

Welcome back to Ma221! Lecture 34, Nov 13

Recall Poisson Equation

$$1D: T_N = \begin{bmatrix} z^{-1} & & & \\ -1 & \ddots & & \\ & \ddots & \ddots & \\ & & -1 & z \end{bmatrix} = Z \Lambda Z^T$$

$$2D: T_N V + V T_N = F, \text{ solve for } N \times N \text{ } V$$

turn V into vector $\text{vec}(V)$

$$(I_N \otimes T_N + T_N \otimes I_N) \text{vec}(V) = \text{vec}(F)$$

$$\hookrightarrow (Z \otimes Z) (I_N \otimes \Lambda + \Lambda \otimes I_N) (Z \otimes Z)^T$$

↑ diagonal, all pairs $\lambda_i + \lambda_j$

where $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_N)$

$$\text{cond} \# = \frac{2 \cdot \lambda_N}{2 \cdot \lambda_1} \text{ same as for } T_N$$

$$3D: (T_N \otimes I_N \otimes I_N + I_N \otimes T_N \otimes I_N + I_N \otimes I_N \otimes T_N)$$

$$= (Z \otimes Z \otimes Z) (\Lambda \otimes I_N \otimes I_N + I_N \otimes \Lambda \otimes I_N + I_N \otimes I_N \otimes \Lambda)$$

$$- (Z \otimes Z \otimes Z)^T \quad \uparrow \text{diagonal, all}$$

triples $\lambda_i + \lambda_j + \lambda_k$

Same condition number

Summary of Performance of all
Algorithms on Poisson in 2D and 3D

Count #flops (all in $O(\cdot)$ sense)

Memory needed (#words)

Parallel steps on "perfect" parallel computers with as many processors as needed

Processors needed

(see CS267 for practical parallel algs)

Entries sorted in 2 orders

from slowest to fastest for Poisson
(roughly) from most general, to
most specific for Poisson

Some Terminology:

"Explicit Inverse" = we compute and store A^{-1} ahead of time, don't count cost of A^{-1} , just multiplying by it

SOR: Successive Overrelaxation

SSOR / Chebyshev \equiv Symmetric SOR
with Chebyshev acceleration

FFT = Fast Fourier Transform

BCR = Block Cyclic Reduction

Lower Bound = assume 1 flop per component of answer

SpMV = Sparse-Matrix-Vector-Multiplication
 $\text{cost}(\text{SpMV}) = \# \text{ nonzeros}$

For 2D Poisson on $n \times n$ mesh
 $N = n^2 = \# \text{ unknowns}$

3D Poisson on $n \times n \times n$ mesh
 $N = n^3 = \# \text{ unknowns}$

If table entry for 2D and 3D different,
 then 3D in parentheses

All entries in $O(\cdot)$ sense

Method	direct or iterative	#flops	Mem	#Parallel steps	#Procs
Dense Cholesky any spd. matrix	D	N^3	N^2	N	N^2
Explicit Inverse any matrix	D	N^2	N^2	$\log N$	N^2
Band Cholesky	D	N^2 ($N^{7/3}$)	$N^{3/2}$ ($N^{5/3}$)	N N	N ($N^{4/3}$)
works on any band s.p.d. matrix, cost = $O(N \cdot bw^2)$					
2D: $bw = n = N^{1/2}$					
3D: $bw = n^2 = N^{2/3}$					
Jacobi	I	N^2 ($N^{5/3}$)	N N	N ($N^{2/3}$)	N N
$\# \text{flops} = O(\# \text{flops-per-iteration} \cdot \# \text{iterations})$ $= O(\# \text{flops}(SpMV) \cdot \# \text{iterations})$ $= O(\text{nnz}(A) \cdot \# \text{iterations})$ $= O(\text{nnz}(A) \cdot \text{cond}(A))$ for Poisson					

works for any diagonally dominant matrix

Gauss-Seidel	I	N^2 $(N^{5/3})$	N N	N $(N^{2/3})$	N N
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cost analysis like Jacobi, better constants
Works for any diagonally dominant
or s.p.d. matrix

Sparse Cholesky	D	$N^{3/2}$ (N^2)	$N \cdot \log N$ $(N^{4/3})$	$N^{1/2}$ $(N^{2/3})$	N $(N^{4/3})$
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assumes we use best reordering of
rows and columns (nested dissection)
 \Rightarrow bottleneck is dense Cholesky on
trailing dense submatrix
of size $n \times n$ in 2D, $n^2 \times n^2$ in 3D

Conjugate Gradients (CG)	I	$N^{3/2}$ $(N^{4/3})$	N N	$N^{1/2} \cdot \log N$ $(N^{1/3} \log N)$	N N
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flops = $O(\# \text{ flops-per-iteration} \cdot \# \text{ iterations})$
 $= O(\# \text{ flops}(SpMV) \cdot \sqrt{\text{cond}(A)})$
works on any s.p.d. matrix

SOR	I	$N^{3/2}$ $(N^{4/3})$	N N	$N^{1/2}$ $(N^{1/3})$	N N
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works on any s.p.d. matrix
steps depends on $\text{cond}(A)$
analogous cost analysis to CG

SSOR/ Chebyshev	I	$N^{5/4}$ $(N^{2/6})$	N N	$N^{1/4}$ $(N^{1/6})$	N N
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$$\# \text{ flops} = O(\text{cost}(SpMV) \cdot (\text{cond}(A))^{1/4})$$

need to know λ_{\max} and λ_{\min} ,
works for Poisson, any s.p.d. matrix

FFT	D	$N \cdot \log N$	N	$\log N$	N
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works for Poisson

BCR	D	$N \cdot \log N$	N	?	?
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slightly more general than FFT

Multigrid I	I	N	N	$\log^2 N$	N
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many variants beyond Poisson,
used for FEM, Elliptic PDEs etc

Lower Bound		N	N	$\log N$	
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