Light and Shading

EECS 442 – David Fouhey

Fall 2019, University of Michigan

http://web.eecs.umich.edu/~fouhey/teaching/EECS442_F19/

Administrivia –Corrections

- I do my best, but we all make mistakes. If you find a substantial one in my slides, tell me!
- I’m really happy if you find mistakes and tell me politely (but don’t go fishing)
- Shengyu found a few mistakes last time and I was *delighted* to hire him as an IA
- Periodically, I’ll bring donuts (or the equivalent – it’s a bit late for donuts) for those who have caught substantial errors and congratulate them on the course website

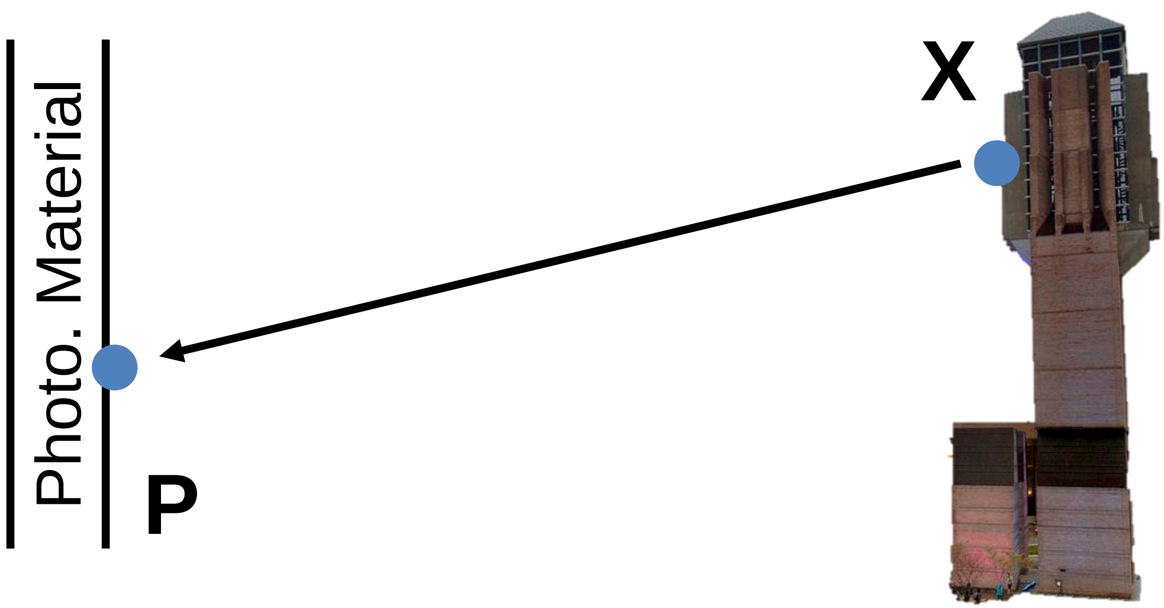
Administrivia – Mastery Assignment

- If you're rusty and want to wait – please do!
- We're covering a bunch of linear algebra and math next week
- It's not due until December 11, and HW1 won't require a ton of linear algebra

Recap: Projection

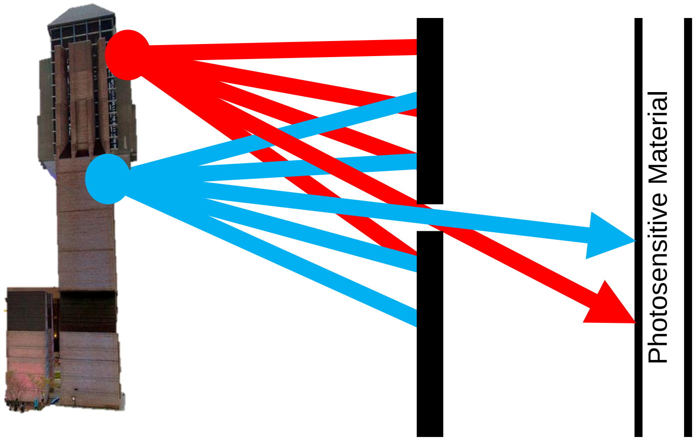
Image → $\boldsymbol{P} = \boldsymbol{K}[\boldsymbol{R}, \boldsymbol{t}]\boldsymbol{X}$ ← *World*

Intrinsic *Extrinsic*



Recap: Lenses

Pinhole Model



Mathematically correct
Not quite correct in practice
Reasonable approximation

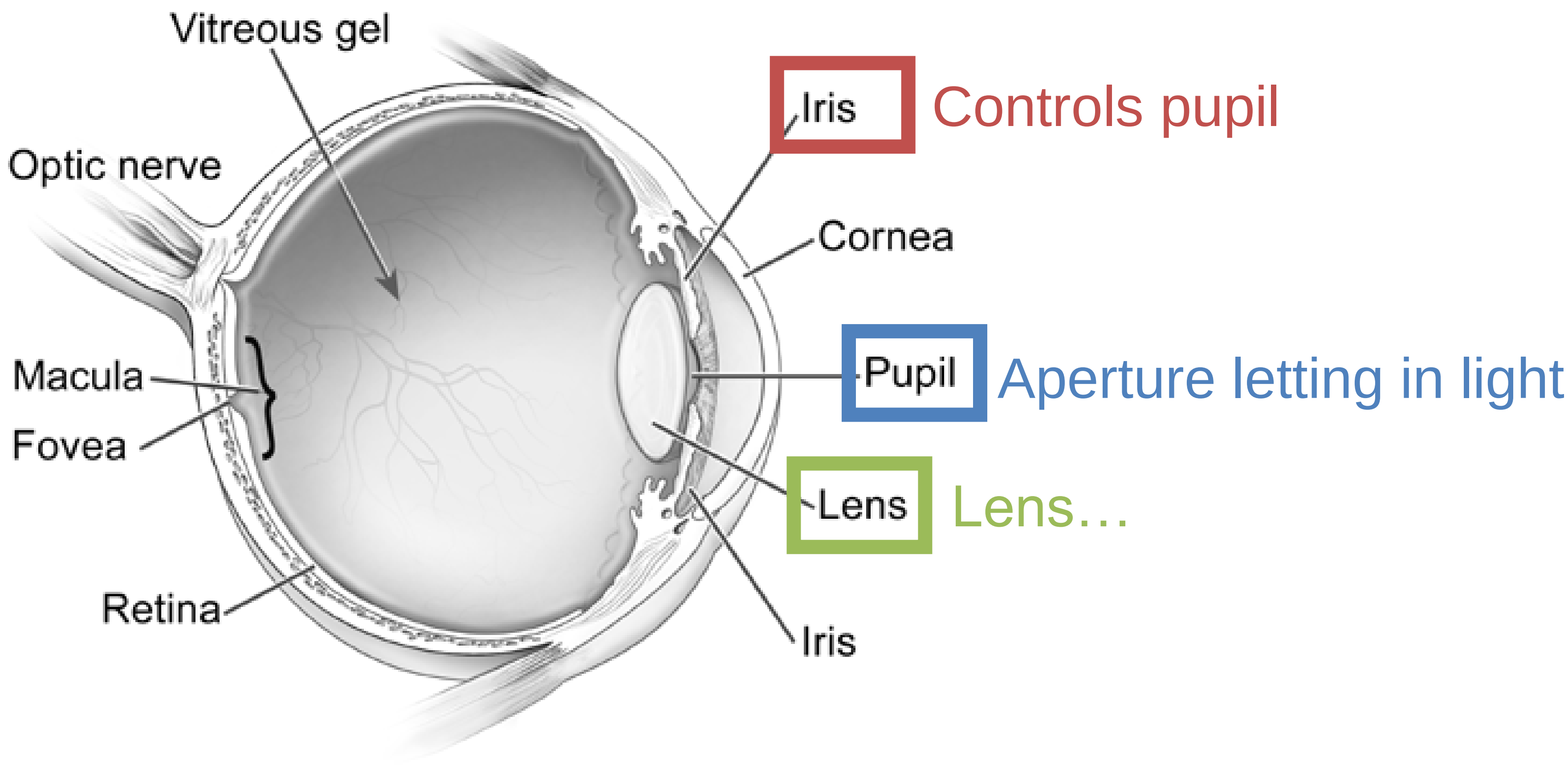
Reality: Lenses

Necessary in practice
Introduce complications
Complications fixable

Today

- A little bit about light and how you represent it
- A little bit about lighting and how it works

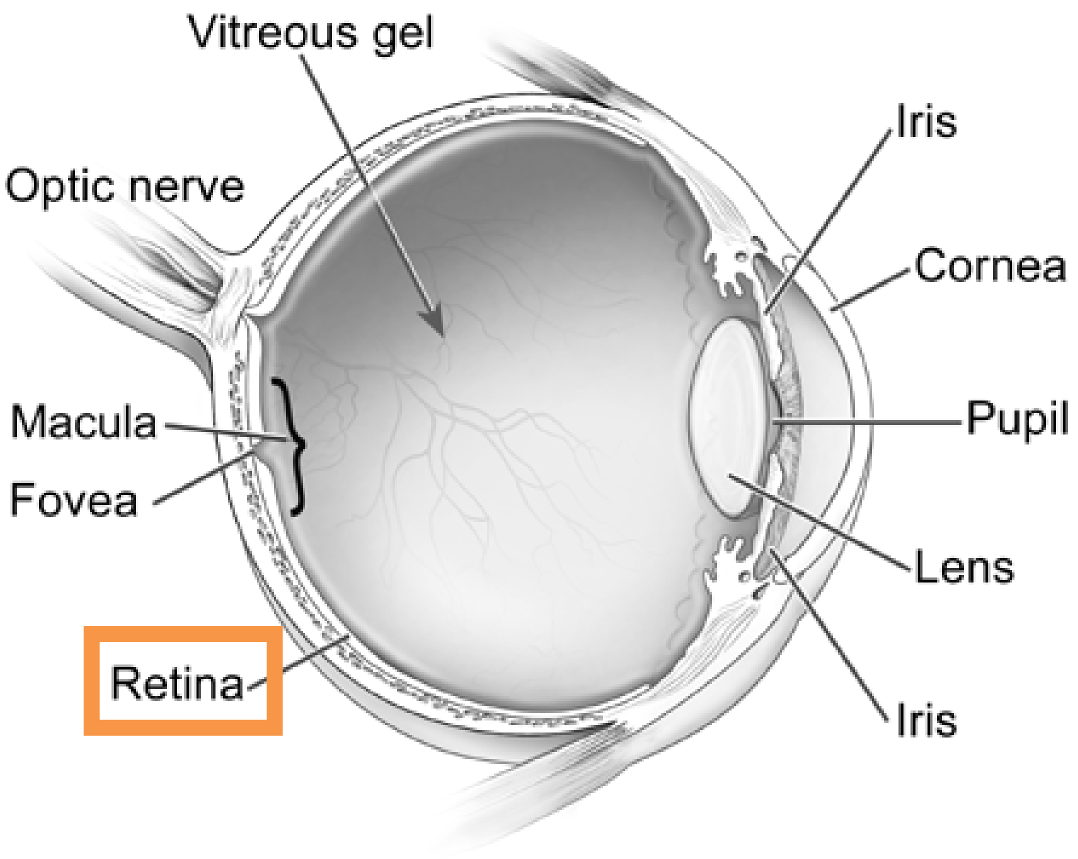
Your Very Own Camera



Where's the film/CCD?

Slide Credit: NIH

Your Very Own Camera

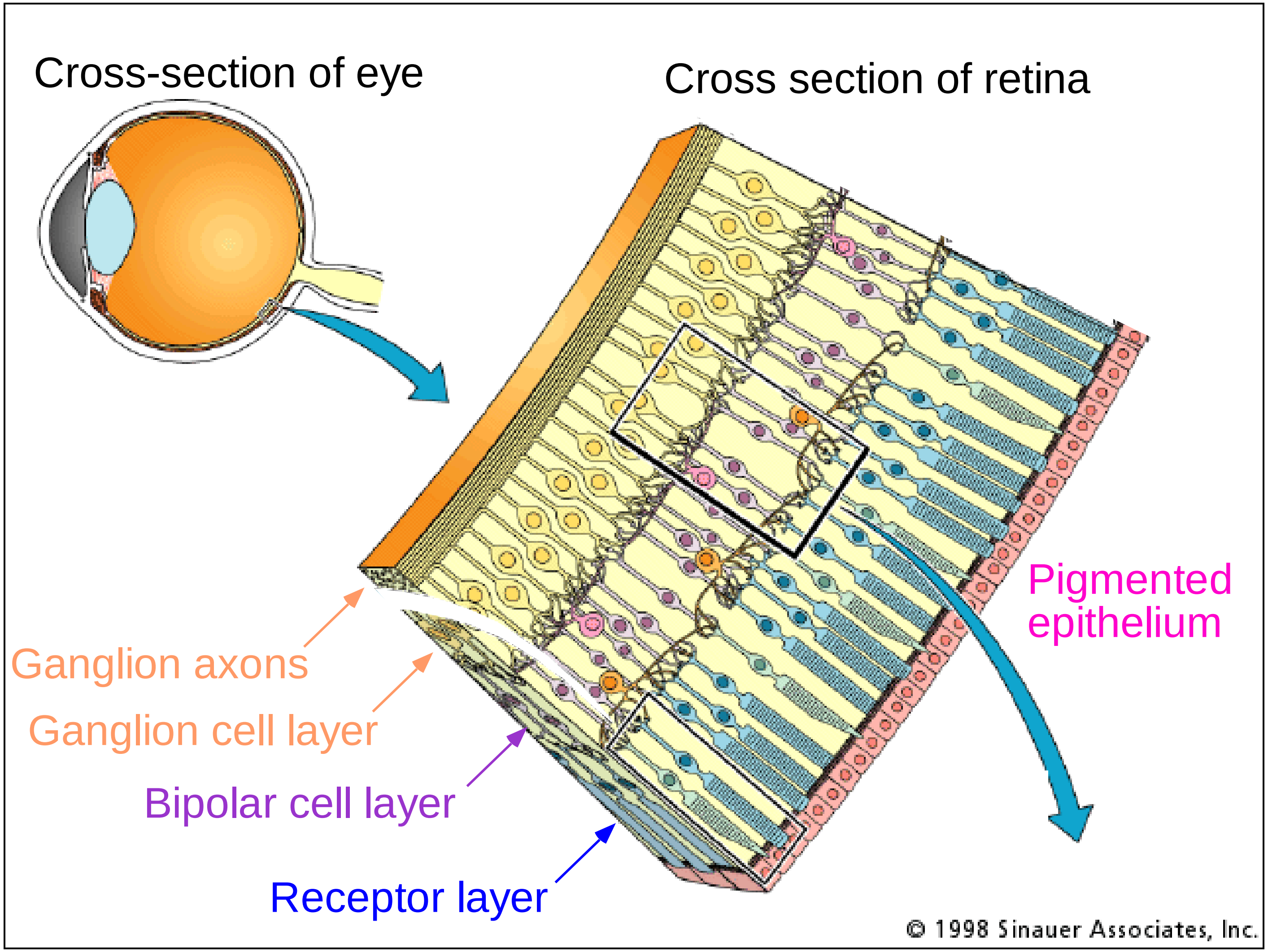


Where's the film/CCD?

