- You have 80 minutes for the exam.
- The exam is closed book, closed notes except your one-page crib sheet.
- No calculators or electronic items.
- Mark your answers ON THE EXAM ITSELF. If you are not sure of your answer you may wish to provide a brief explanation.
- For true/false questions, fill in the True/False bubble.
- For multiple-choice questions, fill in the bubbles for ALL CORRECT CHOICES (in some cases, there may be more than one). We have introduced a negative penalty for false positives for the multiple choice questions such that the expected value of randomly guessing is 0 . Don't worry, for this section, your score will be the maximum of your score and 0 , thus you cannot incur a negative score for this section.

| First name |  |
| :--- | :--- |
| Last name |  |
| SID |  |
| First and last name of student to your left |  |
| First and last name of student to your right |  |

For staff use only:

| Q1. | True or False | $/ 26$ |
| :---: | :--- | :---: |
| Q2. | Multiple Choice | $/ 36$ |
| Q3. | Parameter Estimation | $/ 10$ |
| Q4. | Dual Solution for Ridge Regression | $/ 8$ |
| Q5. | Regularization and Priors for Linear Regression | $/ 8$ |
|  | Total | $/ 88$ |

## Q1. [26 pts] True or False

(a) $[2 \mathrm{pts}]$ If the data is not linearly separable, then there is no solution to the hard-margin SVM.TrueFalse
(b) [2 pts] Logistic Regression can be used for classification.
$\bigcirc$ True $\bigcirc$ False
(c) [2 pts $]$ In logistic regression, two ways to prevent $\beta$ vectors from getting too large are using a small step size and using a small regularization value.True $\bigcirc$ False
(d) [2 pts] The L2 norm is often used because it produces sparse results, as opposed to the L1 norm which does not.
$\bigcirc$ TruFalse
(e) [2 pts] For a Multivariate Gaussian, the eigenvalues of the covariance matrix are inversely proportional to the lengths of the ellipsoid axes that determine the isocontours of the density.
$\bigcirc$ True $\bigcirc$ False
(f) [2 pts] In a generative binary classification model where we assume the class conditionals are distributed as Poisson, and the class priors are Bernoulli, the posterior assumes a logistic form.
$\bigcirc$ True $\bigcirc$
False
(g) [2 pts] Maximum likelihood estimation gives us not only a point estimate, but a distribution over the parameters that we are estimating.
$\bigcirc$ True $\bigcirc$ False
(h) [2 pts] Penalized maximum likelihood estimators and Bayesian estimators for parameters are better used in the setting of low-dimensional data with many training examples as opposed to the setting of high-dimensional data with few training examples.
$\bigcirc$ True $\bigcirc$ False
(i) $[2 \mathrm{pts}]$ It is not a good machine learning practice to use the test set to help adjust the hyperparameters of your learning algorithm.
$\bigcirc$ True $\bigcirc$ False
(j) [2 pts] A symmetric positive semi-definite matrix always has nonnegative elements.
$\bigcirc$ True $\bigcirc$ False
(k) [2 pts] For a valid kernel function $K$, the corresponding feature mapping $\phi$ can map a finite dimensional vector into an infinite dimensional vector.TrueFalse
(l) [2 pts] The more features that we use to represent our data, the better the learning algorithm will generalize to new data points.TrueFalse
(m) [2 pts] A discriminative classifier explicitly models $P(Y \mid X)$
$\bigcirc$ True $\bigcirc$ False

## Q2. [36 pts] Multiple Choice

(a) [3 pts] Which of the following algorithms can you use kernels with?
$\bigcirc$ Support Vector MachinesNone of the above
$\bigcirc$ Perceptrons
(b) $[3 \mathrm{pts}]$ Cross validation:
$\bigcirc$ Is often used to select hyperparameters

