

Welcome to Ma 221! Lecture 8, Sep 11

Start using SVD and norms to analyze condition numbers for A^{-1} and solving $Ax=b$:

If A (or A and b) change a little, how much can A^{-1} (or $A^{-1}b$) change?

Scalar case: if $|x| < 1$, $\frac{1}{1-x} = \sum_{i=0}^{\infty} x^i = 1+x+x^2+\dots$

Matrix case: If for any operator norm $\|X\| < 1$ then $I-X$ invertible, $(I-X)^{-1} = \sum_{i=0}^{\infty} X^i = I+X+X^2+\dots$

$$\|(I-X)^{-1}\| \leq \frac{1}{1-\|X\|}$$

proof: claim: $I+X+X^2+\dots$ converges

$$\|X^i\| \leq \|X\|^i \rightarrow 0 \text{ as } i \rightarrow \infty$$

\Rightarrow each entry of $(I-X)^{-1} = I+X+X^2$

bounded by convergent geometric series

$$(I-X)(I+X+X^2+\dots+X^i) = I - \underbrace{X^{i+1}}_{\rightarrow 0 \text{ as } i \rightarrow \infty} \rightarrow I \text{ as } i \rightarrow \infty$$
$$\rightarrow (I-X)^{-1} \text{ as } i \rightarrow \infty$$

$$\begin{aligned} \|(I-X)^{-1}\| &= \|I+X+X^2+\dots\| \\ &\leq \|I\| + \|X\| + \|X^2\| + \dots \\ &\leq \|I\| + \|X\| + \|X\|^2 + \dots \\ &= 1 + \|X\| + \|X\|^2 + \dots \\ &= 1/(1-\|X\|) \end{aligned}$$

Generalizes to other matrix functions

$$\|e^X\| = \left\| \sum_{i=0}^{\infty} \frac{X^i}{i!} \right\| \leq e^{\|X\|}$$

Lemma: if A invertible

Then $A-E$ invertible if $\|E\| < \frac{1}{\|A^{-1}\|}$
in which case

$$(A-E)^{-1} = A^{-1} + A^{-1}(EA^{-1}) + A^{-1}(EA^{-1})^2 + \dots$$

$$\|(A-E)^{-1}\| \leq \frac{\|A^{-1}\|}{1 - \|E\| \cdot \|A^{-1}\|}$$

proof: $(A-E)^{-1} = ((I - EA^{-1})A^{-1})^{-1}$
 $= A^{-1} \underbrace{(I - EA^{-1})^{-1}}_X$ $\|X\| \leq \|E\| \cdot \|A^{-1}\| < 1$

$$(A-E)^{-1} = A^{-1} (I + X + X^2 + \dots)$$

$$= A^{-1} (I + EA^{-1} + (EA^{-1})^2 + \dots)$$

$$\|(A-E)^{-1}\| \leq \|A^{-1}\| \cdot \frac{1}{1 - \|E\| \cdot \|A^{-1}\|} \quad \text{QED}$$

How much can A^{-1} and $(A-E)^{-1}$ differ?

Lemma: $\|(A-E)^{-1} - A^{-1}\| \leq \frac{\|A^{-1}\|^2 \cdot \|E\|}{1 - \|E\| \cdot \|A^{-1}\|}$

proof: $(A-E)^{-1} - A^{-1} =$

$$A^{-1}(EA^{-1}) + A^{-1}(EA^{-1})^2 + \dots$$

$$= A^{-1}EA^{-1}(I + EA^{-1} + (EA^{-1})^2 + \dots)$$

Take norms

$$\|(A-E)^{-1} - A^{-1}\| \leq \frac{\|A^{-1}\|^2 \cdot \|E\|}{1 - \|E\| \cdot \|A^{-1}\|}$$

$$\underbrace{\frac{\|(A-E)^{-1} - A^{-1}\|}{\|A^{-1}\|}}_{\text{relative error in output}} \leq \frac{\|A^{-1}\| \cdot \|A\|}{1 - \frac{\|E\| \cdot \|A^{-1}\| \cdot \|A\|}} \underbrace{\frac{\|E\|}{\|A\|}}_{\text{relative error in input}}$$

$\kappa(A) = \frac{\|A^{-1}\| \cdot \|A\|}{1}$
 = condition number

Fact: $\kappa(A) \geq 1$

proof: $1 = \|\Sigma\| = \|A \cdot A^{-1}\| \leq \|A\| \cdot \|A^{-1}\| = \kappa(A)$

Thm: $\min \left\{ \frac{\|E\|}{\|A\|} : A-E \text{ singular} \right\} = \frac{1}{\kappa(A)}$

distance to singularity

proof: for $\|\cdot\|_2$ using SVD:

$\min \{ \|E\|_2 : A-E \text{ singular} \} = \sigma_{\min}(A)$

relative dist to singularity = $\frac{\sigma_{\min}(A)}{\|A\|_2}$

= $\frac{\sigma_{\min}(A)}{\sigma_{\max}(A)} = \frac{1}{\frac{\sigma_{\max}(A)}{\sigma_{\min}(A)}} = \frac{1}{\|A\| \cdot \|A^{-1}\|} = \frac{1}{\kappa(A)}$

Extend analysis solving $Ax=b$ vs $(A-E)\tilde{x} = b+f$
 $\tilde{x} = x + \delta x$, solve for δx