Slide Credit: NIH

Demo Time

What is Retina/Film Made Of?



Slide Credit: J. Hays

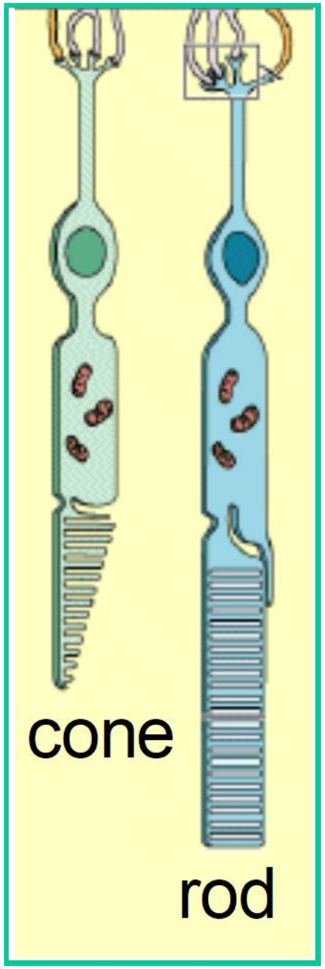
Two Type of Photo Receptors

Cones

cone-shaped
less sensitive
operate in high light
color vision

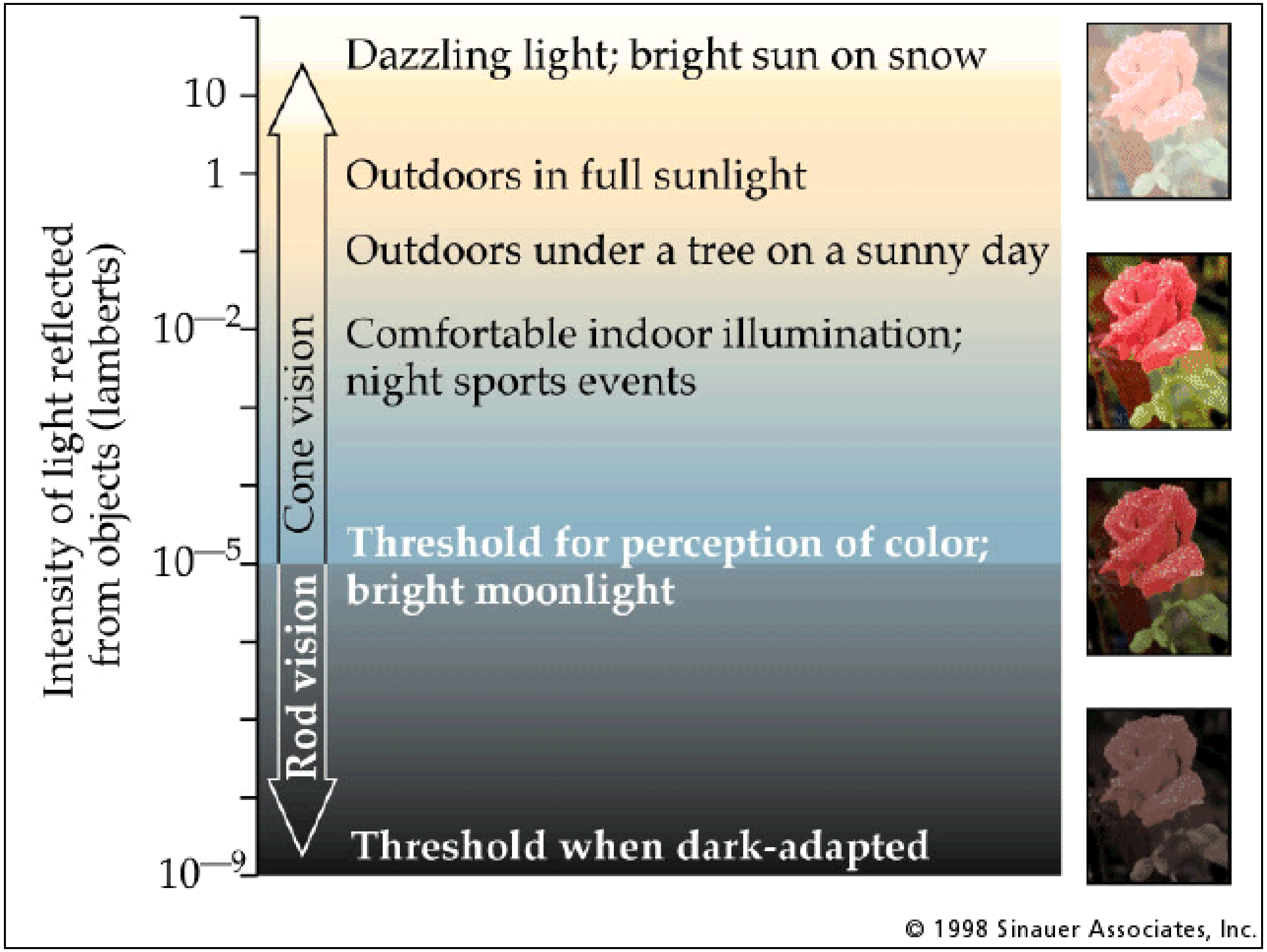
Rods

rod-shaped
highly sensitive
operate at night
gray-scale vision



Slide Credit: J. Hays

Rod / Cone Sensitivity



Slide Credit: J. Hays

Rod/Cone Distribution

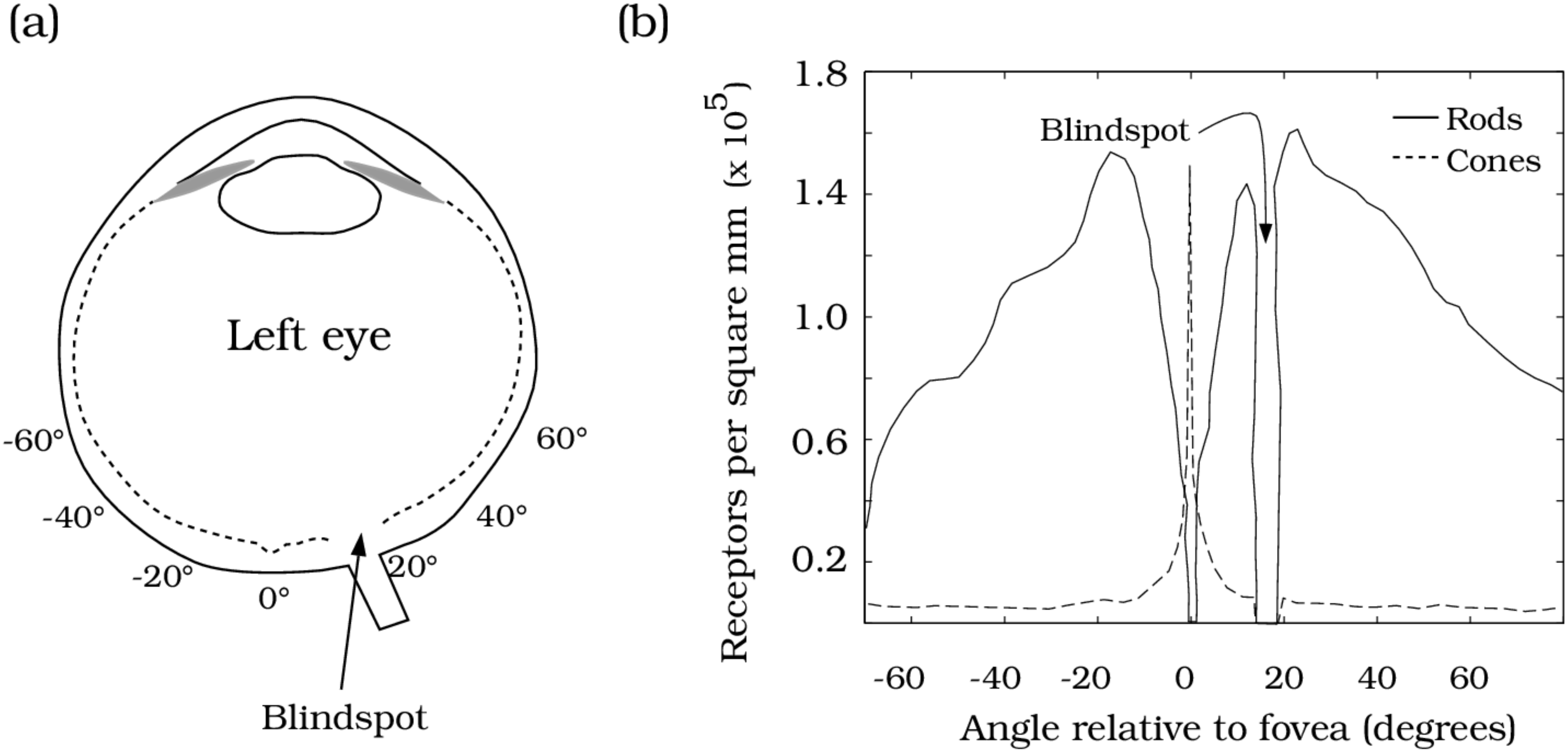
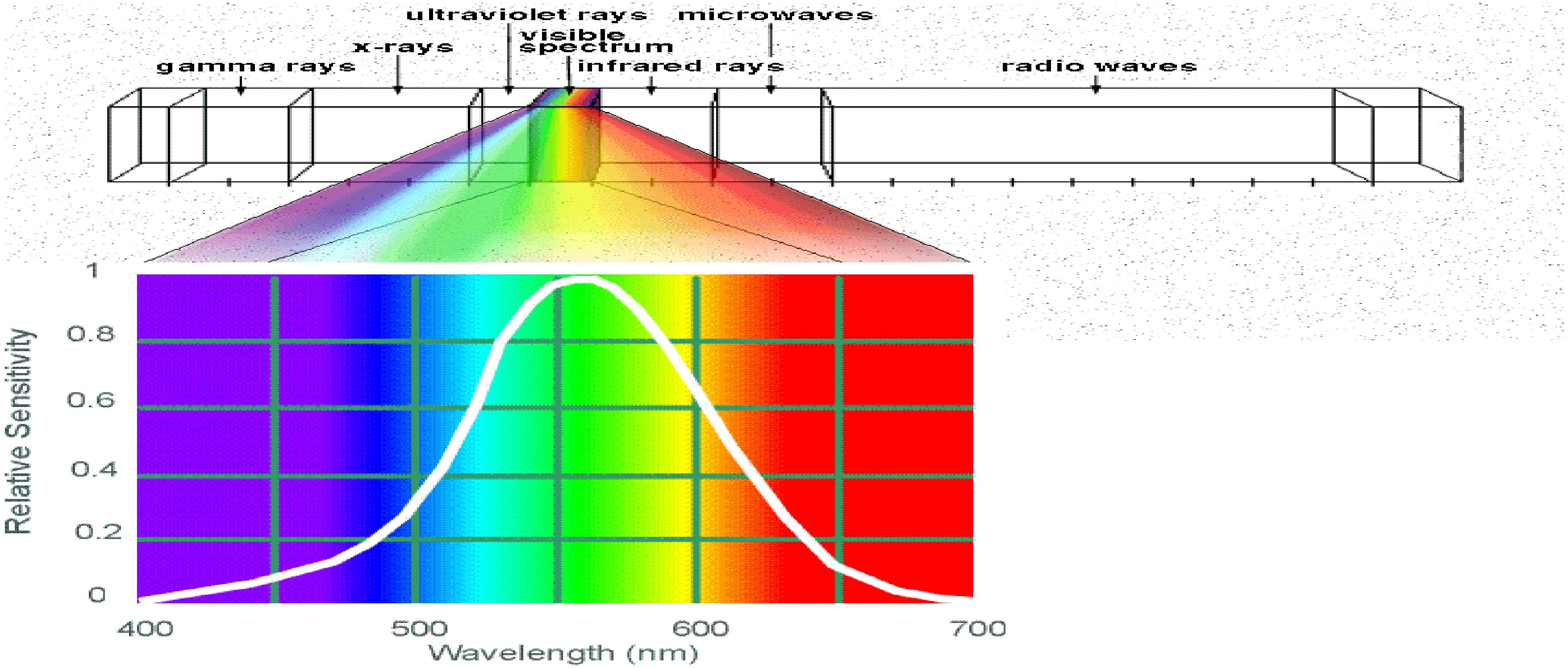


