

Welcome to Ma221! Lec 8 Fall 24

Recall Induction step of $PA = LU$

$$m \times \begin{bmatrix} I & n-1 \\ A_{11} & A_{12} \\ \hline A_{21} & A_{22} \end{bmatrix} = m \times \begin{bmatrix} I & n-1 \\ \hline \frac{A_{21}}{A_{11}} & 0 \\ I & \end{bmatrix} \circ m \times \begin{bmatrix} I & n-1 \\ \hline A_{11} & A_{12} \\ 0 & A_{22} - \frac{A_{21} \cdot A_{12}}{A_{11}} \end{bmatrix}$$

\uparrow
 $L(:,1)$

repeat

Express induction steps as code

for $i = 1 : n$

$$L(i,i) = 1, L(i+1:n,1) = A(i+1:n,1) / A(i,i)$$

... ignore perm for now

$$U(i,i:n) = A(i,i:n)$$

$$\text{if } i < n, A(i+1:n, i+1:n) = A(i+1:n, i+1:n) - L(i+1:n, i) \cdot U(i, i+1:n)$$

Add permutations

if $A(i,i) = 0$ and some $A(j,i) \neq 0$ for $j > i$
 swap rows i and j of L and A ,
 record in P

how to choose nonzero $A(j,i)$

called "pivoting", choices later

Don't waste space: L and U overwrite A

row i of U overwrites row i of A
omit $U(i, i:n) = A(i, i:n)$

col i of L below diagonal overwrites
same entries of A, which are
available because zeroed out:
change first line to

$$A(i+1:n, i) = A(i+1:n, i) / A(i, i)$$

change last line to

$$\begin{aligned} A(i+1:n, i+1:n) &= A(i+1:n, i+1:n) \\ &- A(i+1:n, i) \cdot A(i, i+1:n) \end{aligned}$$

Summarize:

for $i = 1$ to $n-1$

if $A(i, i) = 0 \neq A(j, i)$ for $j > i$,
swaps rows i and j

record swap in P

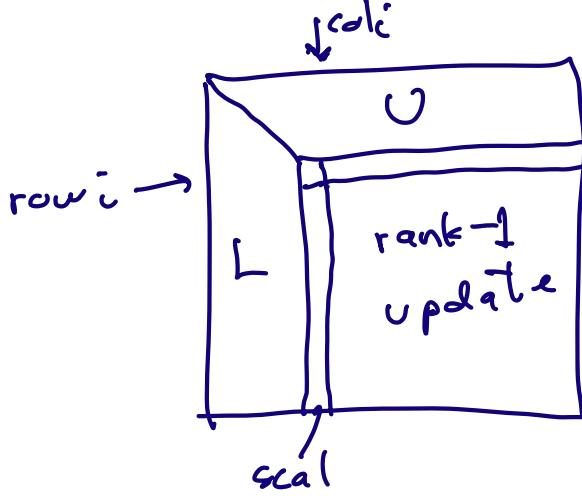
$$A(i+1:n, i) = A(i+1:n, i) / A(i, i)$$

... BLAS1 scal

$$\begin{aligned} A(i+1:n, i+1:n) &= A(i+1:n, i+1:n) \\ &- A(i+1:n, i) \cdot A(i, i+1:n) \end{aligned}$$

... BLAS2 ger rank-1 update

no data reuse yet, slow



$$\begin{aligned} \# fops &= \\ &\sum_{i=1}^{n-1} (n-i) + 2(n-i)^2 \\ &= \frac{2}{3} n^3 + O(n^2) \end{aligned}$$

