

CS-184: Computer Graphics

Lecture #17: Motion Capture

Prof. James O'Brien
University of California, Berkeley

V20.3-F-07.1.0

1

Today	
	<ul style="list-style-type: none">• Motion Capture

2

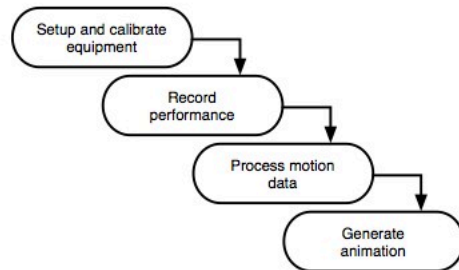
2

Sunday, November 3, 13

Motion Capture

- Record motion from physical objects
- Use motion to animate virtual objects

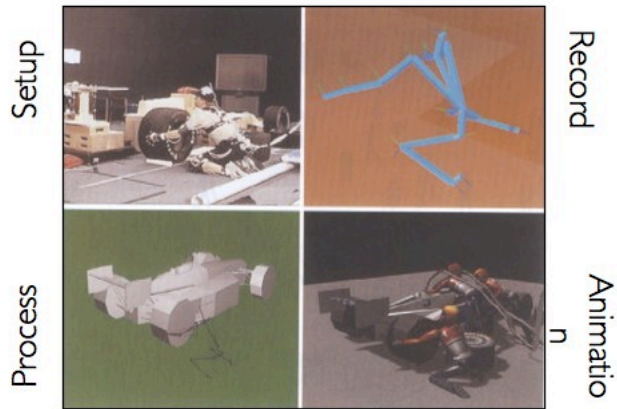
Simplified Pipeline:



3

3

Basic Pipeline



From Rose, *et al.*, 1998

4

4

What types of objects?

- Human, whole body
- Portions of body
- Facial animation
- Animals
- Puppets
- Other objects

5

5

Capture Equipment

- Passive Optical
 - Reflective markers
 - IR (typically) illumination
 - Special cameras
 - Fast, high res., filters
 - Triangulate for positions



Images from Motion Analysis



6

6

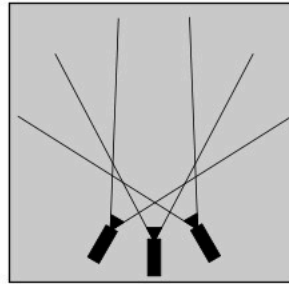
Capture Equipment

- Passive Optical Advantages

- Accurate
- May use many markers
- No cables
- High frequency

- Disadvantages

- Requires lots of processing
- Expensive systems
- Occlusions
- Marker swap
- Lighting / camera limitations



7

7

Capture Equipment

- Active Optical

- Similar to passive but uses LEDs
- Blink IDs, no marker swap
- Number of markers trades off w/ frame rate



Phoenix Technology



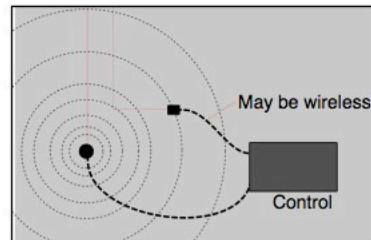
Phase Space

8

8

Capture Equipment

- Magnetic Trackers
 - Transmitter emits field
 - Trackers sense field
 - Trackers report position and orientation



9

9

Capture Equipment

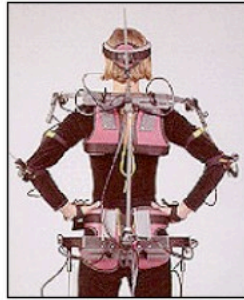
- Electromagnetic Advantages
 - 6 DOF data
 - No occlusions
 - Less post processing
 - Cheaper than optical
- Disadvantages
 - Cables
 - Problems with metal objects
 - Low(er) frequency
 - Limited range
 - Limited number of trackers

10

10

Capture Equipment

- Electromechanical



Analogus

11

11

Capture Equipment

- Puppets



Digital Image Design

12

12

Performance Capture

- Many studios regard **Motion** Capture as evil
 - Synonymous with low quality motion
 - No directive / creative control
 - Cheap
- **Performance Capture is different**
 - Use mocap device as an expressive input device
 - Similar to digital music and MIDI keyboards