Diagram Credit: B. A. Wandell, *Foundations of Vision*

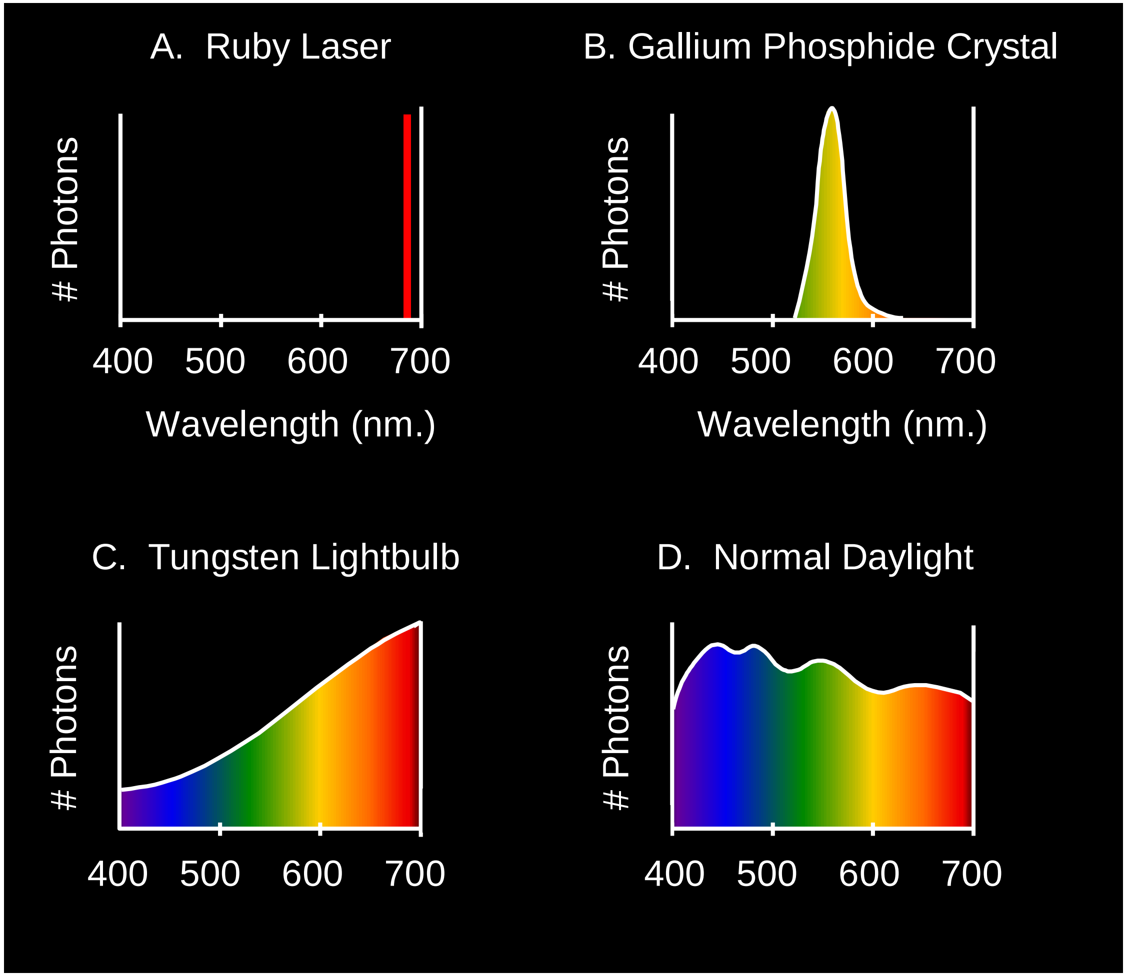
Electromagnetic Spectrum



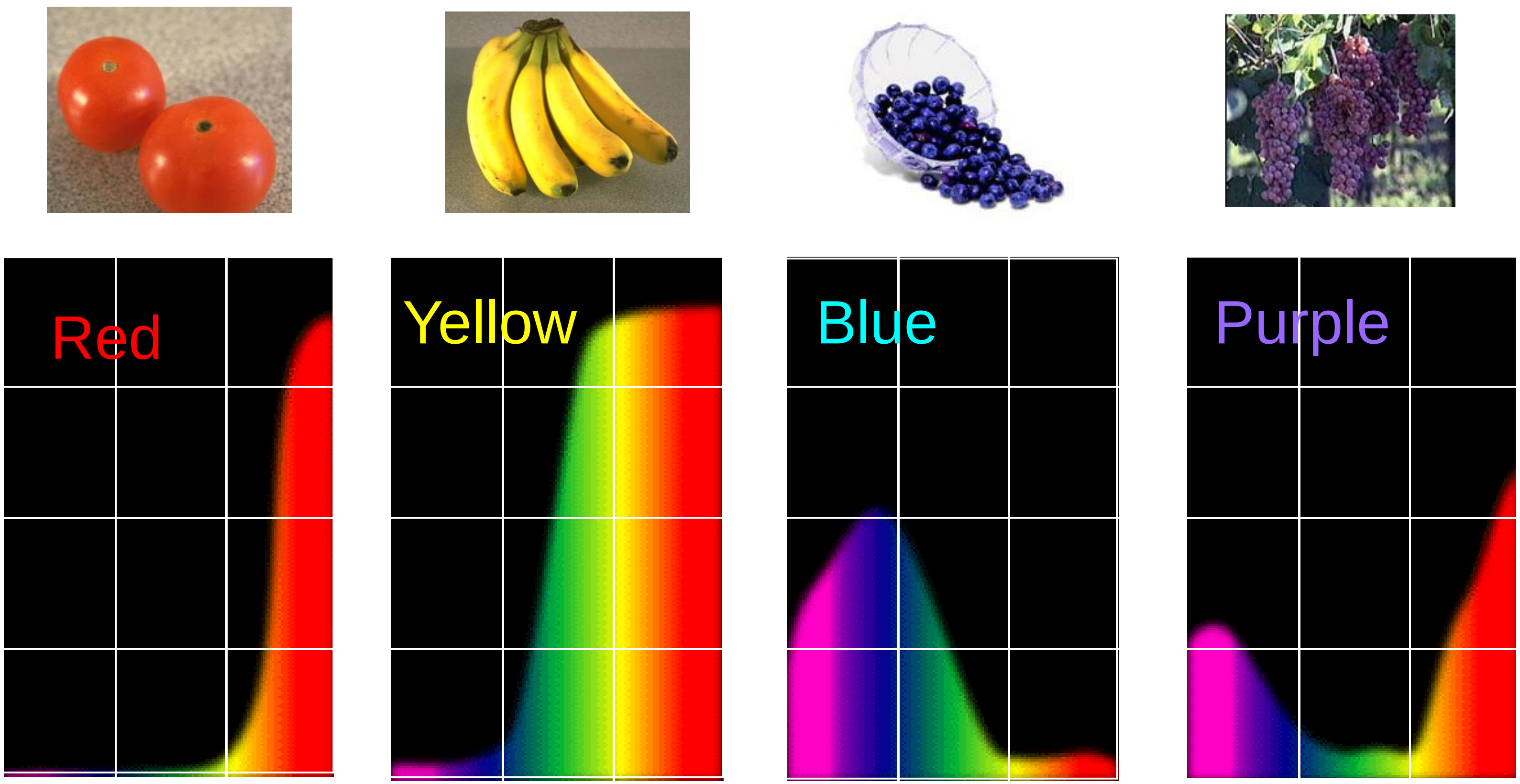
Why do we see light in these wavelengths?

Slide Credit: J. Hays

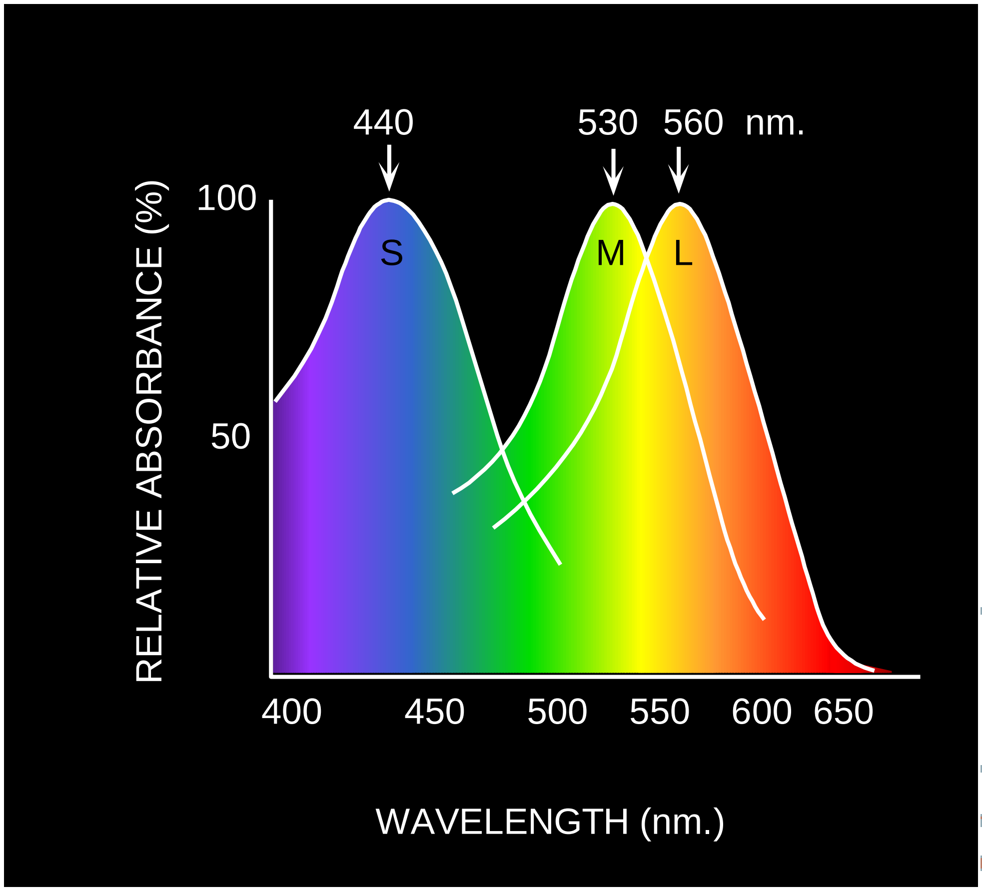
The Physics of Light

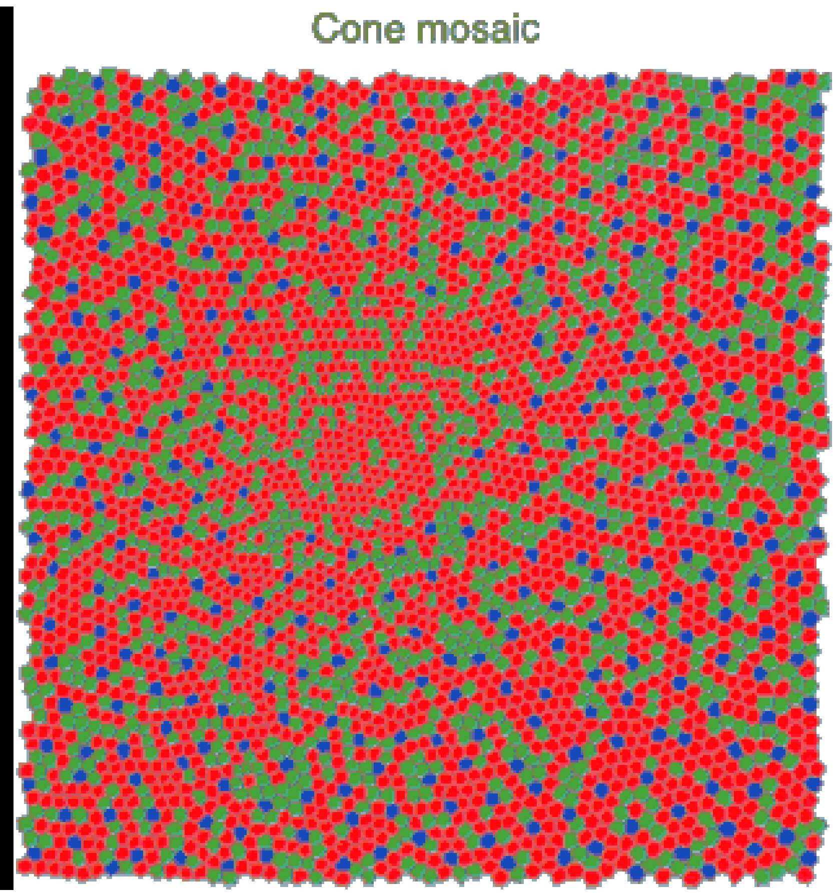


The Physics of Light



The Physics of Light

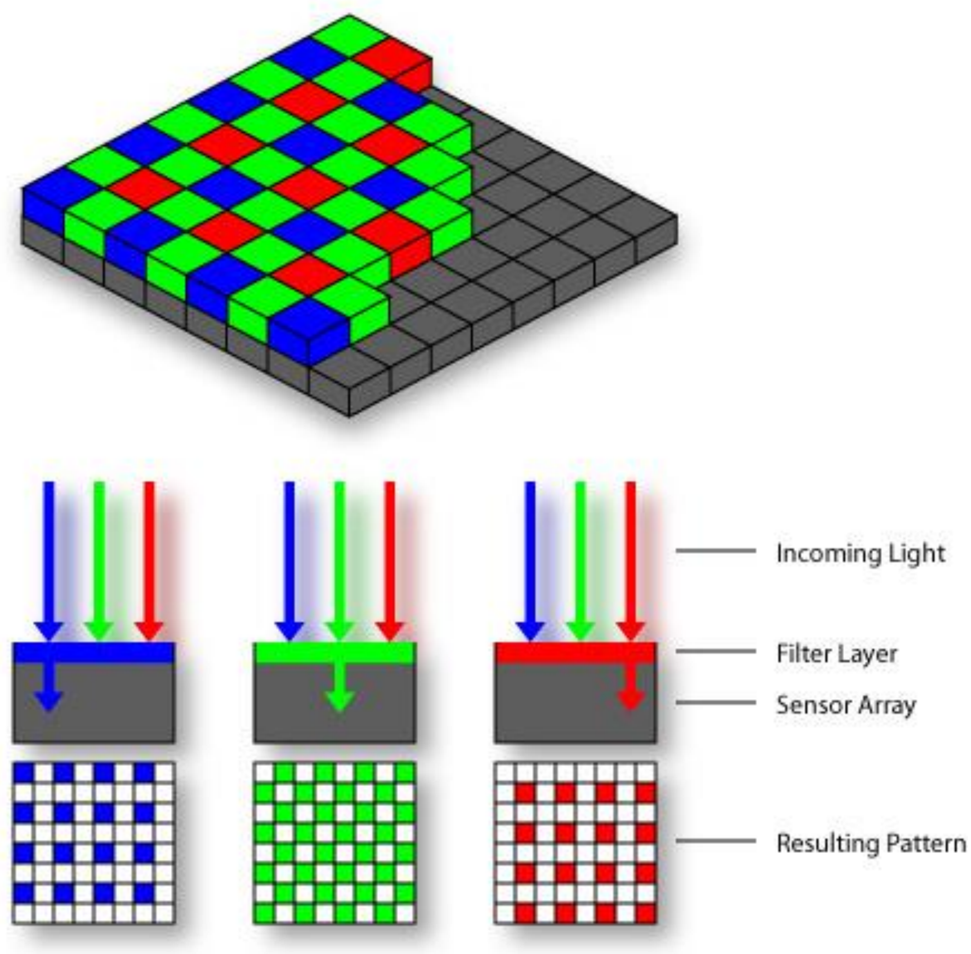


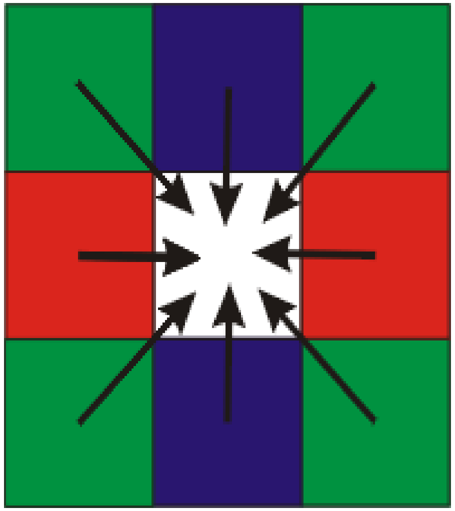


Slide Credit and Copyright: S. Palmer

How Do We Get Light?