Subtract, solve for δx :

$$A \cdot \delta x - E x - E \cdot \delta x = f$$

$$(A-E)\delta x = f + E x$$

$$\delta x = (A-E)^{-1}(f + E x)$$

$$\|\delta x\| \leq \|(A-E)^{-1}\| \cdot (\|f\| + \|E x\|)$$

$$\begin{aligned} &\leq \frac{\|A^{-1}\| \cdot \|A\|}{1 - \|E\| \cdot \|A^{-1}\|} \left(\frac{\|r\|}{\|A\|} + \frac{\|E\| \|x\|}{\|A\|} \right) \\ \frac{\|\delta x\|}{\|x\|} &\leq \frac{\|A^{-1}\| \cdot \|A\|}{1 - \|E\| \cdot \|A^{-1}\|} \left(\frac{\|r\|}{\|A\| \cdot \|x\|} + \frac{\|E\|}{\|A\|} \right) \\ \text{rel change in } x & \\ &\leq \frac{\|A^{-1}\| \cdot \|A\|}{1 - \|E\| \cdot \|A^{-1}\|} \left(\frac{\|r\|}{\|b\|} + \frac{\|E\|}{\|A\|} \right) \\ \text{cond\#} & \quad \text{rel change in } b \quad \text{rel change in } A \end{aligned}$$

Goal of Backward Stability:

$$\frac{\|r\|}{\|b\|}, \frac{\|E\|}{\|A\|} = O(\epsilon) = O(\text{machine epsilon})$$

Practical Questions

given \hat{x} , what is backward error?

how big is $\|E\|$?

Compute residual $r = A\hat{x} - b$

$$r = A\hat{x} - Ax = A(\hat{x} - x) = A \cdot \text{error}$$

$$\|r\| \leq \|A^{-1}\| \cdot \|r\|$$

Thm: Smallest E in norm such that

$$(A+E)\hat{x} = b \quad \text{has norm } \frac{\|r\|}{\|\hat{x}\|}$$

$$\text{attainable: (2-norm)} \quad E = \frac{-r \cdot \hat{x}^T}{\|\hat{x}\|_2^2}$$

"proof:"

$$r = A\hat{x} - b = -E\hat{x}$$

$$\|r\| = \|E\hat{x}\| \leq \|E\| \cdot \|\hat{x}\| \Rightarrow \|E\| \geq \frac{\|r\|}{\|\hat{x}\|}$$

What if error bound too big:
take a few steps of Newton
but be careful about round off

Practical error bounds

$$\|A^{-1}\| = \max_{\|x\|=1} \|A^{-1}x\| = \max_{\|x\|\leq 1} \|A^{-1}x\|$$

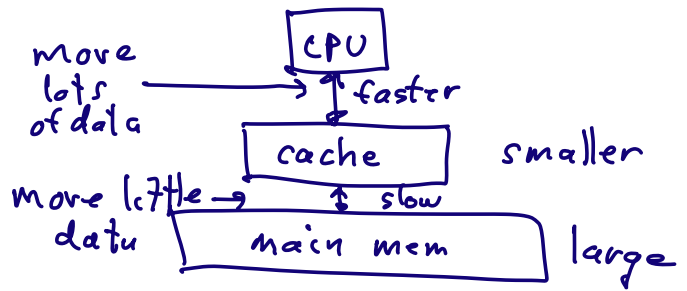
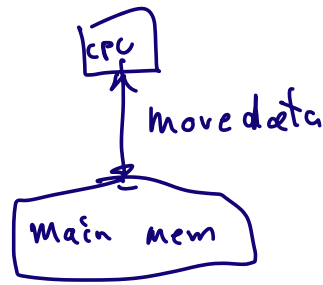
use gradient ascent "go uphill"
to maximize $\|A^{-1}x\|$ costs $O(n^2)$ per
step, $O(5)$ steps works in practice

Thm (D., Diament, Malojovich, 2009)
to estimate $\|A^{-1}\|$ with any
constant factor guaranteed,
costs as much as mat mul.

Goal: understanding real cost
in time (and energy) of running an alg.

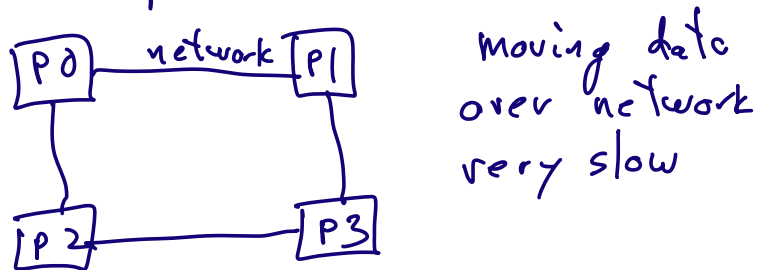
Traditionally: count flops,
but this is cheapest op.

Costs orders of magnitude more
to move data from where it is
stored to where you do arithmetic



Goal: minimize data movement between cache and main mem

Same idea in parallel



Notation: "minimize communication"

Matmul: Theorem: gives a lower bound on how much data needs to move between cache and main mem to do matmul: $n \times n$ matmul
cache size M

(Hong, Kung 1981) # words moved = $\Omega\left(\frac{n^3}{\sqrt{M}}\right)$

Widely used optimal algorithm attains bound

2004: extended to parallel case

2011: extended to all dense
linear alg: GE, LS, ...