How to pivot, ie. Choose $A(i,i) \neq 0$

(goal): backward stability

$$P \cdot L \cdot U = A + E, \quad \|E\| = O(\varepsilon) \cdot \|A\|$$

not guaranteed by $A(i,i) \neq 0$

Ex: single precision $\varepsilon \sim 10^{-7}$

$$A = \begin{bmatrix} 10^{-8} & 1 \\ 1 & 1 \end{bmatrix} \quad A^{-1} \cong \begin{bmatrix} -1 & 1 \\ 1 & -10^{-8} \end{bmatrix}$$

$$\kappa(A) \sim 2.6 \quad \text{well-conditioned}$$

\Rightarrow expect accurate answer

$$L = \begin{bmatrix} 1 & 0 \\ 10^{-8} & 1 \end{bmatrix}, \quad U = \begin{bmatrix} 10^{-8} & 1 \\ 0 & \text{fl}(1 - 10^{-8} \cdot 1) \end{bmatrix} = -10^{-8}$$

$\text{fl}\left(\frac{1}{10^{-8}}\right)$

Get same L, U if $A(2,2)$ were $-5, -1, \dots$

because $\text{fl}(A(2,2) - 10^{-8} \cdot 1)$ "forgets"

$A(2,2)$ if small enough, $O(1)$,

so solving $Ax=b$ using this L, U
gives same answer independent of $A(2,2)$
wrong!

Instead: swap rows 1 and 2 $\Rightarrow A(1,1)=1$
and get full accuracy in $A^{-1}, Ax=b$

Intuition: want large entry of A
on diagonal

Recall Q1.10: $C = fl(A \cdot B) = A \cdot B + E$
 $|E| \leq n \cdot \varepsilon \cdot |A| \cdot |B|$

since $A = P \cdot L \cdot U$, get similar bound:

Thm: (Backward Error of LU)

if P, L, U from Gaussian Elim

$$A - E = P \cdot L \cdot U$$

$$|E| \leq n \cdot \varepsilon \cdot P \cdot |L| \cdot |U|$$

Cor: Solve $Ax=b$ by GE, forward
substitution with L , backwards with U
computed \hat{x} satisfies

$$(A - E)\hat{x} = b, |E| \leq 3 \cdot n \cdot \varepsilon \cdot P \cdot |L| \cdot |U|$$

Proof of Cor: assume $P=I$ for simplicity
(imagine running alg on $P^T A$)

Use Q1.11

Solve $L\hat{y} = b$, get $(L + \delta L)\hat{y} = b$ $|\delta L| \leq n \cdot \varepsilon \cdot \|L\|$
Solve $Ux = \hat{y}$, get $(U + \delta U)\bar{x} = \hat{y}$ $|\delta U| \leq n \cdot \varepsilon \cdot \|U\|$

$$\begin{aligned} b &= (L + \delta L)\hat{y} = (L + \delta L)(U + \delta U)\bar{x} \\ &= (L \cdot U + \delta L \cdot U + L \cdot \delta U + \delta L \cdot \delta U)\bar{x} \quad \text{by Thm} \\ &= (A - E + \delta L \cdot U + L \cdot \delta U + \delta L \cdot \delta U)\bar{x} \\ &= (A - F)\bar{x} \end{aligned}$$

$$\begin{aligned} |F| &\leq |E| + |\delta L \cdot U| + |L \cdot \delta U| + |\delta L \cdot \delta U| \\ &\leq |E| + |\delta L| \cdot |U| + |L| \cdot |\delta U| + |\delta L| \cdot |\delta U| \\ &\leq n \cdot \varepsilon \cdot \|L\| \cdot \|U\| + n \cdot \varepsilon \cdot \|L\| \cdot \|U\| + \|L\| \cdot n \cdot \varepsilon \cdot \|U\| \\ &\quad + (n \cdot \varepsilon)^2 \|L\| \cdot \|U\| \\ &\approx 3n \varepsilon \|L\| \cdot \|U\| \quad \text{QED of Cor.} \end{aligned}$$

Proof sketch of Thm (assume $P = I$)

Trace through alg: how is $U(i,j)$ computed?

$$\begin{aligned} \text{when } i \leq j \quad U(i,j) &= A(i,j) - L(i,1) \cdot U(1,j) \\ &\quad - L(i,2) \cdot U(2,j) \\ &= A(i,j) - \underbrace{\sum_{k=1}^{i-1} L(i,k) \cdot U(k,j)}_{\substack{\text{dot product of} \\ \text{row } i \text{ of } L \text{ with col } j \text{ of } U}} \end{aligned}$$