Artificial Cones

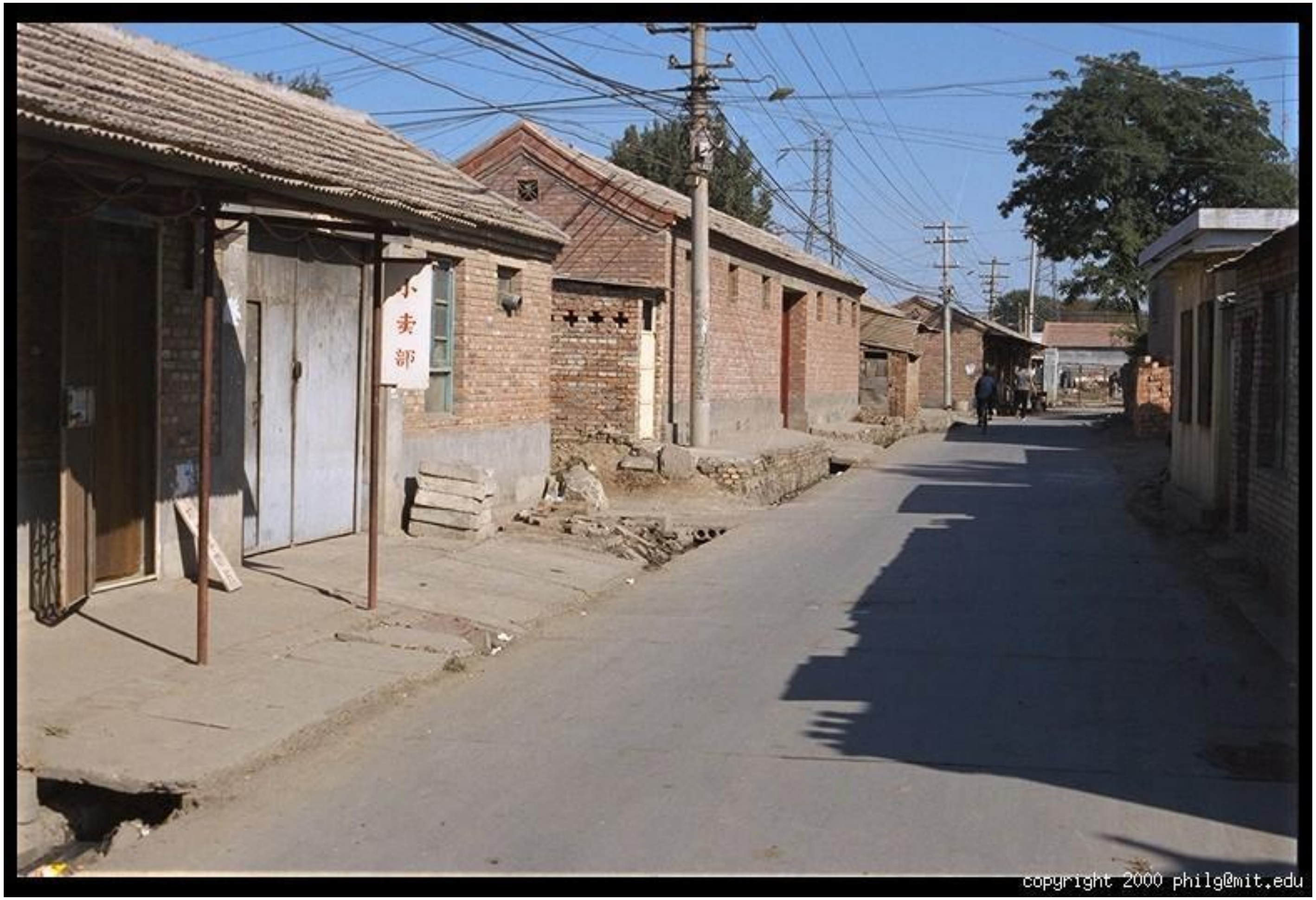




Estimate RGB at 'G' cells from neighboring values

Slide Credit: S. Seitz

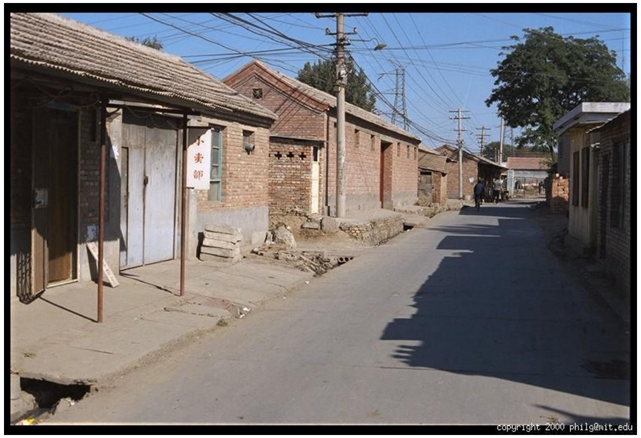
Color Image



Slide Credit: J. Hays

Color Image

Combined



Red

Green

Blue

Slide Credit: J. Hays

Images in Python

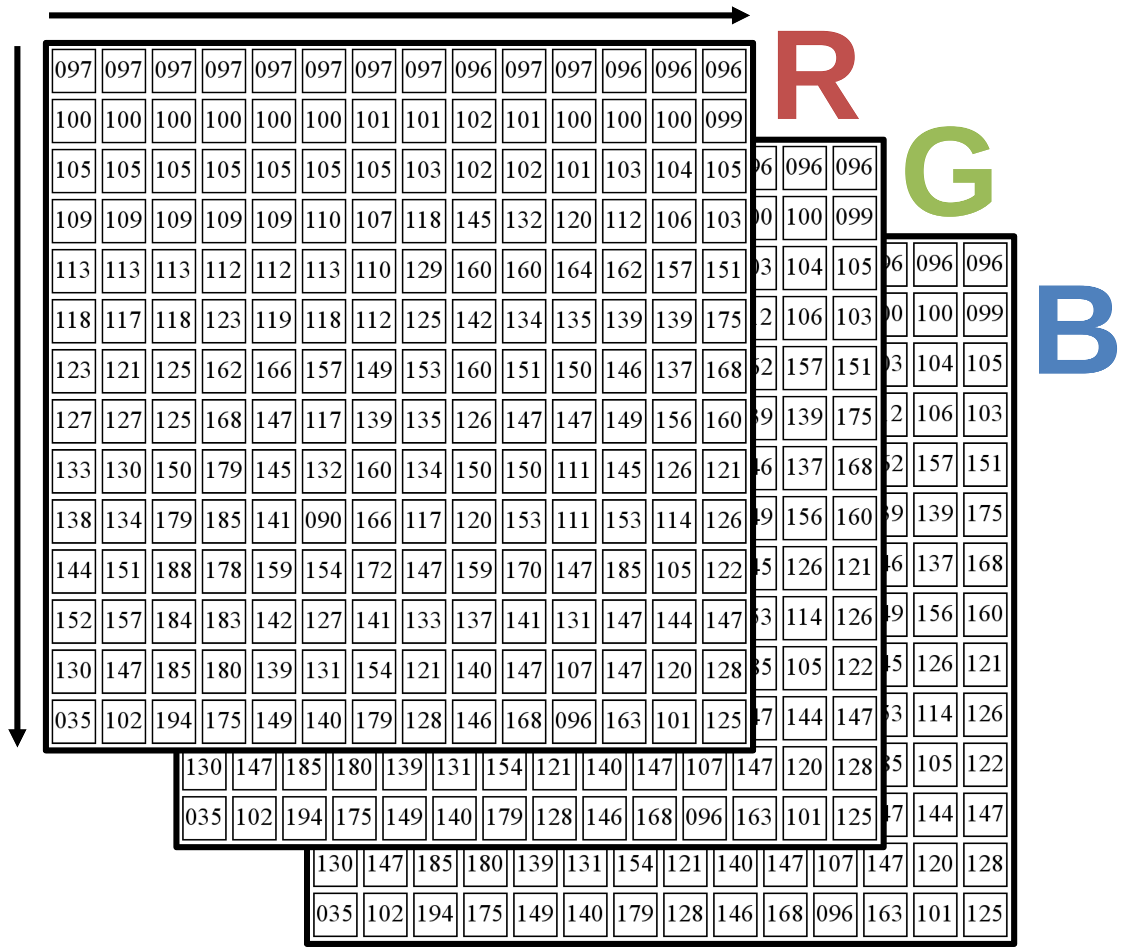
Images in Python

Images are matrix / tensor `im`

`im[0,0,0]`
    top, left, red

`im[y,x,c]`
    row y, column x, channel c

`im[H-1,W-1,2]`
    bottom right blue

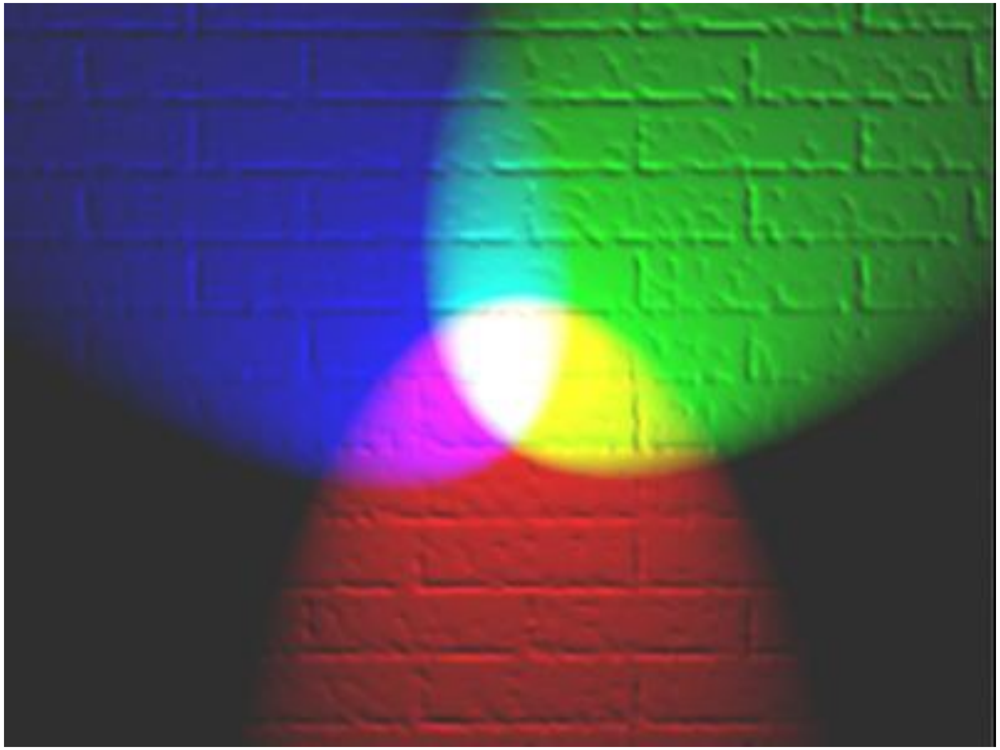


Slide inspired by James Hays

5 Things To Always Remember

1. Origin is top left
2. Rows are first index (**what's the fastest direction for accessing?)**
3. Usually referred to as Height x Width
4. Typically stored as uint8 [0,255]
5. for y in range(H): for x in range(W): will run <u>1 million times </u>for a 1000x1000 image. *A 4GHz processor can do only 4K clock cycles per pixel per second.*

Representing Colored Light



Discussion time: how many numbers do you actually need for colored light? Assume all tuples (R,G,B) are legitimate colors (they are).

