

Welcome to Ma221! Lecture 7, Sep 8

$$\text{SVD: } A^{n \times n} = U \underset{\text{orthog}}{\Sigma} \underset{\text{diag}}{V^T} \underset{\text{orthog}}{U}$$

$$\begin{aligned} \text{"thin SVD"} A_{m \times n}^{m \times n} &= \boxed{A} = \boxed{\underset{m}{U_1} \mid \underset{n}{U_2}} \underset{m \times n}{\Sigma} \underset{n}{V^T} \\ &= \boxed{U_1} \boxed{\Sigma} \boxed{V^T} \end{aligned}$$

Fact 1: $A^{n \times n}$ non-sing.
can solve $Ax = b$ in $O(n^2)$ ops,
given SVD

$$\begin{aligned} A^{-1}b &= (U\Sigma V^T)^{-1}b \\ &= \underline{V(\Sigma^{-1}(U^T b))} \end{aligned}$$

Gaussian Elim cheaper
SVD gives "free" error bound

Fact 2: $m > n$ solve $\underset{x}{\operatorname{argmin}} \|Ax - b\|_2$

$$x = \underline{V\Sigma^{-1}U^T b} \quad \text{if } A \text{ full rank}$$

generalizes " A^{-1} " to rectangular
using "thin SVD" matrices

$$\text{Proof: } A = \hat{U} \hat{\Sigma} V^T \quad O = \begin{bmatrix} U & U' \\ 0 & m-n \end{bmatrix}_{m,n}$$

$$\begin{aligned}
\|Ax - b\|_2^2 &= \|(\hat{U} \hat{\Sigma} V^T)x - b\|_2^2 \\
&= \|\hat{U}^T (\cdot)\|_2^2 \\
&= \|\hat{\Sigma} V^T x - \hat{U}^T b\|_2^2 \\
&= \left\| \begin{bmatrix} \hat{\Sigma} \\ 0 \end{bmatrix} V^T x - \begin{bmatrix} U^T \\ U'^T \end{bmatrix} b \right\|_2^2 \\
&= \left\| \begin{bmatrix} V^T x - U^T b \\ 0 - U'^T b \end{bmatrix} \right\|_2^2 \\
&= \|V^T x - U^T b\|_2^2 + \|U'^T b\|_2^2 \\
&= \text{O} + \|U'^T b\|_2^2
\end{aligned}$$

if $x = V \hat{\Sigma}^{-1} U^T b$ QED

$$\text{Def: } A = \sum_{n \times n}^{m \times n} V^T \quad \text{full rank}$$

$$A^+ = V \hat{\Sigma}^{-1} U^T \quad \text{is}$$

Moore-Penrose pseudo inverse
`pinv(A)` in Matlab

All extends (LS and pinv) to
underdetermined case ($m < n$)
rank deficient

$$\text{regularized LS: } \underset{x}{\operatorname{argmin}} \|Ax - b\|_2^2 + \lambda^2 \|x\|_2^2$$

Q3.13 has more properties of A^+

Fact 3: $A = A^T$ real, with

$$\text{evals } \underline{\lambda} = \text{diag}(\lambda_1, \dots, \lambda_n)$$

$$\text{orthogonal evvecs } \underline{V} = [v(1), \dots, v(n)]$$

$$A = \underline{V} \underline{\lambda} \underline{V}^T \quad (A\underline{v} = \underline{\lambda} \underline{v}) \quad A\hat{v}(i) = \lambda_i v(i)$$

$$= SVD \text{ if all } \lambda_i \geq 0$$

$$\text{otherwise: } A = (\underline{V} \underline{D} \underline{U}^T) \underline{V}^T = SVD$$

$$\underline{D} = \text{diag}(\text{sign}(\lambda_i))$$

Fact 4: using SVD:

$$\begin{aligned} \square &= A^T A = (\underline{U} \underline{\Sigma} \underline{V}^T)^T (\underline{U} \underline{\Sigma} \underline{V}^T) && \text{only need} \\ &\quad \square \quad \square = \underline{V} \underline{\Sigma}^T \underbrace{\underline{U}^T}_{\text{I}} \underline{U} \underline{\Sigma} \underline{V}^T && \text{thin SVD} \\ &= \underline{V} \underline{\Sigma}^T \underline{\Sigma} \underline{V}^T = \square \times \square && \square \square = \square \\ &= \text{eigen decomp of } A^T A \end{aligned}$$

Fact 5: $A A^T = (\underline{U} \underline{\Sigma} \underline{V}^T) (\underline{U} \underline{\Sigma} \underline{V}^T)^T$

$$\begin{aligned} &= \underline{U} \underline{\Sigma} \underbrace{\underline{V}^T}_{\text{I}} \underline{V} \underline{\Sigma}^T \underline{U}^T \\ &= \underline{U} \underline{\Sigma} \underline{\Sigma}^T \underline{U}^T = \square \square \square = \begin{matrix} \underline{U} & \underline{\Sigma} & \underline{U}^T \\ \text{orthog} & \text{diag} & \text{orthog} \end{matrix} \end{aligned}$$

$$\text{Fact 6: } H = \begin{bmatrix} 0 & A^T \\ A & 0 \end{bmatrix} = H^T \quad \cdot m+n \times m+n$$

