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Exercises

1. Magnitude least-squares. The magnitude least-squares problem has the form

$$\min_{w} \, \||X^T w| - y\|_2,$$

where $X \in \mathbf{R}^{n \times m}$, $y \in \mathbf{R}^m_+$ are given, and |z| stands for the vector formed with the magnitude of the elements of vector z. This problem arises in many applications, for example in when recovering a signal or image from the intensity measurements of its Fourier transform, as in X-ray crystallography. (Here, we only work with real numbers, although the problem is often posed in a complex-valued setting, for which the problem is referred to as the phase retrieval problem.) Derive an SDP approximation to the problem. Find its dual. *Hint:* Express the problem as a quadratic one:

$$\min_{w,v} \|v - y\|_2^2 : v_i^2 = (X^T w)_i^2, \ i = 1, \dots, m,$$

and use rank relaxation.

2. Sparse Gaussian models. We are given data points $x_1, \ldots, x_n \in \mathbf{R}^p$, which we assume are generated by a multivariate Gaussian. The empirical covariance matrix C is given by

$$C = \frac{1}{n} \sum_{i=1}^{n} (x_i - \hat{x}) (x_i - \hat{x})^T, \quad \hat{x} := \frac{1}{n} \sum_{i=1}^{n} x_i.$$

This formula can be obtained by assuming that the data points are generated by a Gaussian (\hat{x}, C) , and solving the maximum-likelihood problem, which turns out to have the form

$$\max_{X \succ 0} \log \det X - \operatorname{Tr} CX,$$

At optimum, we have $X = C^{-1}$ if C is invertible; otherwise, the maximum-likelihood problem is not well-posed. The matrix $X = C^{-1}$ is called the precision matrix. It can be shown that $X_{ij} = 0$ implies that variables i, j are conditionally independent.

In many applications, we'd like to fit a *sparse* Gaussian model to data, in the sense that many pairs (i, j) are conditionally independent. This leads to a modified version of the above problem:

$$\max_{X} \log \det X - \operatorname{Tr} XC - \rho \|X\|_{1}$$

where $\rho > 0$ is a parameter, and $||X||_1$ contains the sum of the absolute values of all the elements of X.

- (a) Form a dual to the problem.
- (b) Show that for every $\rho > 0$, the optimal solution to the penalized problem is unique, and bounded as follows: $\alpha I \preceq X \preceq \beta I$, where

$$\alpha := \frac{1}{\lambda_{\max}(C) + \rho p}, \quad \beta := \frac{p}{\rho},$$

where $\lambda_{\max}(C)$ is the largest eigenvalue of C.

Solution:

(a) We can write the problem as

$$\max_{X \succ 0} \min_{\|U\|_{\infty} \le \rho} \log \det X + \operatorname{Tr} X(C+U),$$

where $||U||_{\infty}$ denotes the maximal absolute value of the entries of U. This corresponds to seeking an estimate with maximal worst-case likelihood, over all component-wise bounded additive perturbations C+U of the empirical covariance matrix C.

We can obtain the dual by exchanging the max and the min:

$$\min_{U} \{ -\log \det(C+U) - p : ||U||_{\infty} \le \rho, \ C+U \succ 0 \}$$
(15.1)

The diagonal elements of an optimal U are simply $\hat{U}_{ii} = \rho$. The corresponding covariance matrix estimate is $\hat{C} := C + \hat{U}$. Since the above dual problem has a compact feasible set, the primal and dual problems are equivalent, that is, strong duality holds. The optimality conditions relate the primal and dual solutions by $\hat{C}X = I$.

(b) An optimal X satisfies $X = (C + U)^{-1}$, where $||U||_{\infty} \leq \rho$. To establish a lower bound on the eigenvalues of X, we need an upper bound on those of C + U. We have, from convexity and positive homogeneity of the largest eigenvalue function:

$$\lambda_{\max}(C+U) \le \lambda_{\max}(C) + \lambda_{\max}(U).$$

Since $||U||_{\infty} \leq \rho$, we have

$$\lambda_{\max}(U) \le ||U|| = \max_{\xi : ||\xi||_2 \le 1} ||U\xi||_2 \le p\rho,$$

In the above, we have used that, for every $i \in \{1, \ldots, p\}$, the *i*-th component of $U\xi$ is of the form $u^T\xi$ where $||u||_{\infty} \leq \rho$, hence its absolute value is bounded above by ρ . We obtain $X \succeq \alpha I$, where $\alpha = 1/(\lambda_{\max}(C) + \rho p)$.

Likewise, we can show that X is bounded above. Indeed, at optimum, the primaldual gap is zero:

$$0 = -\log \det(C+U) - p - \log \det X + \langle C, X \rangle + \rho \|X\|_1$$

= $-p + \langle C, X \rangle + \rho \|X\|_1,$

where we have used (C + U)X = I. Since C, X are both positive semi-definite, we obtain

$$||X|| \le ||X||_F \le ||X||_1 \le \frac{p}{\rho}I,$$

as claimed.