13

13

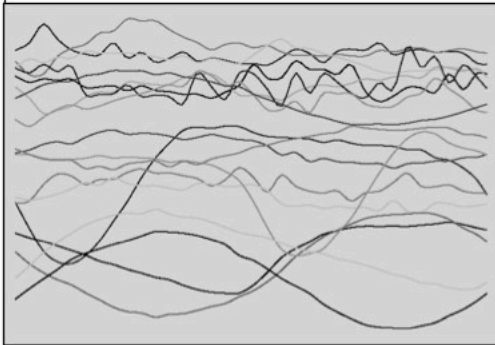
Manipulating Motion Data

- Basic tasks
 - Adjusting
 - Blending
 - Transitioning
 - Retargeting
- Building graphs

14

14

Nature of Motion Data



Witkin and Popovic, 1995

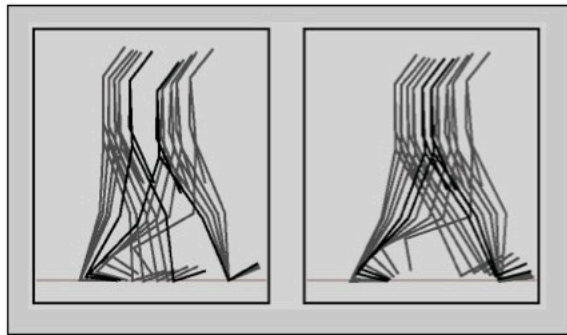
Subset of motion curves from captured walking motion.

15

15

Adjusting

- IK on single frames will not work



Gleicher, SIGGRAPH 98

16

16

Adjusting

- Define desired motion function in parts

The diagram shows the equation $m(t) = m_0(t) + d(t)$ inside a grey box. Three arrows point from labels to terms in the equation: 'Adjustment' points to $d(t)$, 'Initial sampled data' points to $m_0(t)$, and 'Result after adjustment' points to $m(t)$.

17

17

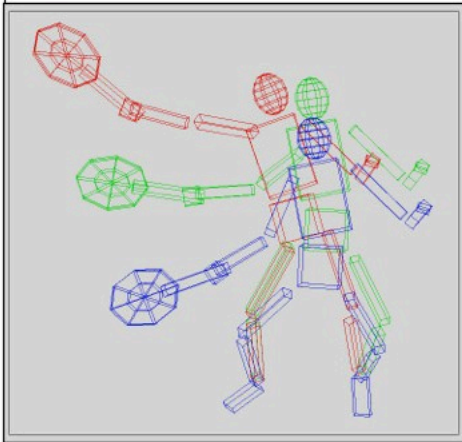
Adjusting

- Select adjustment function from “some nice space”
 - Example C2 B-splines
- Spread modification over reasonable period of time
 - User selects support radius

18

18

Adjusting



IK uses control points of the B-spline now

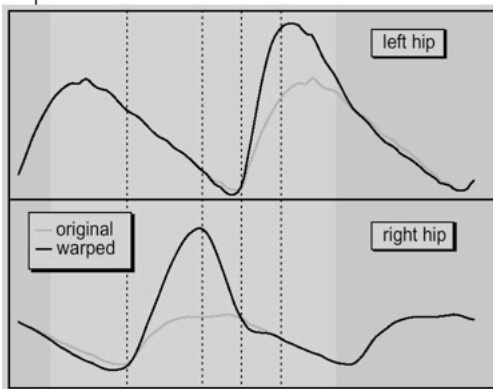
Example:
position racket
fix right foot
fix left toes
balance

Witkin and Popovic SIGGRAPH 95

19

19

Adjusting



Witkin and Popovic SIGGRAPH 95

What if adjustment periods overlap?

20

20

Blending

- Given two motions make a motion that combines qualities of both

$$\mathbf{m}_\alpha(t) = \alpha \mathbf{m}_a(t) + (1 - \alpha) \mathbf{m}_b(t)$$

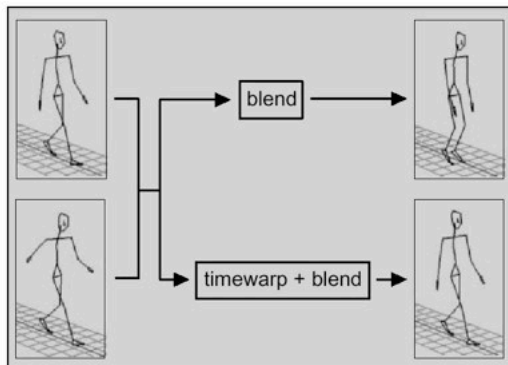
- Assume same DOFs
- Assume same parameter mappings