Is guaranteed to prevent overfitting

Does nothing to prevent overfitting

None of the above
(c) $[3 \mathrm{pts}]$ In linear regression, L2 regularisation is equivalent to imposing a:Logistic priorLaplace prior
$\bigcirc$ Gaussian priorGaussian class-conditional
(d) [3 pts] Say we have two 2-dimensional Gaussian distributions representing two different classes. Which of the following conditions will result in a linear decision boundary:
$\bigcirc$ Same mean for both classes
$\bigcirc$ Same covariance matrix for both classes

Linearly separable data
(e) $[3 \mathrm{pts}]$ The normal equations can be derived from:
$\bigcirc$ Minimizing empirical risk
$\bigcirc$ Assuming that $Y=\beta^{T} x+\epsilon$, where $\epsilon \sim N\left(0, \sigma^{2}\right)$.
$\bigcirc$ Assuming that the $P(Y \mid X=x)$ is distributed normally with mean $\beta^{\boldsymbol{\top}} x$ and variance $\sigma^{2}$
$\bigcirc$ Finding a linear combination of the rows of the design matrix that minimizes the distance to our vector of labels $Y$
(f) $[3 \mathrm{pts}]$ Logistic regression can be motivated from:
$\bigcirc$ Generative models with uniform class conditionals

O Generative models with Gaussian class conditionals
(g) [3 pts] The perceptron algorithm will converge:
$\bigcirc$ If the data is linearly separable
$\bigcirc$ Even if the data is linearly inseparable

Log odds being equated to an affine function of $x$None of the aboveAs long as you initialize $\theta$ to all 0 's
$\bigcirc$ Always
(h) [3 pts] Which of the following is true:
$\bigcirc$ Newton's Method typically is more expensive to calculate than gradient descent, per iteration
Or quadratic equations, Newton's Method typically requires fewer iterations than gradient descent
$\bigcirc$ Gradient descent can be viewed as iteratively reweighted least squaresNone of the above
(i) [3 pts] Which of the following statements about duality and SVMs is (are) true?

Complementary slackness implies that every training point that is misclassified by a soft-margin SVM is a support vector.

$\bigcirc$
When we solve the SVM with the dual problem, we need only the dot product of $x_{i}, x_{j}$ for all $i, j$, and no other information about the $x_{i}$.
$\bigcirc$ We use Lagrange multipliers in an optimization problem with inequality $(\leq)$ constraints.None of the above
(j) [3 pts] Which of the following distance metrics can be computed exclusively with inner products, assuming $\Phi(x)$ and $\Phi(y)$ are feature mappings of $x$ and $y$, respectively?
$\Phi(x)-\Phi(y)$$\|\Phi(x)-\Phi(y)\|_{2}^{2}$.
$\bigcirc \Phi(x)-\Phi(y) \|_{1}$None of the above
(k) [3 pts] Strong duality holds for:Hard Margin SVMConstrained optimization problems in general
○ Soft Margin SVMNone of the above
(l) [3 pts] Which the following facts about the ' C ' in SVMs is (are) true?
$\bigcirc$ As C approaches 0 , the soft margin SVM isA larger $C$ tends to create a larger margin equal to the hard margin SVMNone of the above
$\bigcirc$ C can be negative, as long as each of the slack variables are nonnegative

## Q3. [10 pts] Parameter Estimation

In this problem, we have $n$ trials with $k$ possible types of outcomes $\{1,2, \ldots, k\}$. Suppose we observe $X_{1}, \ldots, X_{k}$ where each $X_{i}$ is the number of outcomes of type $i$. If $p_{i}$ refers to the probability that a trial has outcome $i$, then $\left(X_{1}, \ldots, X_{k}\right)$ is said to have a multinomial distribution with parameters $p_{1}, \ldots, p_{k}$, denoted $\left(X_{1}, \ldots, X_{k}\right) \sim \operatorname{Multinomial}\left(p_{1}, \ldots, p_{k}\right)$. It may be useful to know that the probability mass function of the multinomial distribution is given as follows.

