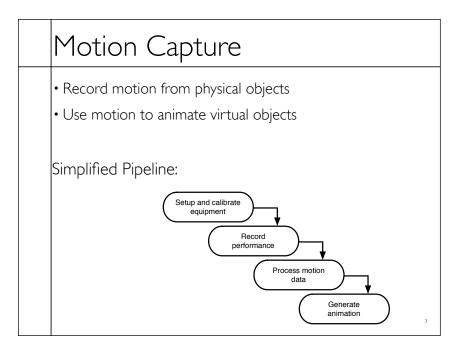
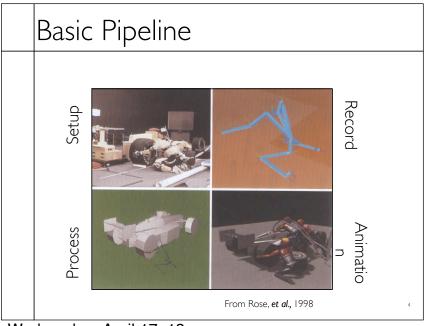
CS-184: Computer Graphics
Lecture #19: Motion Capture
Prof. James O'Brien University of California, Berkeley

Today	
• Motion Capture	
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What types of objects?

• Human, whole body

• Portions of body

• Facial animation

Animals

Puppets

• Other objects

Capture Equipment

Passive Optical

• Reflective markers

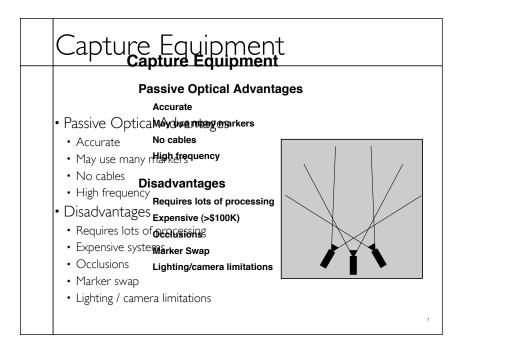
- IR (typically) illumination
- Special cameras
- Fast, high res., filters
- Triangulate for positions

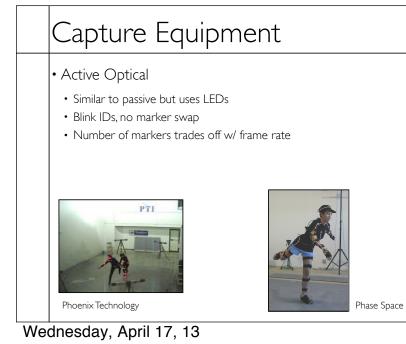


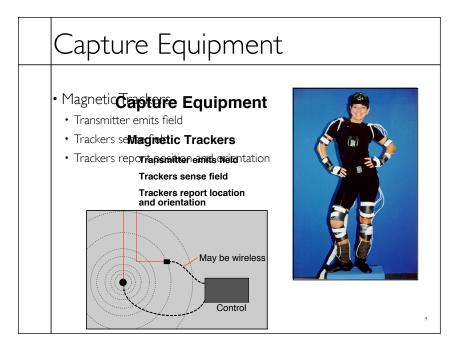
Images from Motion Analysis

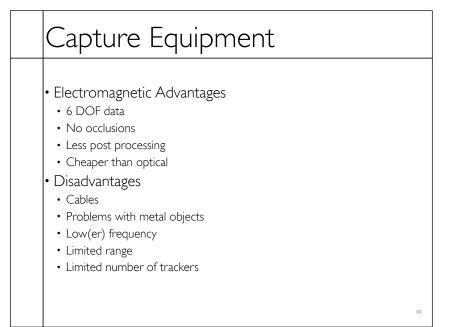












Capture Equipment

• Electromechanical





Analogus

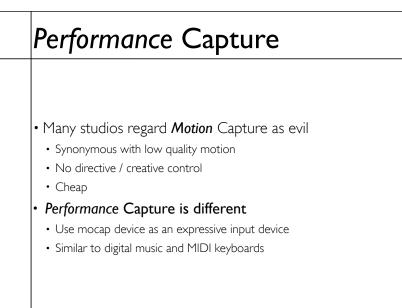
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 • Puppets