21

21

Blending

- Consider blending *slow-walk* and *fast-walk*



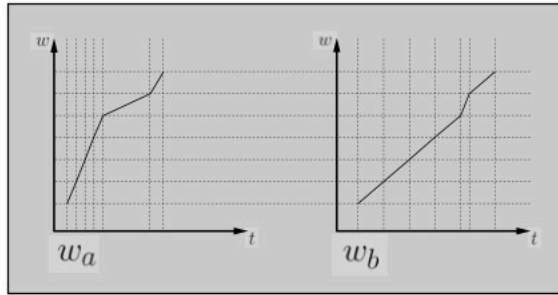
Bruderlin and Williams, SIGGRAPH 95

22

22

Blending

- Define timewarp functions to align features in motion



Normalized time is w

23

23

Blending

- Blend in normalized time

$$\mathbf{m}_\alpha(w) = \alpha \mathbf{m}_a(w_a) + (1 - \alpha) \mathbf{m}_b(w_b)$$

- Blend playback rate

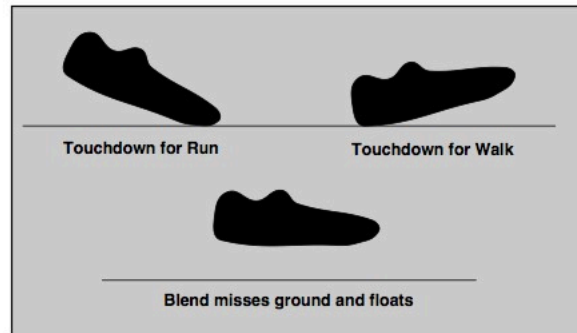
$$\frac{dt}{dw} = \alpha \frac{dt}{dw_a} + (1 - \alpha) \alpha \frac{dt}{dw_b}$$

24

24

Blending

- Blending may still break features in original motions

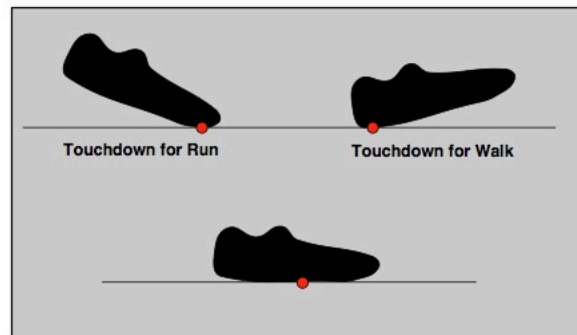


25

25

Blending

- Add explicit constraints to key points
 - Enforce with IK over time



26

26

Blending / Adjustment

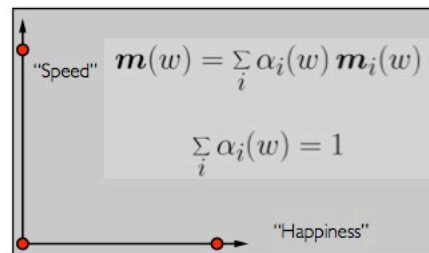
- Short edits will tend to look acceptable
- Longer ones will often exhibit problems
- Optimize to improve blends / adjustments
 - Add quality metric on adjustment
 - Minimize accelerations / torques
 - Explicit smoothness constraints
 - Other criteria...

27

27

Multivariate Blending

- Extend blending to multivariate interpolation

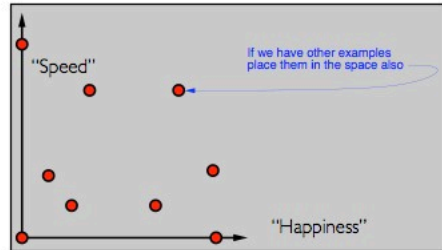


28

28

Multivariate Blending

- Extend blending to multivariate interpolation



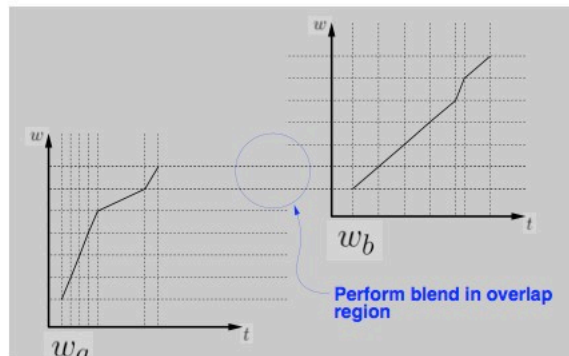
Use standard scattered-data interpolation methods