$$
P\left(X_{1}=x_{1}, \ldots, X_{k}=x_{k}\right)=\frac{n!}{x_{1}!x_{2}!\ldots x_{k}!} p_{1}^{x_{1}} \ldots p_{k}^{x_{k}}
$$

We want to find the maximum likelihood estimators for $p_{1}, \ldots, p_{k}$. You may assume that $p_{i}>0$ for all $i$.
(a) [4 pts] What is the log-likelihood function, $l\left(p_{1}, \ldots, p_{k} \mid X_{1}, \ldots, X_{k}\right)$ ?
(b) $[6 \mathrm{pts}]$ You might notice that unconstrained maximization of this function leads to an answer in which we set each $p_{i}=\infty$. But this is wrong. We must add a constraint such that the probabilities sum up to 1 . Now, we have the following optimization problem.

$$
\begin{gathered}
\max _{p_{1}, \ldots, p_{k}} l\left(p_{1}, \ldots, p_{k} \mid X_{1}, \ldots, X_{k}\right) \\
\quad \text { s.t. } \sum_{i=1}^{k} p_{i}=1
\end{gathered}
$$

Recall that we can use the method of Lagrange multipliers to solve an optimization problem with equality constraints. Using this method, find the maximum likelihood estimators for $p_{1}, \ldots, p_{k}$.

## Q4. [8 pts] Dual Solution for Ridge Regression

Recall that ridge regression minimizes the objective function:

$$
L(w)=\|X w-y\|_{2}^{2}+\lambda\|w\|_{2}^{2}
$$

where $X$ is an $n$-by- $d$ design matrix, $w$ is a $d$-dimensional vector and $y$ is a $n$-dimensional vector. We already know that the function $L(w)$ is minimized by

$$
w^{*}=\left(X^{T} X+\lambda I\right)^{-1} X^{T} y
$$

Alternatively, the minimizer can be represented by a linear combination of the design matrix rows. That is, there exists a $n$-dimensional vector $\alpha^{*}$ such that the objective function $L(w)$ is minimized by $w^{*}=X^{T} \alpha^{*}$. The vector $\alpha^{*}$ is called the dual solution to the linear regression problem.
(a) [2 pts] Using the relation $w=X^{T} \alpha$, define the objective function $L$ in terms of $\alpha$.
(b) $[3 \mathrm{pts}]$ Show that $\alpha^{*}=\left(X X^{T}+\lambda I\right)^{-1} y$ is a dual solution.
(c) [3 pts] To make the solution in question (b) well-defined, the matrix $X X^{T}+\lambda I$ has to be an invertible matrix. Assuming $\lambda>0$, show that $X X^{T}+\lambda I$ is an invertible matrix. (Hint: positive definite matrices are invertible)

## Q5. [8 pts] Regularization and Priors for Linear Regression

Linear regression is a model of the form $P(y \mid \mathbf{x}) \sim \mathcal{N}\left(\mathbf{w}^{\mathbf{T}} \mathbf{x}, \sigma^{2}\right)$, where $\mathbf{w}$ is a d-dimensional vector. Recall that in ridge regression, we add an $\ell_{2}$ regularization term to our least squares objective function to prevent overfitting, so that our loss function becomes:

$$
\begin{equation*}
J(\mathbf{w})=\sum_{i=1}^{n}\left(Y_{i}-\mathbf{w}^{\mathbf{T}} \mathbf{X}_{\mathbf{i}}\right)^{2}+\lambda \mathbf{w}^{\mathbf{T}} \mathbf{w} \tag{*}
\end{equation*}
$$

We can arrive at the same objective function in a Bayesian setting, if we consider a MAP (maximum a posteriori probability) estimate, where $\mathbf{w}$ has the prior distribution $\mathcal{N}(0, f(\lambda, \sigma) I)$.
(a) $[3 \mathrm{pts}]$ What is the conditional density of $w$ given the data?
(b) [5 pts] What $f(\lambda, \sigma)$ makes this MAP estimate the same as the solution to $\left(^{*}\right)$ ?