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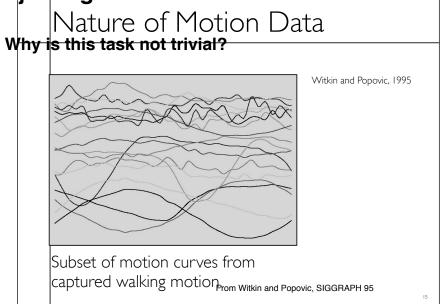
Digital Image Design

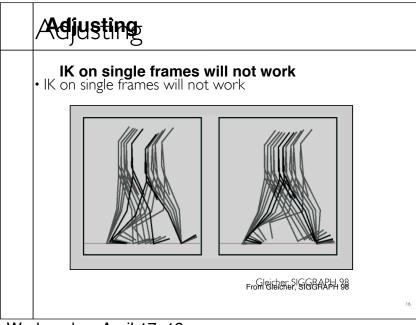


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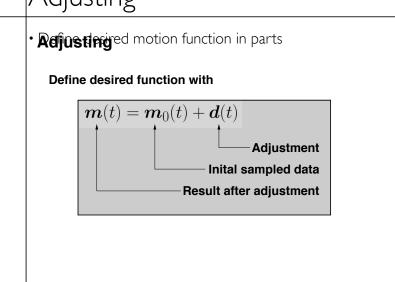
Manipulating Motion Data	
 Basic tasks Adjusting Blending Transitioning Retargeting Building graphs 	
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Adjusting

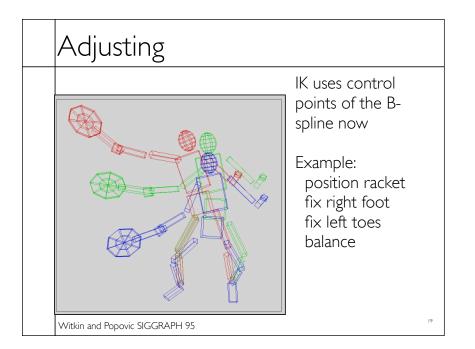


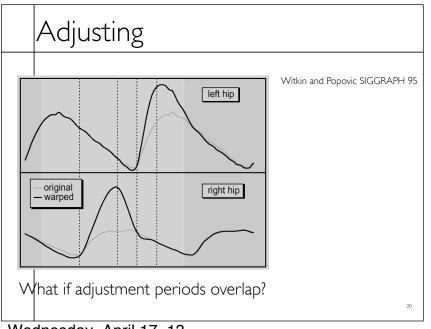






Adjusting
• Select adjustment function from "some nice space"
Example C2 B-splines
 Spread modification over reasonable period of time User selects support radius





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Blending

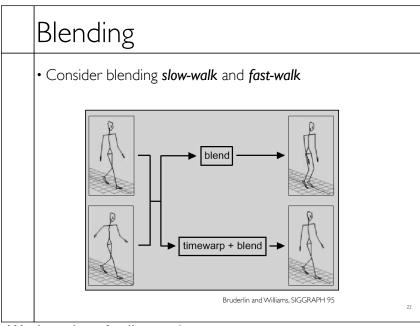
• Given two motions make a motion that combines qualities of bothto find a motion 1/2 between them?