29

29

Transitions

- Transition from one motion to another



30

30

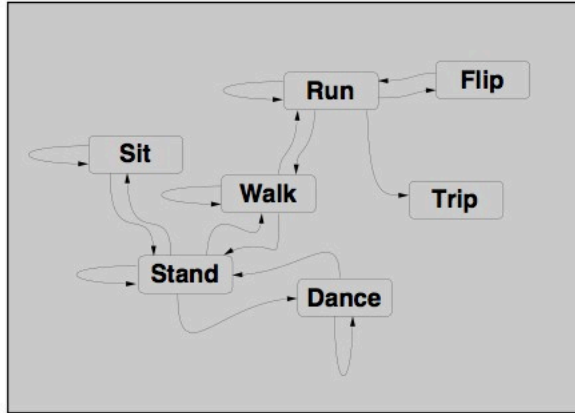
Cyclification

- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

31

31

Transition Graphs

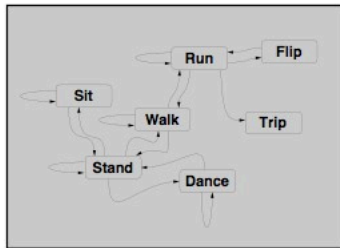


32

32

Motion Graphs

- Hand build motion graphs often used in games
 - Significant amount of work required
 - Limited transitions by design
- Motion graphs can also be built automatically



33

33

Motion Graphs

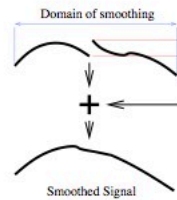
- Similarity metric
 - Measurement of how similar two frames of motion are
 - Based on joint angles or point positions
 - Must include some measure of velocity
 - Ideally independent of capture setup and skeleton
- Capture a "large" database of motions

34

34

Motion Graphs

- Random walks
 - Start in some part of the graph and randomly make transitions
 - Avoid dead ends
 - Useful for “idling” behaviors
- Transitions
 - Use blending algorithm



35

35

Motion graphs

- Match imposed requirements
 - Start at a particular location
 - End at a particular location
 - Pass through particular pose
 - Can be solved using *dynamic programming*
 - Efficiency issues may require approximate solution
 - Notion of “goodness” of a solution