3. The unconstrained optimization problem

$$q^{\star}(\rho) := \sum_{k=1}^{m} \sqrt{\rho^2 + (a_k^T x - b_k)^2},$$
(15.2)

where ρ is a small positive constant, is sometimes used as a smooth approximation of the ℓ_1 -minimization problem

$$p^* := \text{ minimize } ||Ax - b||_1.$$

 $(A \in \mathbf{R}^{m \times n} \text{ is the matrix with rows } a_k^T)$ In this problem, we investigate the following issue: how small should ρ be, in order to guarantee that $|\phi(\rho) - p^*| \leq \epsilon$?

Solution:

(a) Problem (15.2) is equivalent to

minimize
$$\sum_{k=1}^{m} \sqrt{\rho^2 + y_k^2}$$

subject to $y = Ax - b$,

with variables $x \in \mathbf{R}^n$, $y \in \mathbf{R}^m$. Derive the Lagrange dual.

(b) Let \hat{x} be the optimal solution of (15.2) and define $\hat{y} = A\hat{x} - b$ for k = 1, ..., m. Let p^* be the optimal value of the ℓ_1 -minimization problem. Show that

$$\|\hat{y}\|_1 \ge p^* \ge \sum_{k=1}^m \frac{\hat{y}_k^2}{\sqrt{\rho^2 + \hat{y}_k^2}},$$

and that this implies

$$q^{\star}(\rho) \ge p^{\star} \ge q^{\star}(\rho) - m\rho$$

where $q^{\star}(\rho)$ is the optimal value of (15.2).

Solution.

(a) The Lagrangian is

$$L(x, y, z) = \sum_{k=1}^{m} \sqrt{\rho^2 + y_k^2} + z^T (y - Ax + b).$$

This is bounded below as a function of x only if $A^T z = 0$. We find the minimum over y_k by setting the derivative equal to zero:

$$z_k = -\frac{y_k}{\sqrt{\rho^2 + y_k^2}}.$$

This is solvable only if $|z_k| < 1$, with solution

$$y_k = -\rho \frac{z_k}{\sqrt{1 - z_k^2}}, \qquad \inf_y \left(\sqrt{\rho^2 + y_k^2} + z_k y_k\right) = \rho \sqrt{1 - z_k^2}$$

If $z_k = 1$, the infimum of $(\rho^2 + y_k^2)^{1/2} + z_k y_k$ is reached asymptotically as $y_k \to -\infty$, and if $z_k = -1$, the infimum of is reached as $y_k \to \infty$. Therefore the dual problem is

maximize
$$b^T z + \rho \sum_{k=1}^m \sqrt{1 - z_k^2}$$

subject to $A^T z = 0$ (15.3)
 $\|z\|_{\infty} \le 1.$

(b) The first inequality is an immediate consequence of the definition of p^* . The second inequality can be derived from the optimality conditions of the smooth problem,

$$\hat{z}_k = \frac{-\hat{y}_k}{\sqrt{\rho^2 + \hat{y}_k^2}}, \qquad A^T \hat{z} = 0, \qquad \hat{y} = A\hat{x} - b,$$

and the dual of the ℓ_1 problem

maximize
$$-b^T z$$

subject to $A^T z = 0$
 $\|z\|_{\infty} \le 1.$

If we plug in \hat{z} in the dual of the $\ell_1\text{-approximation}$ problem we find the lower bound

$$p^{\star} \geq -b^{T}\hat{z} \\ = (A\hat{x} - b)^{T}\hat{z} \\ = -\hat{y}^{T}z \\ = \sum_{k=1}^{m} \hat{y}_{k}^{2} / \sqrt{\rho^{2} + \hat{y}_{k}^{2}}.$$

The inequality $q^{\star}(\rho) \ge p^{\star}$ follows from

$$\|\hat{y}\|_{1} \leq \sum_{k} \sqrt{\rho^{2} + (a_{k}^{T}\hat{x} - b_{k})^{2}} = q^{\star}(\rho).$$

The second inequality $q^{\star}(\rho) - m\rho$ follows from

$$\begin{split} \sum_{k=1}^{m} \frac{\hat{y}_{k}^{2}}{\sqrt{\rho^{2} + \hat{y}_{k}^{2}}} &= \sum_{k=1}^{m} \sqrt{\rho^{2} + \hat{y}_{k}^{2}} - \rho^{2} \sum_{k=1}^{m} \frac{1}{\sqrt{\rho^{2} + \hat{y}_{k}^{2}}} \\ &= q^{\star}(\rho) - \rho^{2} \sum_{k=1}^{m} \frac{1}{\sqrt{\rho^{2} + \hat{y}_{k}^{2}}} \\ &\geq q^{\star}(\rho) - m\rho. \end{split}$$