Image Credit: http://en.wikipedia.org/wiki/File:RGB_illumination.jpg

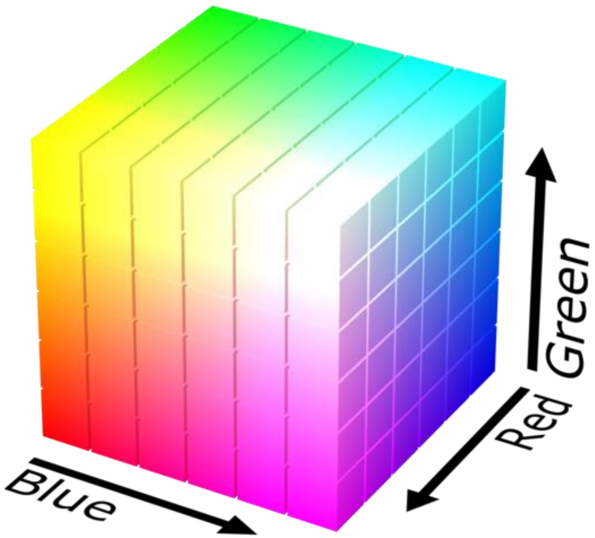
One Option: RGB

<u>Pros</u>

1. Simple
2. Common

<u>Cons</u>

1. Distances don't make sense
2. Correlated



Slide Credit: J. Hays, RGB cube: https://en.wikipedia.org/wiki/RGB_color_model

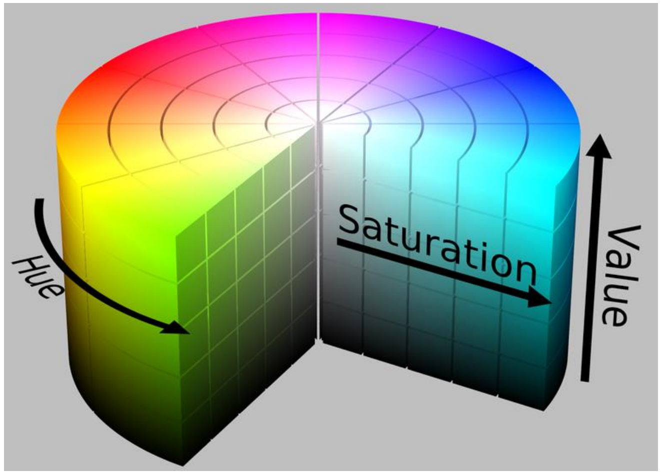
RGB

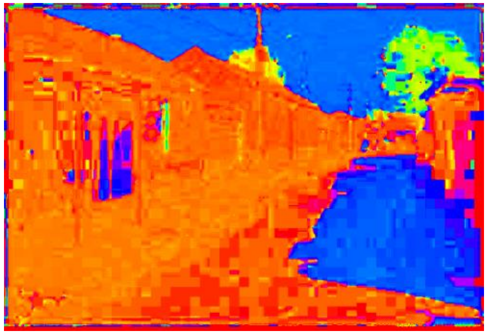
Photo credit: J. Hays

Another Option: HSV

Pros
1. Intuitive for picking colors
2. Sort of common
3. Fast to convert

Cons
1. Not as good as other better spaces





H
(S=1,V=1)

S
(H=1,V=1)

V
(H=1,S=0)

Slide Credit: J. Hays, HSV cylinder: https://en.wikipedia.org/wiki/HSL_and_HSV

HSV

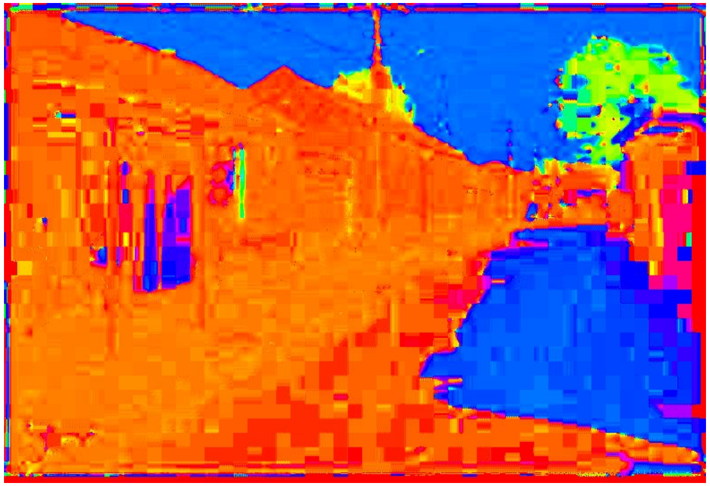


Photo credit: J. Hays

Another Option: YCbCr/YUV

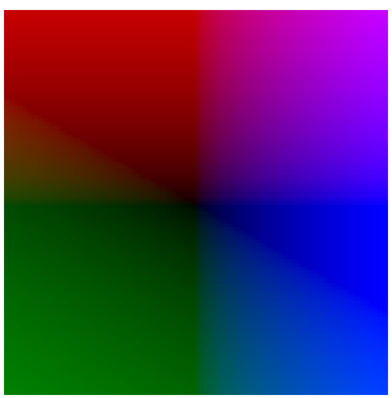
Pros

1. Great for transmission / compression

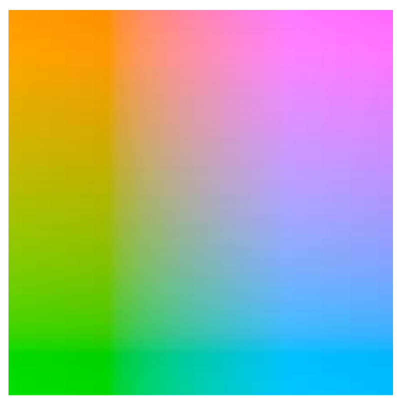
Cons

1. Not as good as other better smart color spaces

Y = 0



Y = 0.5



Y
(Cb=0.5, Cr=0.5)

Cb
(Y=0.5, Cr=0.5)

Cr
(Y=0.5, Cb=05)

Slide Credit: J. Hays, YUV cube: https://en.wikipedia.org/wiki/YUV

YCbCr

Photo credit: J. Hays

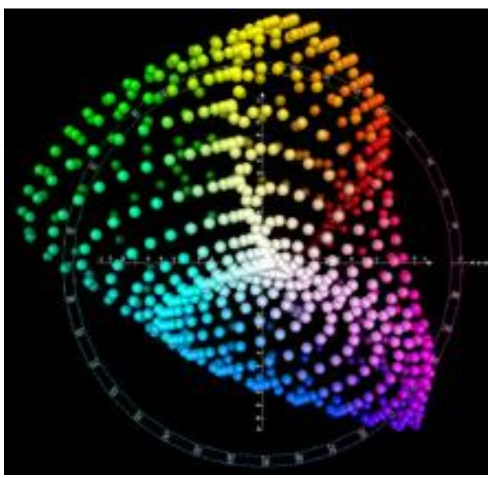
Another Option: Lab

<u>Pros</u>

1. Distances correspond with human judgment
2. Safe

<u>Cons</u>

1. Complex to calculate (don't write it yourself, lots of fp calculations)



L
(a=0,b=0)

a
(L=65,b=0)

b
(L=65,a=0)

Slide Credit: J. Hays, Lab diagram cube: https://en.wikipedia.org/wiki/CIELAB_color_space

Lab

Photo credit: J. Hays

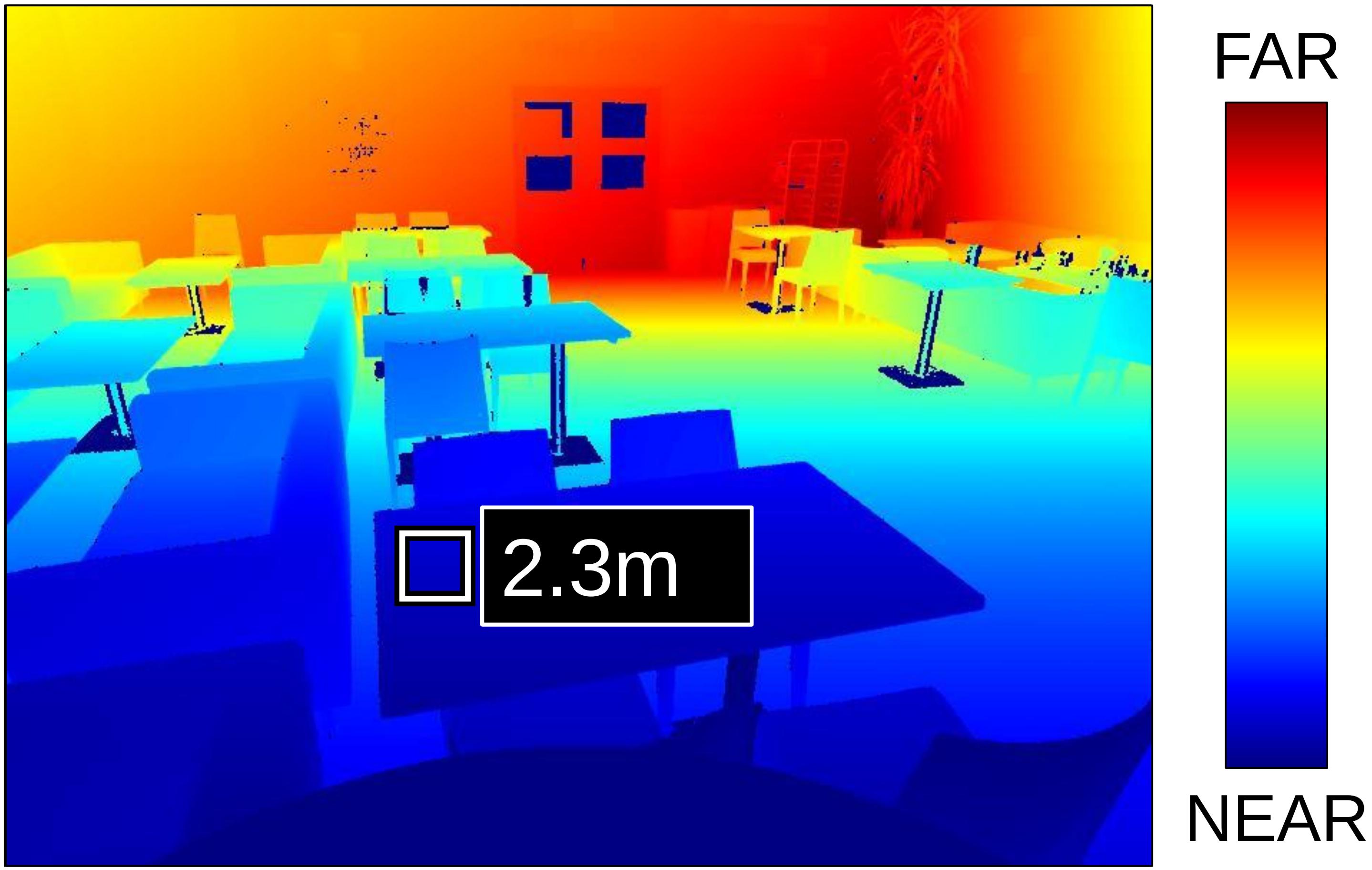
Why Are There So Many?

- Each serves different functions
  - RGB: sort of intuitive, standard, everywhere
  - HSV: good for picking, fast to compute
  - YCbCr/YUV: fast to compute, compresses well
  - Lab: the right(?) thing to do, but “slow” to compute
- Pick based on what you need and don’t sweat it: color really isn’t crucial

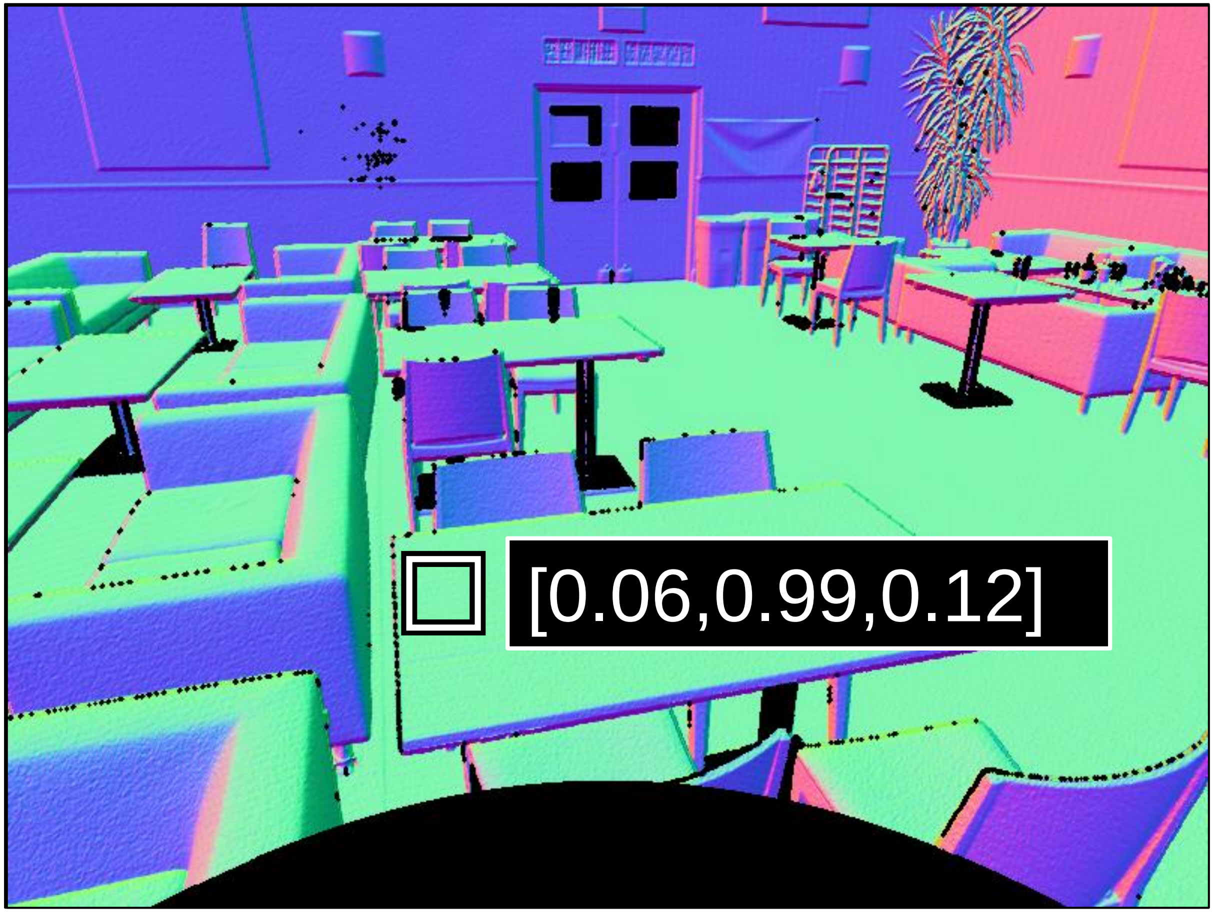
Only Images

- Almost all of this class is about ordinary RGB images because this has driven a lot of applications
- However, there are lots of other images

