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CS-184: Computer Graphics

Lecture #19: Motion Capture

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	Today
	<ul style="list-style-type: none">• Motion Capture

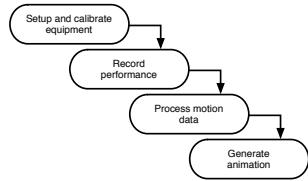
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Motion Capture

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- Record motion from physical objects
- Use motion to animate virtual objects

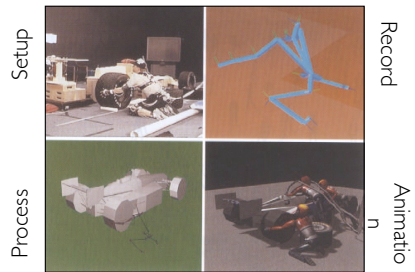
Simplified Pipeline:



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Basic Pipeline

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From Rose, et al., 1998

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Capture Equipment

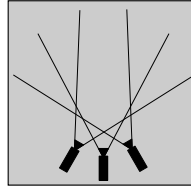
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• Passive Optical Advantages

- Accurate
- May use many markers
- No cables
- High frequency

• Disadvantages

- Requires lots of processing
- Expensive systems
- Occlusions
- Marker swap
- Lighting / camera limitations



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Capture Equipment

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• Active Optical

- Similar to passive but uses LEDs
- Blink LEDs, no marker swap
- Number of markers trades off w/ frame rate



Phoenix Technology

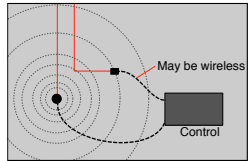


Phase Space 8

Capture Equipment

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- Magnetic Trackers
 - Transmitter emits field
 - Trackers sense field
 - Trackers report position and orientation



Capture Equipment

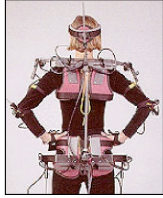
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- Electromagnetic Advantages
 - 6 DOF data
 - No occlusions
 - Less post processing
 - Cheaper than optical
- Disadvantages
 - Cables
 - Problems with metal objects
 - Low(er) frequency
 - Limited range
 - Limited number of trackers

Capture Equipment

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- Electromechanical



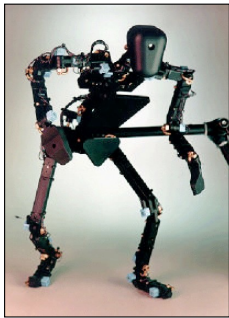
Analogus

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Capture Equipment

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- Puppets



Digital Image Design

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Performance Capture

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- Many studios regard *Motion* Capture as evil
 - Synonymous with low quality motion
 - No directive / creative control
 - Cheap
- **Performance Capture is different**
 - Use mocap device as an expressive input device
 - Similar to digital music and MIDI keyboards

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Manipulating Motion Data

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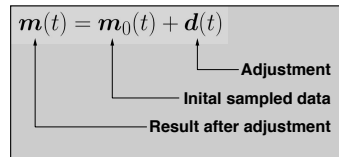
- Basic tasks
 - Adjusting
 - Blending
 - Transitioning
 - Retargeting
- Building graphs

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Adjusting

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- Define desired motion function in parts


$$m(t) = m_0(t) + d(t)$$

Adjustment
Initial sampled data
Result after adjustment

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Adjusting

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- Select adjustment function from “some nice space”
 - Example C2 B-splines
- Spread modification over reasonable period of time
 - User selects support radius

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Blending

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- Given two motions make a motion that combines qualities of both

$$m_{\alpha}(t) = \alpha m_a(t) + (1 - \alpha) m_b(t)$$

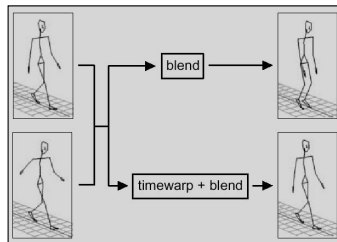
- Assume same DOFs
- Assume same parameter mappings

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Blending

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- Consider blending *slow-walk* and *fast-walk*



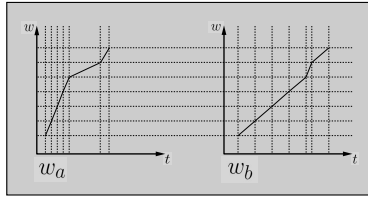
Bruderlin and Williams, SIGGRAPH 95

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Blending

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- Define timewarp functions to align features in motion



Normalized time is w

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Blending

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- Blend in normalized time

$$m_\alpha(w) = \alpha m_a(w_a) + (1 - \alpha) m_b(w_b)$$

- Blend playback rate

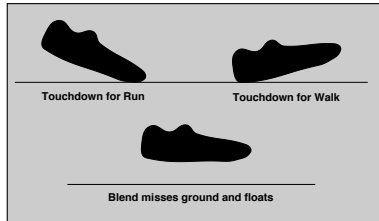
$$\frac{dt}{dw} = \alpha \frac{dt}{dw_a} + (1 - \alpha) \frac{dt}{dw_b}$$

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Blending

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- Blending may still break features in original motions

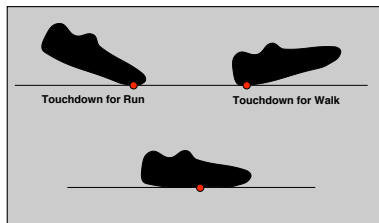


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Blending

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- Add explicit constrains to key points
 - Enforce with IK over time



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Blending / Adjustment

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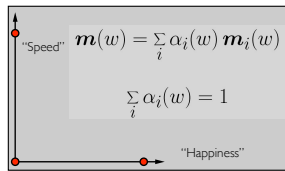
- Short edits will tend to look acceptable
- Longer ones will often exhibit problems
- Optimize to improve blends / adjustments
 - Add quality metric on adjustment
 - Minimize accelerations / torques
 - Explicit smoothness constraints
 - Other criteria...

