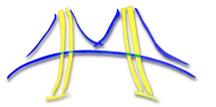




Symmetric Eigenvalue Problem: Reduction to Tridiagonal

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Symmetric Eigenvalue Problem

- Eigenvalues and eigenvectors are usually computed via two steps [Dem97]
 - Reduction of the matrix to tridiagonal form using two-sided orthogonal transformations
 - Solve eigenproblem on tridiagonal matrix (e.g. QR iteration, divide-and-conquer)
 - Eigenvalues of tridiagonal matrix are the same as the original matrix
 - Eigenvectors of tridiagonal matrix are transformations of those of the original matrix
- The bulk of the work (and communication) of the entire algorithm occurs in the reduction to tridiagonal step
- In this project, we assume that only the eigenvalues of the matrix are desired

Single Step vs. Multistep Reduction Algorithms

Utilizing BLAS 3

- Naive approach (column-by-column) is completely BLAS 2
- Single step reduction: LAPACK approach does multiple trailing matrix updates at once
 - column panel reduction still BLAS 2
 - trailing matrix update becomes BLAS 3
- Multistep reduction: first reduce full matrix to banded (phase 1), then reduce banded matrix to tridiagonal (phase 2)
 - phase 1 performs QR on column panels (entirely BLAS 3)
 - phase 2 requires "chasing the bulge"

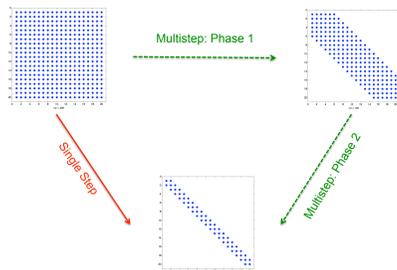


Figure 1: Single step and multistep reduction paths.

Algorithm 1: full→tridiagonal

Input: A is symmetric $n \times n$ matrix

- for $i = 1$ to n **step** b **do**
- for $j = i$ to $i + b - 1$ **do**
- Reduce column j to tridiagonal
- Update columns $j + 1$ to $i + b - 1$
- ▷ store Householder vector info
- end for**
- Update trailing submatrix
- end for**

Output: A is symmetric tridiagonal with same eigenvalues

Algorithm 2: full→banded

Input: A is symmetric $n \times n$ matrix

- for $i = 1$ to $n - b$ **step** b **do**
- Reduce $A(i + b : n, i : i + b)$ to upper triangular
- ▷ Use TSQR
- Update trailing submatrix
- end for**

Output: A is symmetric banded (bandwidth b) with same eigenvalues

"Chasing the Bulge" [BLS00b]

- Different data-structures and algorithms are used to reduce banded matrix to tridiagonal
- Large design space, but general idea consists of repeatedly
 - annihilating one or several elements, and
 - bulge chasing to restore the banded form
- Parameters include number of elements/bands to annihilate at a time and how much of the bulge to chase
 - tradeoffs between extra flops/storage and performance

Current Performance

Sequential Performance

- Multistep reduction outperforms single step reduction for $N \geq 1200$
 - BLAS 2 computation in single step kills performance when the problem no longer fits in L2 cache (6 MB)
 - Multistep incurs overhead in extra computation and repacking the matrix into banded form
- Intermediate bandwidth for multistep is tunable parameter ($b = 64$ generally performs well for large matrices)

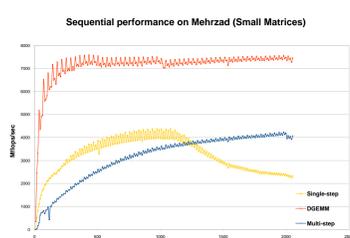


Figure 2: Sequential performance for small matrices.

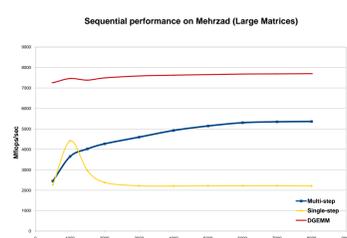


Figure 3: Sequential performance for large matrices.

Multithreaded Performance

- Multistep outperforms single step for $N \geq 3000$
- More L2 cache is available in multi-threaded mode
- All measurements were taken using 8 threads
- Large performance gap compared to DGEMM

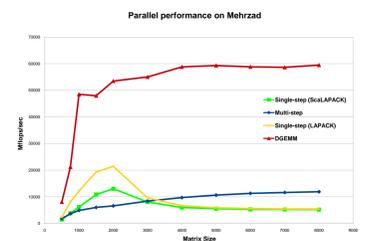


Figure 4: Parallel performance for large matrices.

Processor Architecture

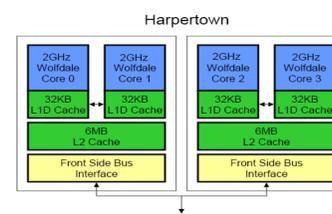


Figure 5: Processor architecture.

- All performance data was gathered on "Mehrzad"
- 2 quad-core Intel Xeon E5405 (Harpertown) processors
 - 2x6 MB L2 cache on each chip
 - 32 KB L1 cache for each core
 - 2.0 GHz sequential peak performance

Our Goal: Optimizing Reduction to Banded

Coarse-grain data flow model

- We will use the coarse-grain approach of "algorithms-by-tiles" or "algorithms-by-blocks" (see [CVZB⁺08], [LKD09])
 - matrix blocks become fundamental units of data, operations on blocks become fundamental (sequential) computations (matrix is stored in contiguous blocks)
 - static or dynamic scheduling and out-of-order execution determined by block computation DAG

Successive Band Reduction (SBR) toolbox [BLS00a]

- The SBR toolbox contains Fortran routines which supplement LAPACK and include
 - full to banded, banded to narrower banded, and banded to tridiagonal reductions
 - repacking routines to convert between full and banded storage schemes
- Most of the running time is spent in the full to banded reduction routine
 - for $N = 2048, b = 32$, 83% of time is spent in reduction to banded (in sequential case)
- Optimizing banded to tridiagonal reduction for multi-core is an open problem

SMP Superscalar (SMPSs) framework [Bar08]

- We have chosen to use the SMPSs framework in which
 - the programmer identifies atomic tasks and specifies input/output dependencies
 - a runtime library schedules tasks to cores based on computation DAG
- SMPSs scheduling performed almost as well as handwritten static scheduling for LU, QR, Cholesky [KLD⁺09]
- SMPSs scheduling performed as well as handwritten dynamic and handwritten static scheduling of Hessenberg and bidiagonal reductions (just to banded form) [LKD09]
 - Hessenberg reduction becomes tridiagonal reduction in the symmetric case

References

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