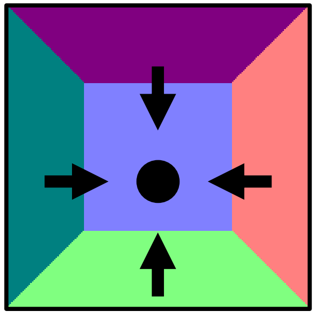
Depthmap



Surface Normals



Room



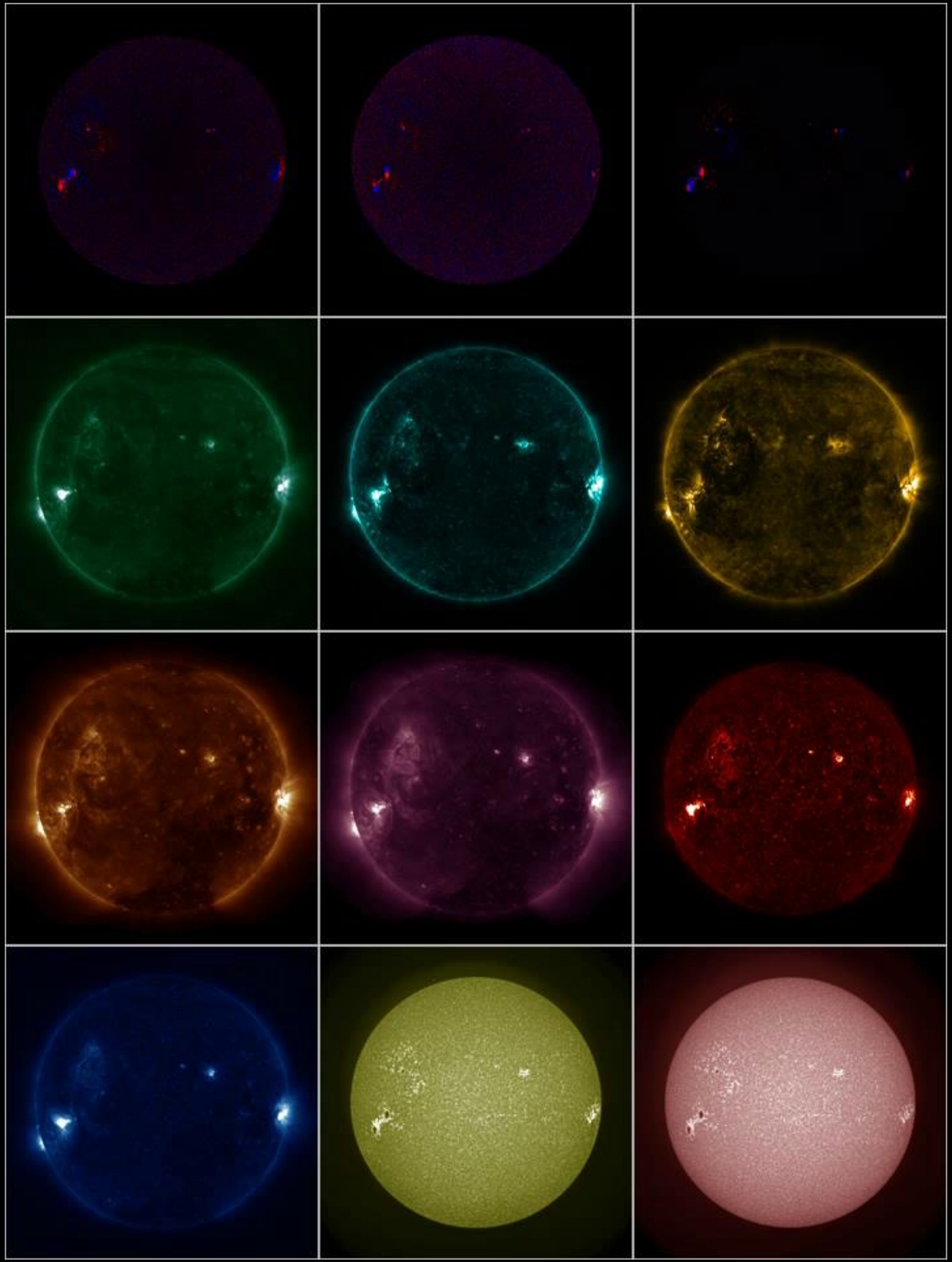
Legend

Science Data

Magnetic Field in:
x, y, z

Light at 9 ~wavelenths:
9.4nm, 13.1nm, 17.1nm
19.3nm, 21.1nm, 30.4nm
33.5nm, 160nm, 170nm

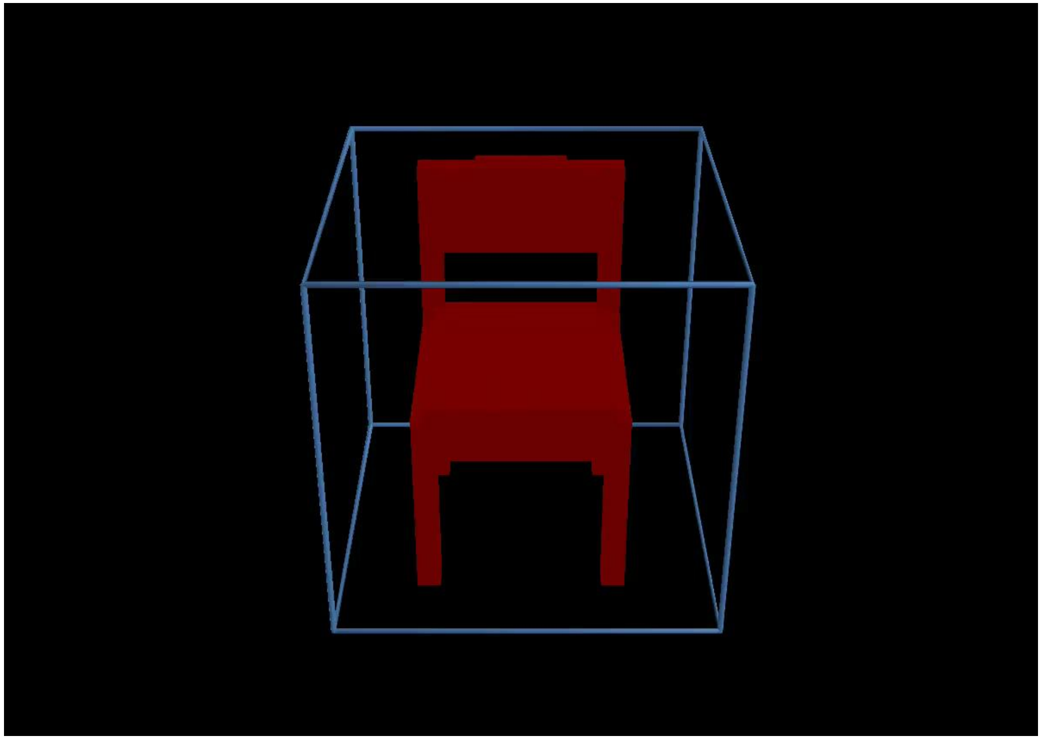
NASA Solar Dynamics Observatory observing solar flare



Volumes

Volumes: images with more dimensions.

Emerge in 3D reconstruction, medical imaging, temporal data



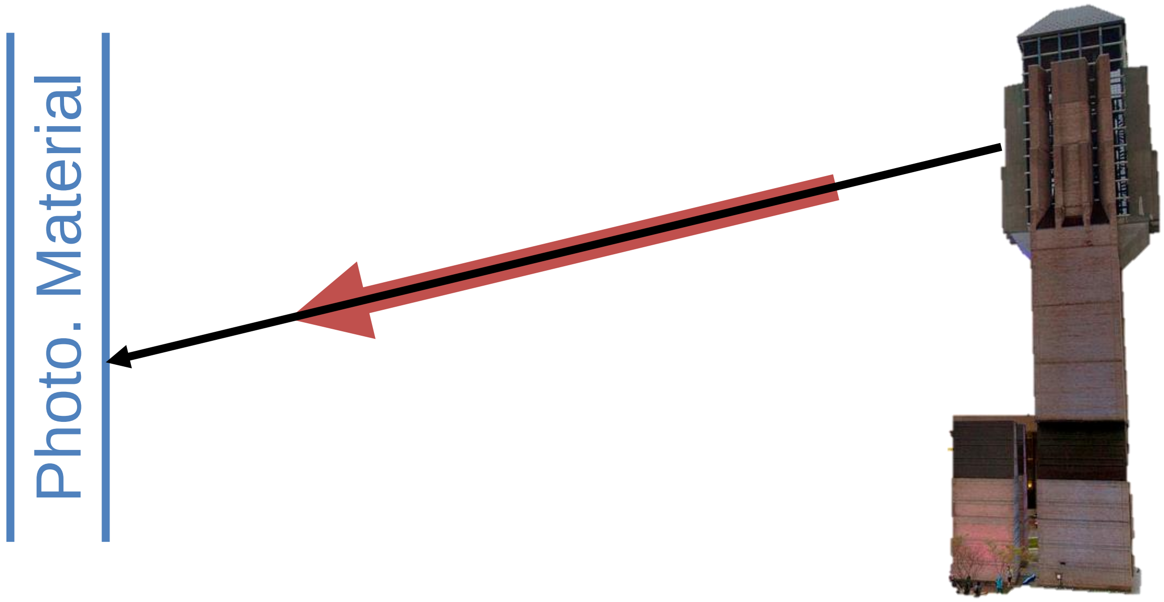
From: Girdhar et al., *Learning a predictable and generative vector representation for objects*. ECCV 2016

Other Images

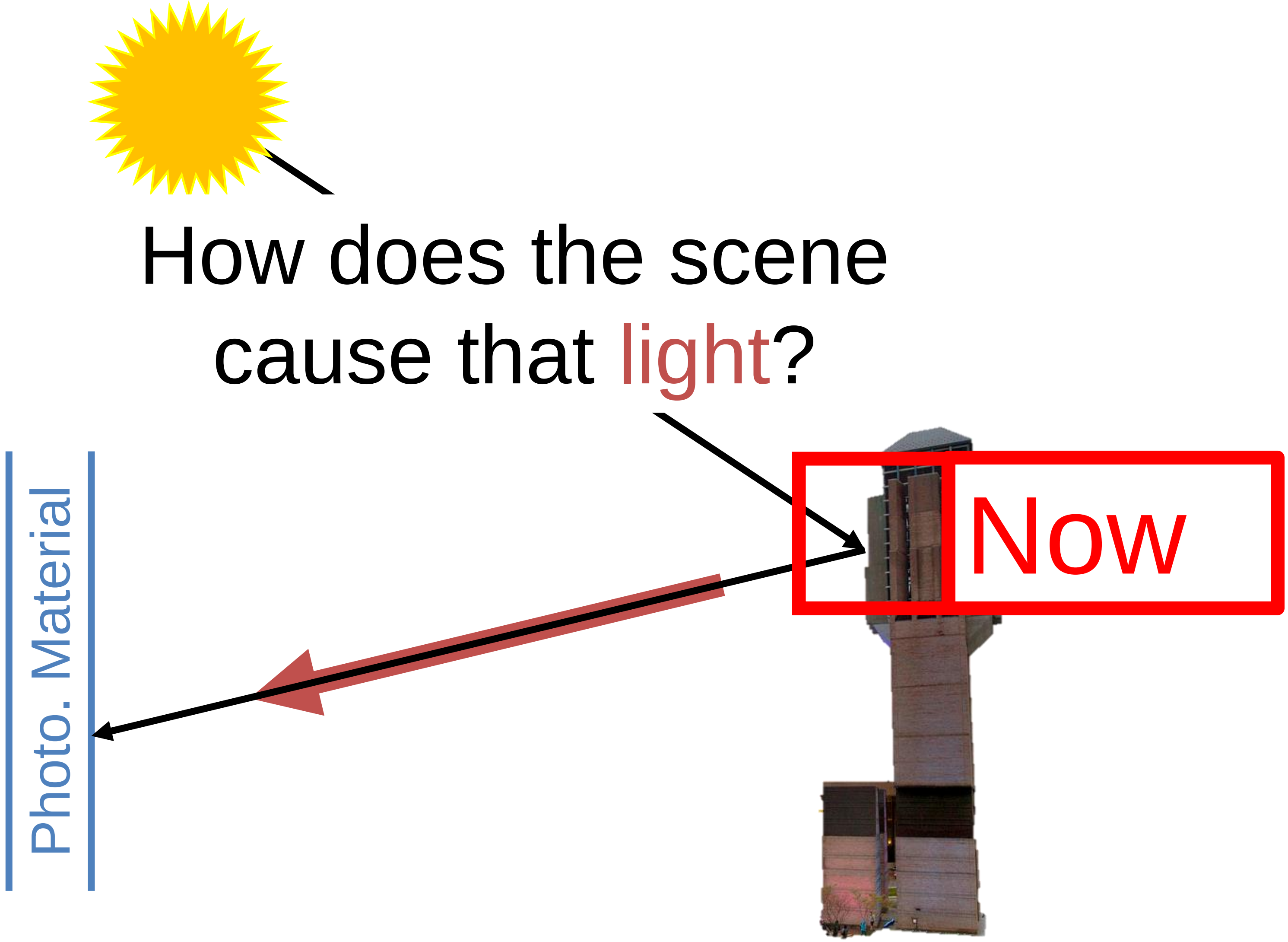
- A small part of computer vision in this class is really only for ordinary images
- The rest is easily generalized to other images
- Really transformative stuff will happen when good vision techniques get traction in other areas

So Far

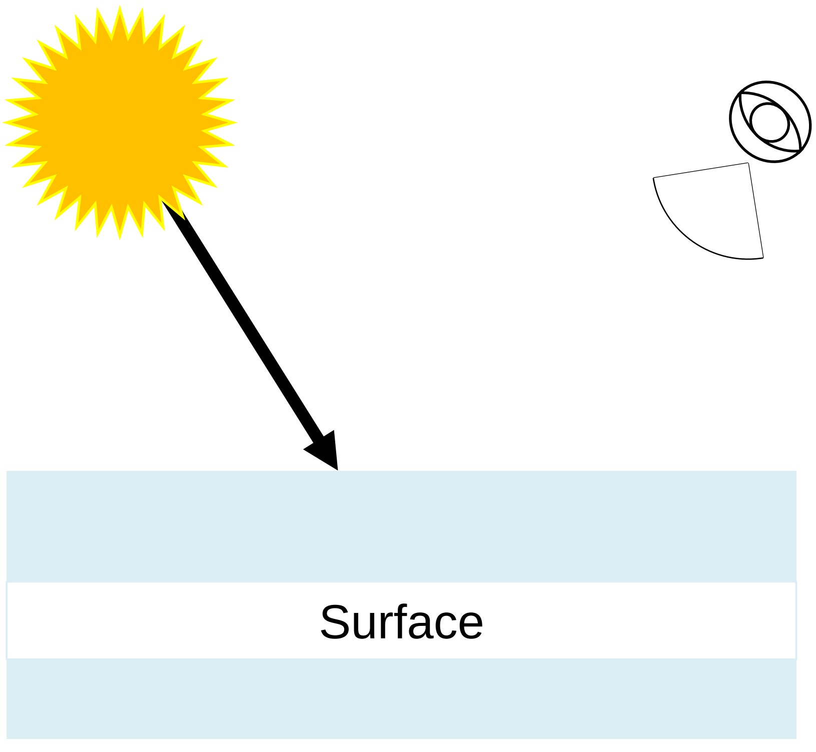
How do we represent light
and its storage on film?