Use previous analysis of dot prod

when $i > j$ same idea

$$L(i,j) = \frac{A(i,j) - \sum_{k=1}^{j-1} L(i,k) \cdot U(k,j)}{U(j,j)}$$

again use dot product QED

\Rightarrow intuition: want $|L(i,j)|$ to be small

(i) Standard: "partial pivoting" (GEPP)
At each step choose largest entry
among $A(i:n, \bar{c})$

$$\Rightarrow |L(k,i)| = |A(k,\bar{c}) / A(i,\bar{c})| \leq 1$$

Then: with GEPP, $|L| \leq 1$

$$\text{and } \max(|U(:, \bar{c})|) \leq 2^{n-1} \max(|A(:, \bar{c})|)$$

Bad news: attainable in worst case

$$\|F\| \leq n \cdot \varepsilon \cdot 2^n \|A\|, \text{ lose all}$$

precision in single precision for $n \geq 24$

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ -1 & 1 & 0 & 2 \\ -1 & -1 & 1 & 2 \\ -1 & -1 & -1 & 12 \end{bmatrix} \begin{matrix} 4 \\ 4 \\ 8 \end{matrix}$$

Good news: hardly ever happens,
GEPP is standard alg

Empirical observation $\frac{\|LU\cdot 101\|}{\|A\|} = g \leq n^{2/3}$
 $g = \text{"growth factor"}$

If entries of A are random
 true with high probability

(2) Complete Pivoting: permute rows and columns
 so each $A(i,i)$ is largest in all remaining
 rows and columns

$$P_r^T A P_c^T = LU \quad \text{called GECP}$$

more stable than GEPP, $O(n^3)$ more expensive

Thm $g \leq n^{(\log n)/4}$

Empirically $g \leq n^{1/2}$, not much better than GEPP
 rarely used in practice

(3) Tournament pivoting: needed to
 hit communication lower bound $O\left(\frac{n^3}{JM}\right)$

(4) Threshold pivoting (sparse case)

trade off stability and sparsity,
 i.e. speed

Error bound for $Ax = b$

$$\frac{\|x - \hat{x}\|}{\|x\|} \leq k(A) \cdot \text{backward error}$$

$$\leq k(A) \cdot 3 \cdot n \cdot \varepsilon \cdot g$$

$g = \text{growth factor}$

$$= k(A) \cdot 3 \cdot n \cdot \varepsilon \cdot \frac{\|L \cdot U\|}{\|A\|}$$

We can estimate $k(A)$ and g in $O(n^2)$ work

What if error bound too large?

or error ok, but too slow, so want to use lower precision?

Try Iterative Refinement, aka Newton's Method

use mixed precision

most work ($O(h^3)$ part) in low prec (fast)

rest, $O(h^2)$, in high prec. (slow)

Low/high could mean

single / double

half / single

double / quad

other combinations, using 3 precisions, or ...

Do GEPP to solve $Ax=b$ in low prec
call initial solution $x(1)$

$i=1$
 repeat $r = A \cdot x(i) - b$ in high prec
 $O(n^2)$ cost

solve $A d = r$ in low prec, using
 $A = P \cdot L \cdot U$, $O(n^2)$ cost
 update $x(i+1) = x(i) - d$ in low prec
 $O(n)$ cost
 until "convergence"

Testing "convergence" depends on goals:

(1) Getting a small backward in higher prec.

$$\|A x_{\text{comp}} - b\| = O(\varepsilon_{\text{high}}) \cdot \|A\| \cdot \|x_{\text{comp}}\|$$

or get a warning that A too ill-conditioned
to converge

Easy to implement because we already have

$$r = A \cdot x_{\text{comp}} - b$$

Motivation: use 16-bit accelerators
for $O(n^3)$ work

Recent work beyond Newton:
use GMRES instead (Chap 6)

(2) Getting a small relative error
in lower precision

$$\frac{\|x - x_{\text{comp}}\|}{\|x\|} = O(\varepsilon_{\text{low}})$$

or a warning if too ill-conditioned;
convergence criterion complicated, need
to avoid being "fooled" by misconvergence
Details in class notes, see LAPACK
sgesvx

(3) What is value of doing $r = Ax(0) - b$
in low prec?

can get $|E| \leq n \cdot \varepsilon^{-1} \|A\|$

i.e. preserve sparsity

Rearranging GE to Minimize Comm.