36

36

Typical Motion Graph

Walking #1

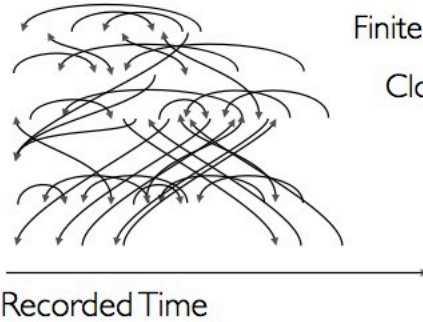
Running

Idle

Fall down

Walking #2

Punches



Finite number of states

Cloth is hysteretic

37

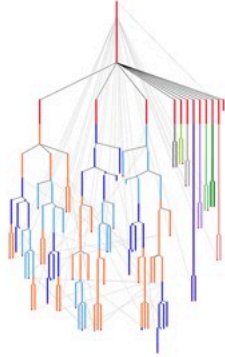
Naïve Precomputation

Initially computed cloth motion
Jumpy transitions



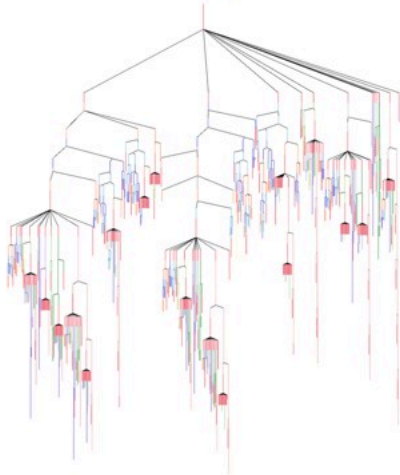
38

Graph Unrolling



39

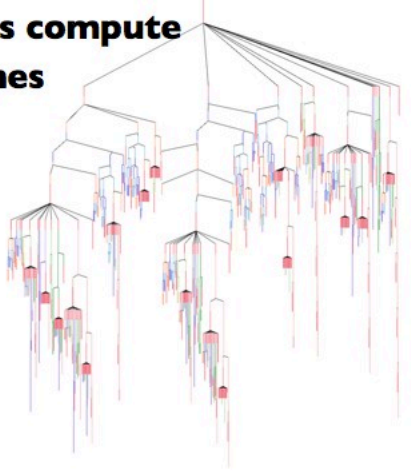
Graph Unrolling



40

Graph Unrolling

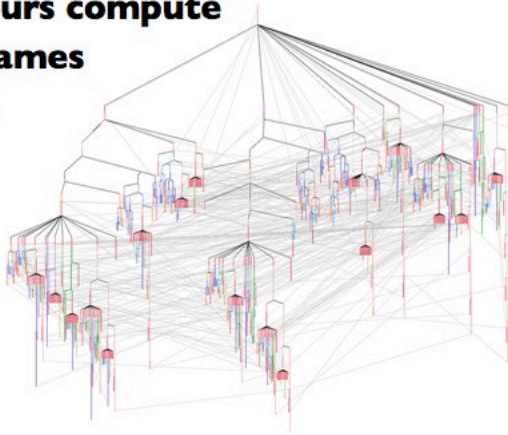
5000 hours compute
100K frames
330 GB



41

Graph Unrolling

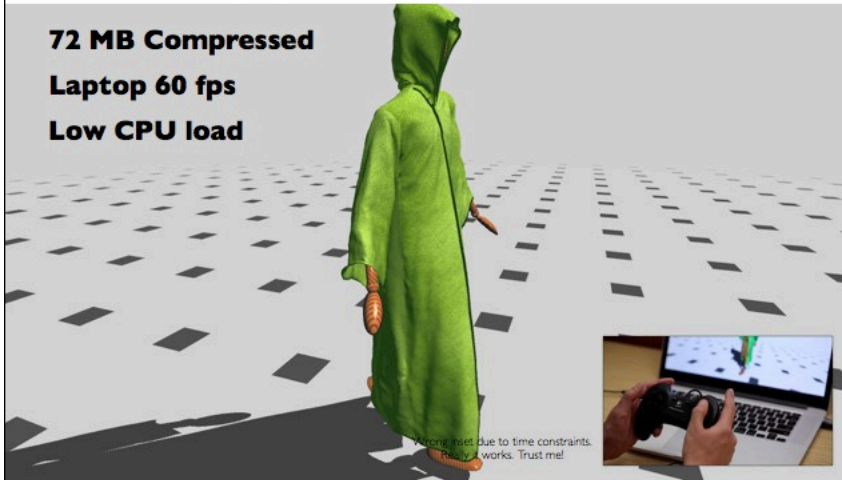
5000 hours compute
100K frames
330 GB



42

Precomputed Cloth

72 MB Compressed
Laptop 60 fps
Low CPU load



43

Precomputed Cloth



44

Precomputed Simulation

- No significant CPU load at runtime
- Decouples quality from runtime cost
- No new data at runtime
 - Simulation can't crash application
 - All motion can be inspected/edited
 - Allows QA and art direction of simulations
- Extend to other types of simulation?
- Dynamic variations?

45

Suggested Reading

- Fourier principles for emotion-based human figure animation, Unuma, Anjyo, and Takeuchi, SIGGRAPH 95
- Motion signal processing, Bruderlin and Williams, SIGGRAPH 95
- Motion warping, Witkin and Popovic, SIGGRAPH 95
- Efficient generation of motion transitions using spacetime constraints, Rose et al., SIGGRAPH 96
- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Verbs and adverbs: Multidimensional motion interpolation, Rose, Cohen, and Bodenheimer; IEEE: Computer Graphics and Applications, v. 18, no. 5, 1998
- Doyub Kim, Woojong Koh, Rahul Narain, Kayvon Fatahalian, Adrien Treuille, and James F. O'Brien. "Near-exhaustive Precomputation of Secondary Cloth Effects", SIGGRAPH 2013.

46

46

Suggested Reading

- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Footskate Cleanup for Motion Capture Editing, Kovar, Schreiner, and Gleicher, SCA 2002.
- Interactive Motion Generation from Examples, Arikan and Forsyth, SIGGRAPH 2002.
- Motion Synthesis from Annotations, Arikan, Forsyth, and O'Brien, SIGGRAPH 2003.
- Okan Arikan, David A. Forsyth, and James F. O'Brien. "Pushing People Around". Symposium on Computer Animation 2005, pages 56–66, July 2005.
- Automatic Joint Parameter Estimation from Magnetic Motion Capture Data, O'Brien, Bodenheimer, Brostow, and Hodgins, GI 2000.
- Skeletal Parameter Estimation from Optical Motion Capture Data, Kirk, O'Brien, and Forsyth, CVPR 2005.
- Perception of Human Motion with Different Geometric Models, Hodgins, O'Brien, and Tumblin, IEEE TVCG 1998.

47

47