Now

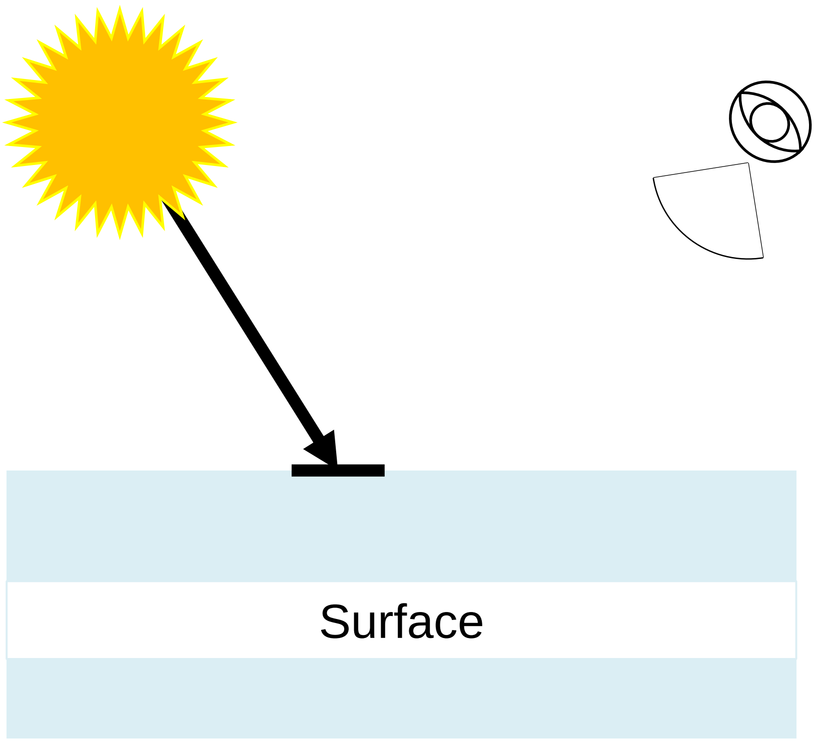


Light and Surfaces



What happens when light hits a surface?

Light and Surfaces

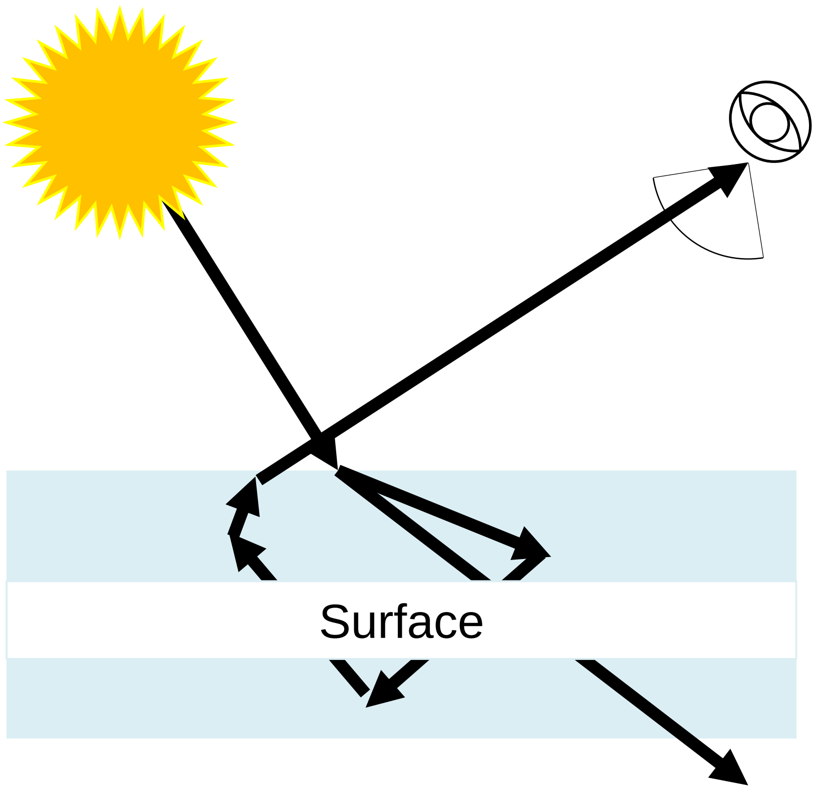


What happens when light hits a surface?

1. Absorbed

It's absorbed and converted into some other form of energy (e.g., a black shirt getting hot in the sun)

Light and Surfaces

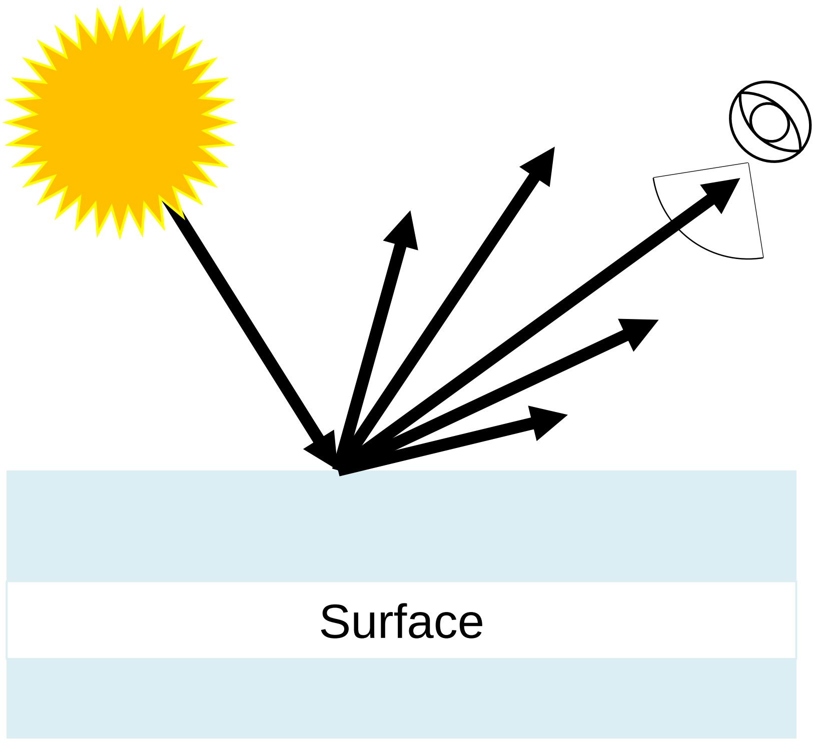


What happens when light hits a surface?

2. Transmitted

Possibly bouncing around before going through or out (e.g. lenses bend and go through, milk bounces around)

Light and Surfaces

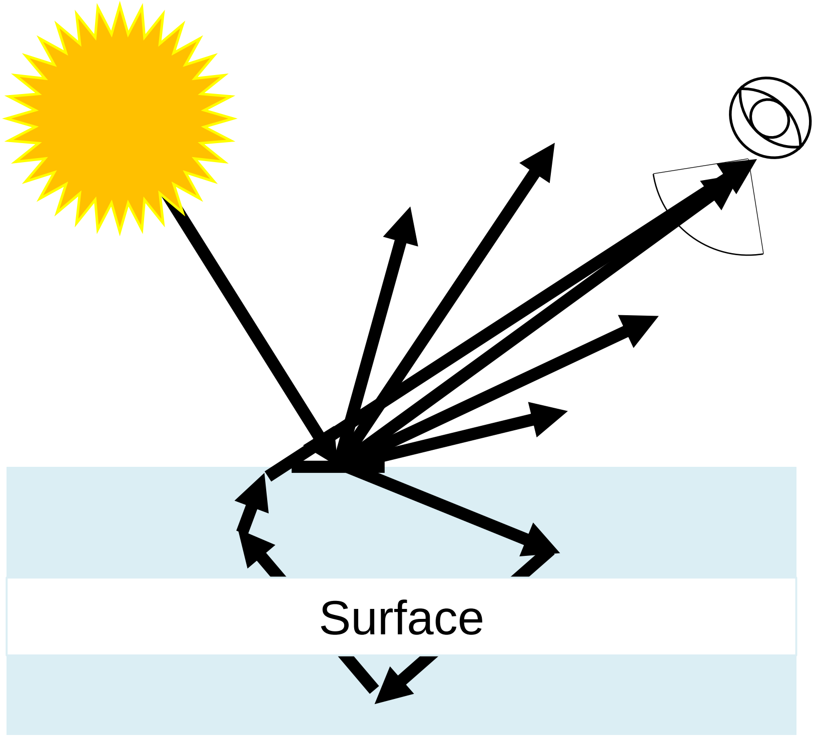


What happens when light hits a surface?

3. Reflected

It's reflected back, in one or more directions with varying amounts (e.g., mirror, or a white surface)

Light and Surfaces

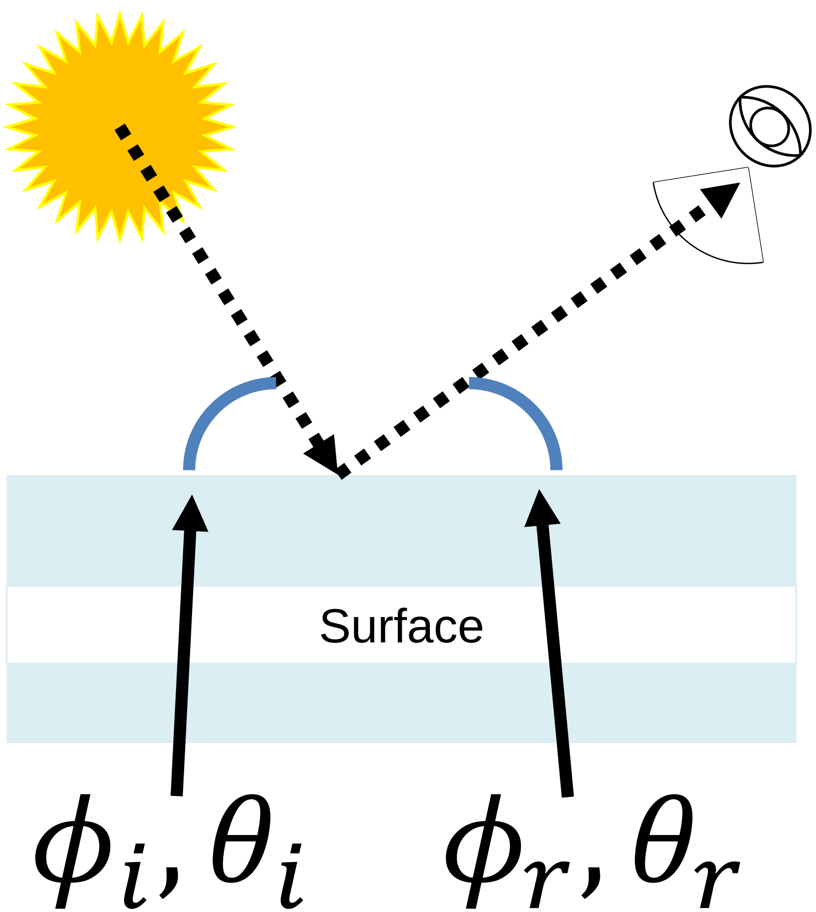


What happens when light hits a surface?

4. Everything

All of the above! Real surfaces often have combinations of all of these options.

Modeling Light and Surfaces



Opaque Reflections

Bi-directional reflectance function: % reflected given *__i__ncident angle* to light *__r__eflected angle* to the viewer.