Goal: same lower bound as Matmul:

$$\Omega\left(\frac{n^3}{\sqrt{M}}\right)$$

Historically: reorganize GEPP to
use BLAS3 (use GEMM i.e. matmul
and TRSM, $LX = B$)

Idea: similar induction proof as
for GEPP:

do b columns at a time,
apply updates to Schur
complement all at once, using GEMM

Ignore pivoting

$$A = b \begin{bmatrix} b & n-b \\ \hline A_{11} & A_{12} \\ \hline A_{21} & A_{22} \end{bmatrix} = \begin{bmatrix} L_{11} \cdot U_{11} & A_{12} \\ \hline L_{21} \cdot U_{11} & A_{22} \end{bmatrix}$$

where $\begin{bmatrix} A_{11} \\ A_{21} \end{bmatrix} = \begin{bmatrix} L_{11} \\ L_{21} \end{bmatrix} U_{11}$ using GEPP on b columns

$$= \begin{bmatrix} L_{11} U_{11} & L_{11} \cdot U_{12} \\ \hline L_{21} U_{11} & A_{22} \end{bmatrix} \quad \text{where we solved } A_{12} = L_{11} U_{12} \text{ for } U_{12} \text{ using TRSM}$$

$$= \begin{bmatrix} L_{11} & 0 \\ \hline L_{21} & I \end{bmatrix} \circ \begin{bmatrix} U_{11} & U_{12} \\ \hline C & A_{22} - L_{21} \cdot U_{12} \end{bmatrix} \quad S = \text{Schur complement}$$

update A_{22} using GEMM
repeat on S

Often very fast, but for some combinations of n and $M = \text{cache size}$, can't choose $b = \text{block size}$ to reach $O(\frac{n^3}{JM})$

Just as for matmul, there is a cache oblivious GEPP that reaches $O(\frac{n^3}{JM})$ (1997 Toledo)

High level

Do LU on left half of A

Update right half (U at top)

Schur complement

at bottom

Do LU on Schur Complement

Function $[L, U] = RLUV(A)$ recursive LU

... assume A $n \times m$, $n \geq m$, m power of 2

if $m=1$... one column

pivot so $A(1,1)$ largest entry, pivot
rest of matrix

$$L = A/A_{11}, U = A_{11}$$

e.g. write $A = \frac{m}{2} \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$ $L_1 = \begin{bmatrix} L_{11} \\ L_{21} \end{bmatrix}^{\frac{m}{2}}$

$$[L_1, U_1] = RLUV\left(\begin{bmatrix} A_{11} \\ A_{21} \end{bmatrix}\right) \dots \text{LU of left half}$$

Solve $A_{12} = L_{11} \cdot U_{12}$ for $U_{12} \dots$
update U

$$A_{22} = A_{22} - L_{21} \cdot U_{12} \dots \text{update}$$

Schur comp

$$[L_2, U_2] = RLUV(A_{22})$$

$$L = [L_1, \begin{bmatrix} 0 \\ L_2 \end{bmatrix}]^{n \times m}, U = \begin{bmatrix} U_{11} & U_{12} \\ 0 & U_{22} \end{bmatrix}^{m \times m}$$

correct by induction

$$\begin{aligned}
 \text{Cost } A(n) &= \text{recurrence} \\
 &= \# \text{arith ops} = \frac{2}{3} n^3 + O(n^2) \\
 &= \text{same as usual GEPP} \\
 W(n) &= \# \text{words move} = O\left(\frac{n^3}{M}\right)
 \end{aligned}$$

RLV : only minimizes # words moved
 not # messages : need more ideas