H has evals $\pm \sigma_i$ of A

$$\text{evvecs } \frac{1}{\sqrt{2}} \begin{bmatrix} v(i) \\ \pm u(i) \end{bmatrix}$$

\Rightarrow algs for sym eigen problem closely related to eigs for SVD

Fact 7: $\|A\|_2 = \|\mathbf{U}\Sigma\mathbf{V}^T\|_2 = \|\Sigma\|_2 = \sigma_1$,
 $\|A^{-1}\|_2 = \|\mathbf{V}\Sigma^{-1}\mathbf{U}^T\|_2 = \|\Sigma^{-1}\|_2 = \frac{1}{\sigma_n}$
 $\sigma_1 \geq \dots \geq \sigma_n > 0$

Def: $\kappa(A) = \frac{\sigma_1}{\sigma_n} = \text{condition number of } A$

Fact 8: Let S be the unit sphere in \mathbb{R}^n

then $A \cdot S$ is an ellipsoid centered at 0

with principal axes v_i , length σ_i

proof: $S = [s_1, \dots, s_n] \quad \|S\|_2 = 1$

$$AS = \mathbf{U}\underbrace{\Sigma\mathbf{V}^T}_\text{unit} S = \mathbf{U}\Sigma\hat{S} = \sum_i \hat{s}_i \underbrace{U_i(\sigma_i \hat{s}_i)}_{\text{ellipsoid}}$$

$$U_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad U_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad AS = \begin{bmatrix} \sigma_1 \hat{s}_1 \\ \sigma_2 \hat{s}_2 \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad \left(\frac{x}{\sigma_1}\right)^2 + \left(\frac{y}{\sigma_2}\right)^2 = \frac{\hat{s}_1^2}{\sigma_1^2} + \frac{\hat{s}_2^2}{\sigma_2^2} = 1$$

Fact 9: Suppose

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0 = \sigma_{r+1} = \dots = \sigma_n$$

$$\Rightarrow \text{rank}(A) = r$$

null space = $\text{span}(v_{r+1}, v_{r+2}, \dots, v_n)$

range space = $\text{span}(v_1, \dots, v_r)$

$$Ax = \mathbf{U}\Sigma\mathbf{V}^T x = \sum_{i=1}^r v_i \sigma_i (\underline{v_i^T x})$$

Fact 10: Matrix A_k of rank k

closest to A in 2-norm is

$$A_k = \sum_{i=1}^k v_i \sigma_i v_i^T = U \underbrace{\Sigma_k}_{\Sigma_k = \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_k & 0 & \cdots & 0 \end{bmatrix}} V^T$$

$$\Sigma_k = \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_k & 0 & \cdots & 0 \end{bmatrix}$$

$$\|A - A_k\|_2 = \sigma_{k+1}$$

In particular, closest non-full rank matrix to A is at distance $\sigma_n = \sigma_{\min}$

$$\text{recall } \|A^\perp\|_2 = \frac{1}{\sigma_{\min}}$$

Proof: Easy: A_k has rank k ✓

and right distance from A :

$$\|A - A_k\|_2 = \left\| \sum_{i=k+1}^n v_i \sigma_i v_i^T \right\| = \sigma_{k+1}$$

SRD of $A - A_k$

Suppose B has rank k ,

need to show $\|A - B\|_2 \geq \sigma_{k+1}$

nullspace of B has dimension $n-k$

space spanned by $\{v_1, \dots, v_{k+1}\}$ has dim $k+1$

$\text{nullspace}(B) \cap \text{span}\{v_1, \dots, v_{k+1}\} \neq \{0\}$

$$\dim = n-k + \dim = k+1 = n+1$$

these two spaces intersect, $\|h\|_2 = 1$

$$\|A - B\|_2 \geq \|(A - B)h\|_2 = \|Ah\|_2 \text{ since } Bh = 0$$

$$= \left\| U \underbrace{\Sigma_k}_{X} V^T h \right\|_2 \quad X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{k+1} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$= \|\Sigma x\|_2 = \left\| \begin{bmatrix} \sigma_1 x_1 \\ \sigma_2 x_2 \\ \vdots \\ \sigma_{k+1} x_{k+1} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right\|_2 \geq \sigma_{k+1} \|x\|_2 = \sigma_{k+1}$$

QED

Start using SVD norms to analyze condition number for A^{-1} and for solving $Ax = b$.
 if A (and b) change "a little" how much can A^{-1} (and $A^{-1}b$) change?

If $|x| < 1$, $\frac{1}{1-x} = 1 + x + x^2 + \dots$

Generalize to matrices:

Lemma: If $\|X\| < 1$ any operator norm

then $I - X$ nonsingular:

$$(I - X)^{-1} = \sum_{c=0}^{\infty} X^c \quad \| (I - X)^{-1} \| \leq \frac{1}{1 - \|X\|}$$