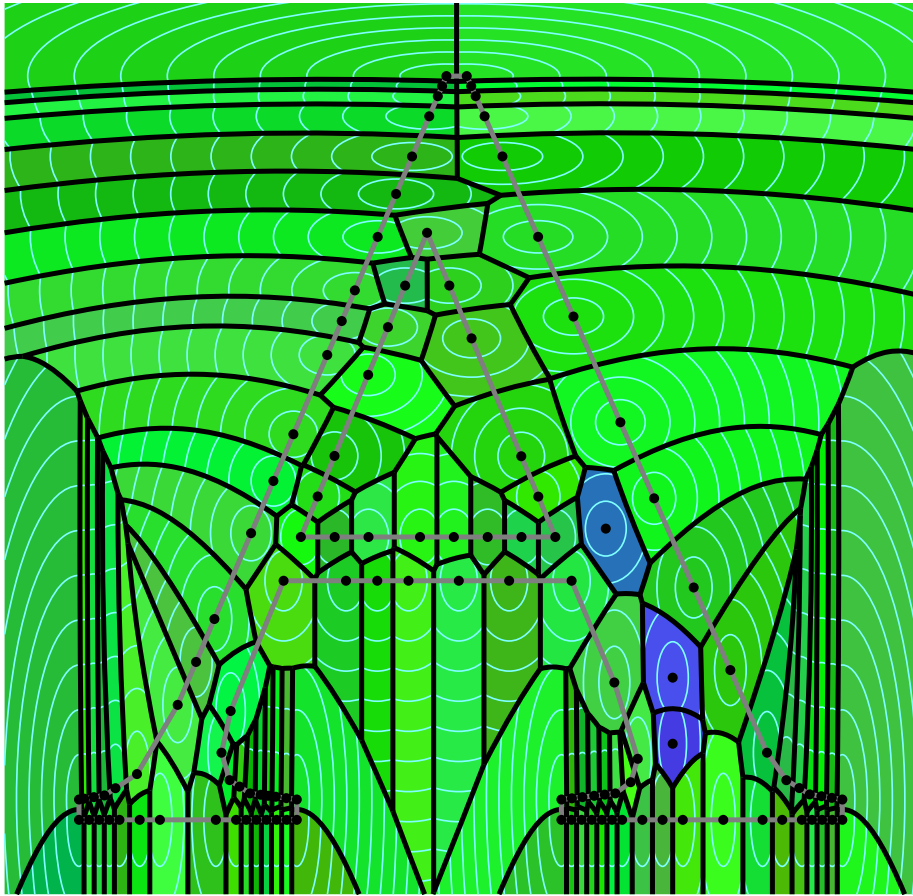
loose anisotropic  
Voronoi diagram

# Conclusions

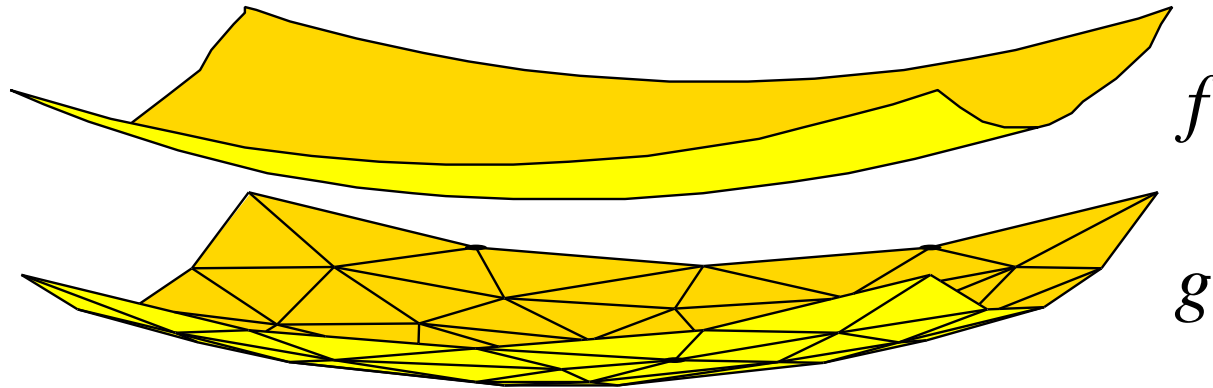
- Anisotropic Voronoi diagrams offer an elegant and fast way to define anisotropic “Delaunay” triangulations.
- The first theoretically guaranteed anisotropic mesh generation algorithm!

# Future Work

- Should work in practice in 3D (though the theoretical properties don't all follow).



# Anisotropy and Interpolation Error



$H$  = Hessian of  $f$ .

Suppose  $|\mathbf{d}^T H(p) \mathbf{d}| < \mathbf{d}^T C \mathbf{d}$  for any direction  $\mathbf{d}$ .

Let  $E^2 = C$  with  $E$  symmetric positive definite.

You can judge the error  $\|f - g\|_\infty$  of an element  $t$  by judging  $Et$  by isotropic error bounds/measures.