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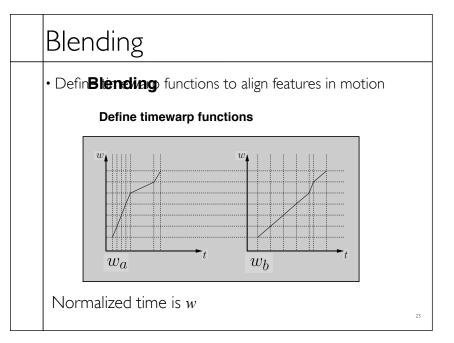
 $\boldsymbol{m}_{\alpha}(t) = \alpha \boldsymbol{m}_{a}(t) + (1 - \alpha) \boldsymbol{m}_{b}(t)$

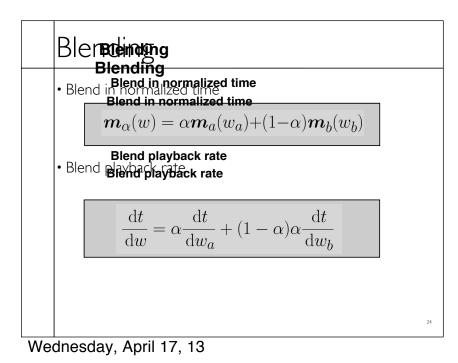
• Assumassume same DOFs

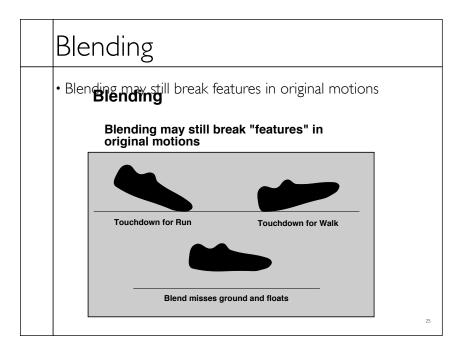
Assume same parameter in spinse

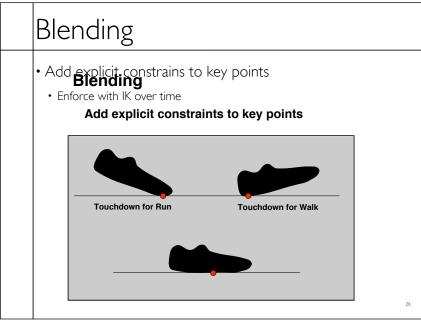


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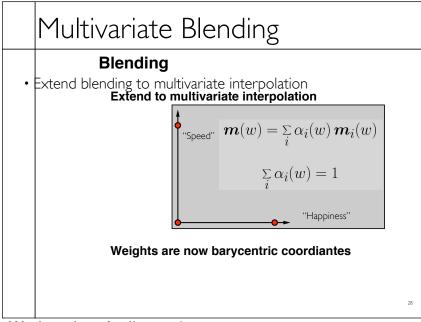
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Blending / Adjustment

• Short edits will tend to look acceptable

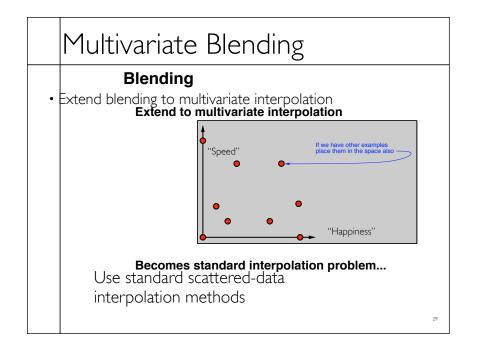
- Longer ones will often exhibit problems
- Optimize to improve blends / adjustments
- Add quality metric on adjustment
- Minimize accelerations / torques
- Explicit smoothness constraints

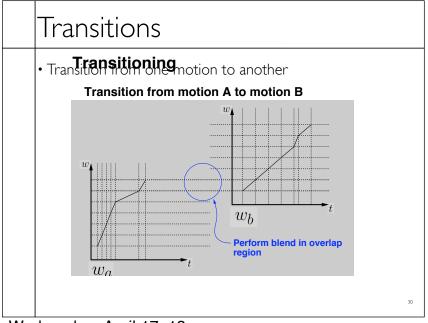
• Other criteria...