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Multivariate Blending

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- Extend blending to multivariate interpolation



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Multivariate Blending

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- Extend blending to multivariate interpolation



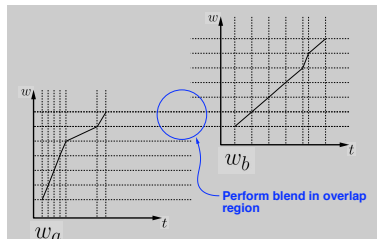
Use standard scattered-data interpolation methods

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Transitions

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- Transition from one motion to another



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Cyclification

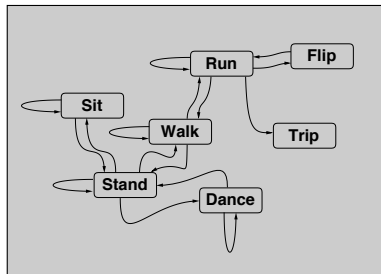
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- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

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Transition Graphs

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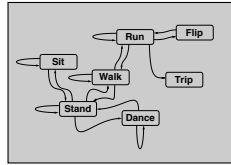


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Motion Graphs

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- Hand build motion graphs often used in games
 - Significant amount of work required
 - Limited transitions by design
- Motion graphs can also be built automatically



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Motion Graphs

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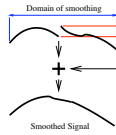
- Similarity metric
 - Measurement of how similar two frames of motion are
 - Based on joint angles or point positions
 - Must include some measure of velocity
 - Ideally independent of capture setup and skeleton
- Capture a "large" database of motions

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Motion Graphs

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- Random walks
 - Start in some part of the graph and randomly make transitions
 - Avoid dead ends
 - Useful for "idling" behaviors
- Transitions
 - Use blending algorithm



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Motion graphs

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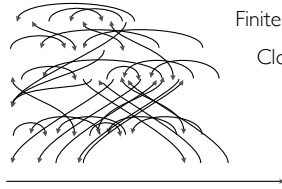
- Match imposed requirements
 - Start at a particular location
 - End at a particular location
 - Pass through particular pose
 - Can be solved using **dynamic programming**
 - Efficiency issues may require approximate solution
 - Notion of "goodness" of a solution

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Typical Motion Graph

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Walking #1
Running
Idle
Fall down
Walking #2
Punches



Finite number of states

Cloth is hysteretic

Recorded Time

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Naïve Precomputation

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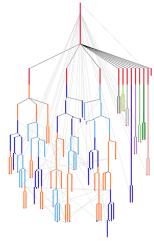
Initially computed cloth motion
Jumpy transitions



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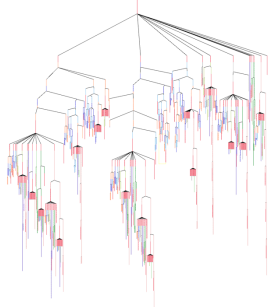
Graph Unrolling

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Graph Unrolling

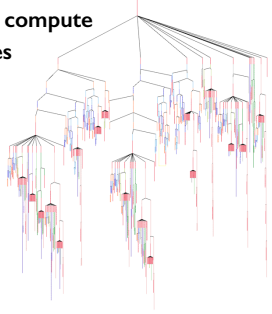
40



Graph Unrolling

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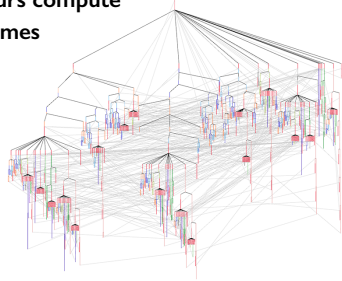
5000 hours compute
100K frames
330 GB



Graph Unrolling

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5000 hours compute
100K frames
330 GB



Precomputed Simulation

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- No significant CPU load at runtime
- Decouples quality from runtime cost
- No new data at runtime
 - Simulation can't crash application
- All motion can be inspected/edited
 - Allows QA and art direction of simulations
- Extend to other types of simulation?
- Dynamic variations?

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Suggested Reading

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- Fourier principles for emotion-based human figure animation, Unuma, Anjo, and Takeuchi, SIGGRAPH 95
- Motion signal processing, Bruderlin and Williams, SIGGRAPH 95
- Motion warping, Witkin and Popovic, SIGGRAPH 95
- Efficient generation of motion transitions using spacetime constraints, Rose et al., SIGGRAPH 96
- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Verbs and adverbs: Multidimensional motion interpolation, Rose, Cohen, and Bodenheimer, IEEE Computer Graphics and Applications, v. 18, no. 5, 1998

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