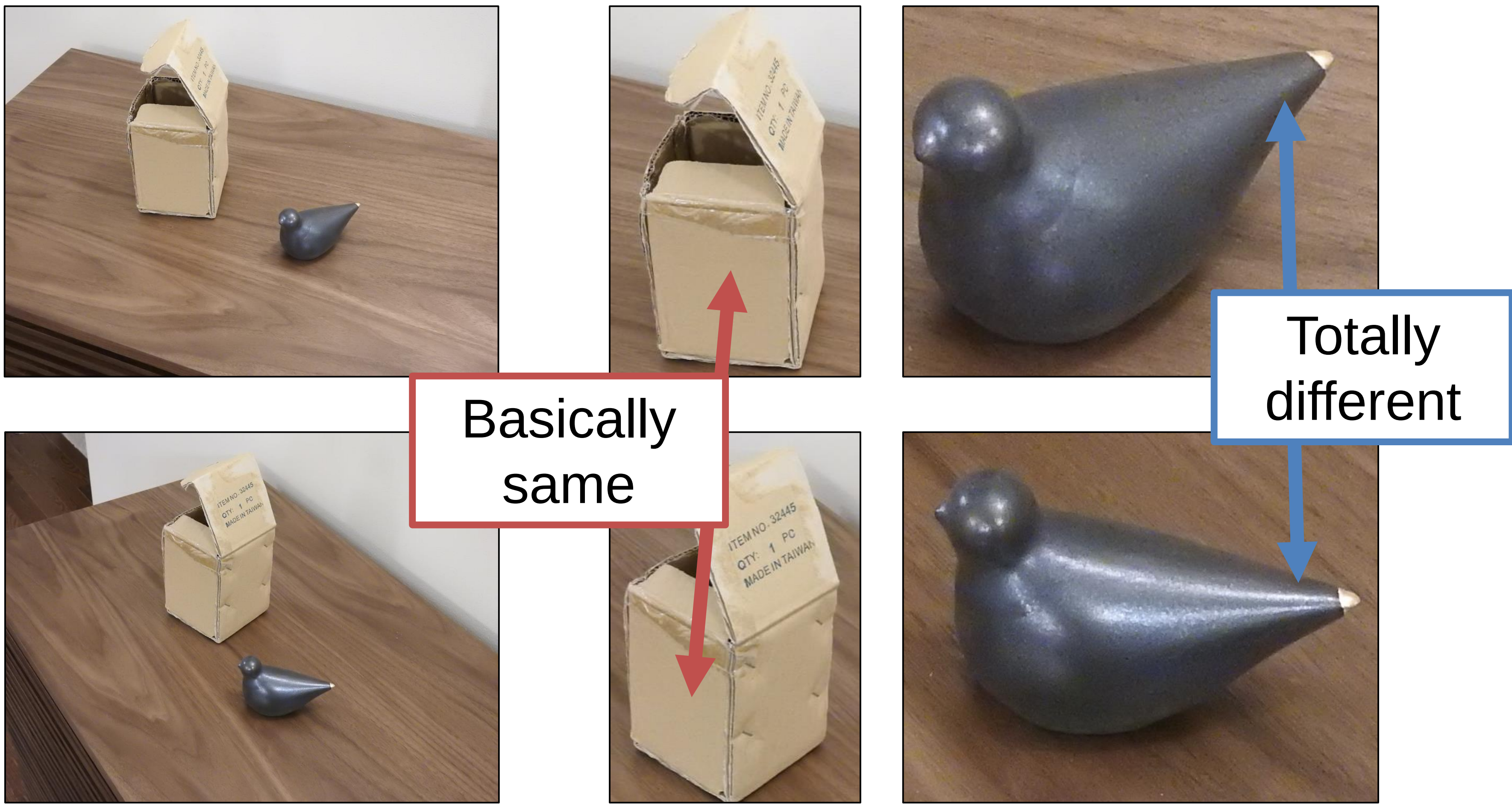
Note: have not specified form of function.

Specular and Diffuse Reflection

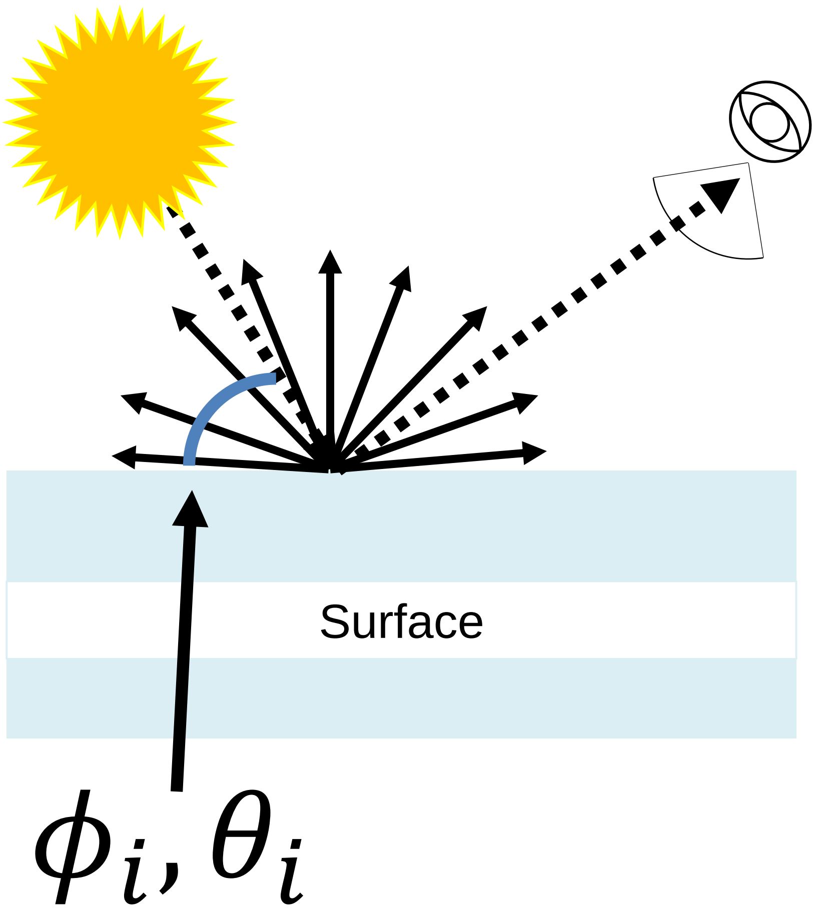
Same lighting, as close as possible camera settings, but different **location**

Specular and Diffuse Reflection

Diffuse Specular



Diffuse Reflection



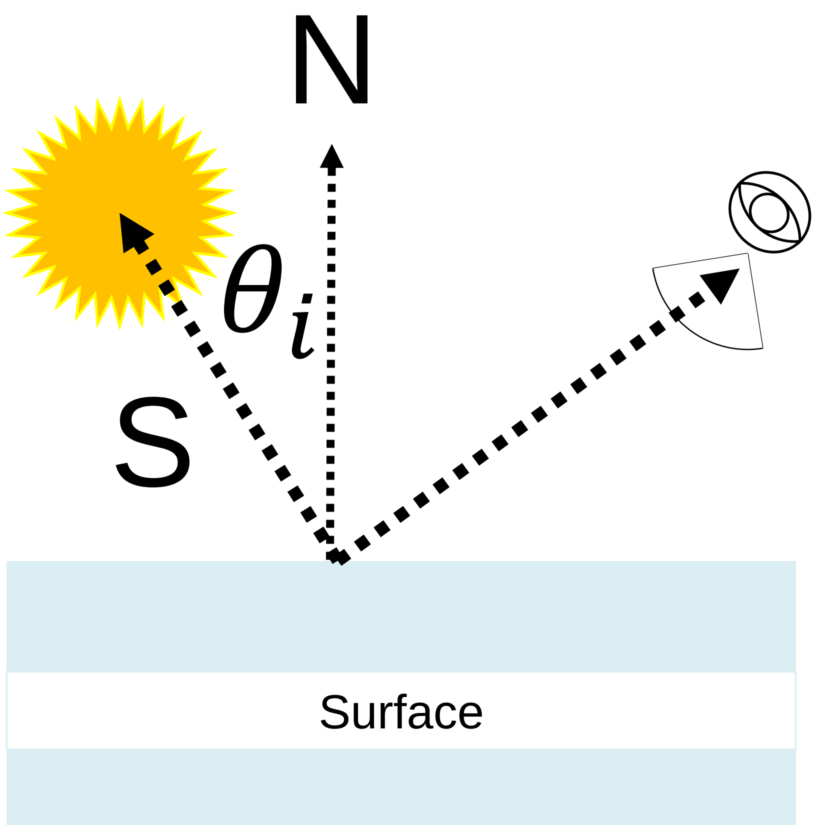
Lambertian Surface

Light depends **only** on orientation of surface

ϕ_i, θ_i

to light. Result of random small facets. Looks identical at all views.

Diffuse Reflection



Lambert's Law

N: surface normal

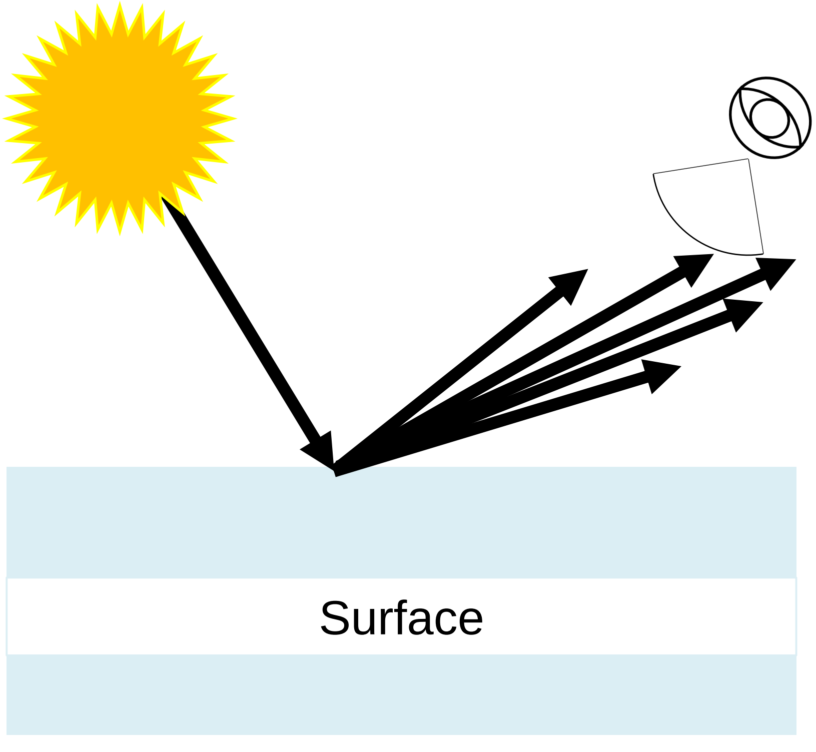
S: source direction **and** strength

ρ: how much is reflected

$$B = \rho \boldsymbol{N} \cdot \boldsymbol{S}$$

$$B = \rho ||\boldsymbol{S}|| \cos(\theta)$$

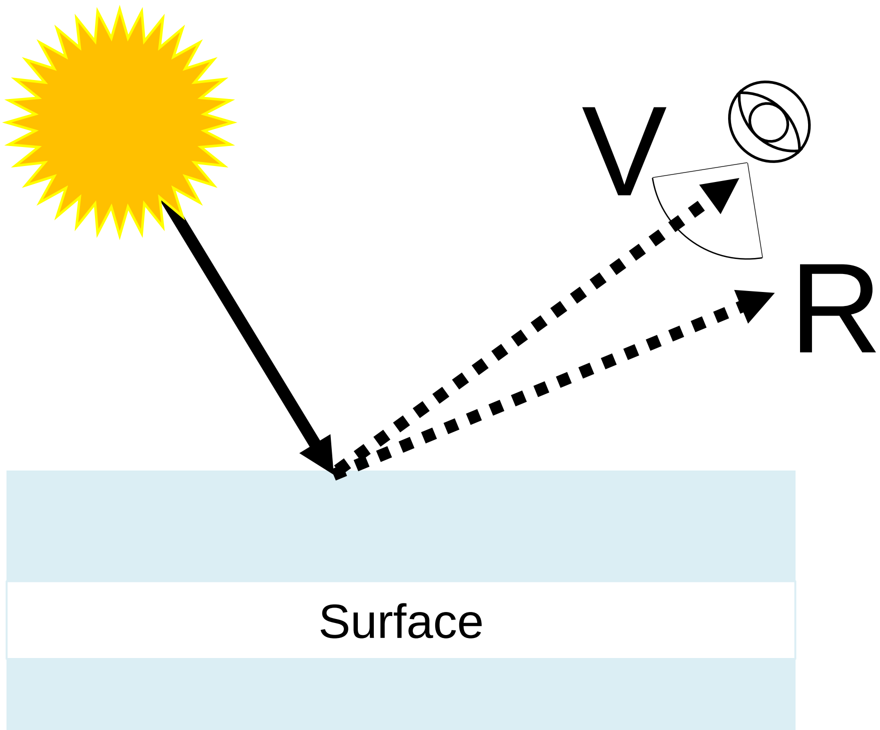
Specular Reflection



Specular Surface

Light reflected like a mirror, but spreads out in a “lobe” around the reflection ray

Specular Reflection



Phong Model

V: vector to viewer

R: reflection ray

α: shininess constant

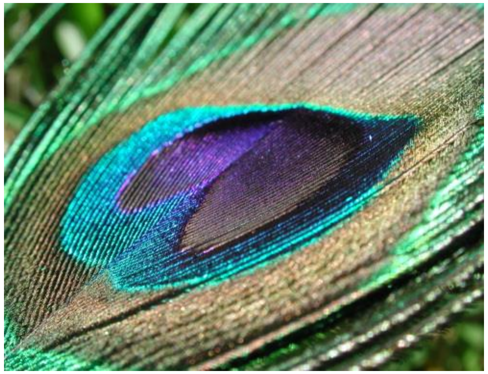
$$B = (V^T R)^\alpha$$

BRDFs can be incredibly complicated…










Slide Credit: L. Lazebnik

What Can This Be Used For

Shape from Shading

Lambert's Law: for every pixel i

$$B_i = \rho \boldsymbol{N}_i \cdot \boldsymbol{S}$$

Reflected Light (1 dim)	Surface Orientation (3? dim)	Illumination Global, (3 dim)

Given: illumination and light, recover normals

Potential problems?

Shape From Shading

$$B_i = \rho \boldsymbol{N}_i \cdot \boldsymbol{S}$$

1D, **fixed**

actually 2D
unknown

3D, **fixed**

- System of equations that’s underdetermined (N equations, 2N unknowns, N+3 known)
- **Solution**: Add more equations that enforce smoothness or finding a single surface.

Realistic Shape From Shading

$$B_i = \rho \boldsymbol{N}_i \cdot \boldsymbol{S}$$

1D, **fixed**

2D **unknown**

3D, **unknown**

- System of equations that's underdetermined (N equations, 2N+3 unknowns)
- **Solution**: need prior beliefs to disambiguate.

Ambiguity

Ambiguity

Humans assume light from above (and the blueness also tells you distance)

Photo Credit: https://en.wikipedia.org/wiki/Meteor_Crater

Shape from Shading in Practice

https://www.youtube.com/watch?v=4GiLAOtjHNo