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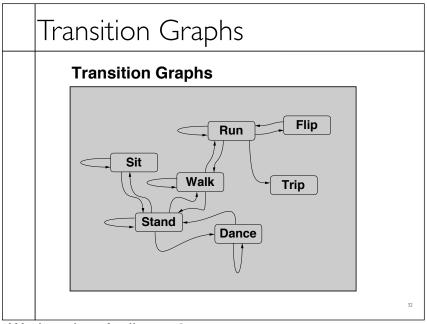


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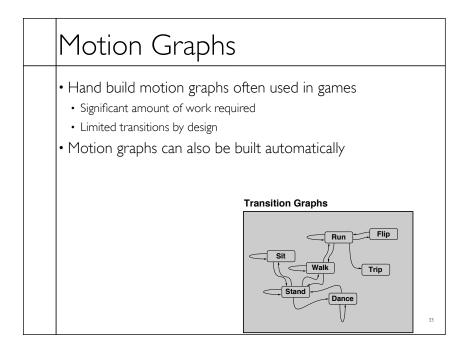
Cyclification

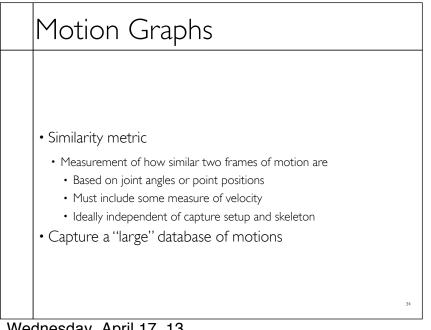
- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

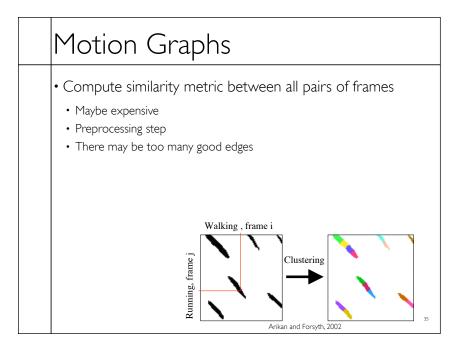
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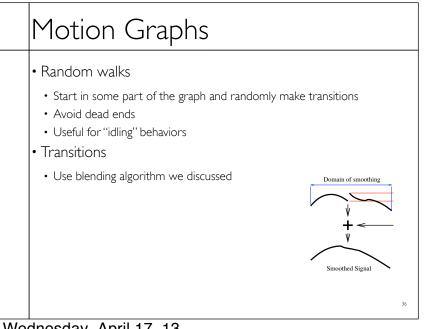


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Motion graphs

- Match imposed requirements
 - Start at a particular location
 - End at a particular location
- Pass through particular pose
- Can be solved using *dynamic programing*
- Efficiency issues may require approximate solution

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• Notion of "goodness" of a solution

Suggested Reading Fourier principles for emotion-based human figure animation, Unuma, Anjyo, and Takeuchi, SIGGRAPH 95 Motion signal processing, Bruderlin and Williams, SIGGRAPH 95 Motion warping, Witkin and Popovic, SIGGRAPH 95 Efficient generation of motion transitions using spacetime constrains, Rose et al., SIGGRAPH 96 Retargeting motion to new characters, Gleicher, SIGGRAPH 98 Verbs and adverbs: Multidimensional motion interpolation, Rose, Cohen, and Bodenheimer, IEEE: Computer Graphics and Applications, v. 18, no. 5, 1998

Suggested Reading

- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Footskate Cleanup for Motion Capture Editing, Kovar, Schreiner, and Gleicher, SCA 2002.
- Interactive Motion Generation from Examples, Arikan and Forsyth, SIGGRAPH 2002.
- Motion Synthesis from Annotations, Arikan, Forsyth, and O'Brien, SIGGRAPH 2003.
- Pushing People Around, Arikan, Forsyth, and O'Brien, unpublished.
- Automatic Joint Parameter Estimation from Magnetic Motion Capture Data, O'Brien, Bodenheimer, Brostow, and Hodgins, GI 2000.
- Skeletal Parameter Estimation from Optical Motion Capture Data, Kirk, O'Brien, and Forsyth, CVPR 2005.
- Perception of Human Motion with Different Geometric Models, Hodgins, O'Brien, and Tumblin, IEEE:TVCG 1998.

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