Adaptive Approaches to Relieving Broadcast Storms in a Wireless Multihop Mobile Ad Hoc Network*

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Abstract: In a multihop mobile ad hoc network, broadcasting is an elementary operation to support many applications. In [15], it is shown that naively broadcasting by flooding may cause serious redundancy, contention, and collision in the network, which we refer to as the broadcast storm problem. Several threshold-based schemes are shown to perform better than flooding in [15]. However, how to choose thresholds also poses a dilemma between reachability and efficiency under different host densities. In this paper, we propose several adaptive schemes, which can dynamically adjust thresholds based on local connectivity information. Simulation results show that these adaptive schemes can offer better reachability as well as efficiency as compared to the results in [15].

1 Introduction

The mobile ad hoc network (MANET) distinguishes itself from traditional wireless networks by its dynamic changing topology, no base-station support, and multihop communication capability. In a MANET, a mobile host is free to move around and may communicate with other hosts at anytime. When a communicating partner is within a host's radio coverage, they can communicate directly in a single-hop fashion. Otherwise, a route consisting of several relaying hosts is needed to forward messages from the source to the destination in a multihop fashion. To support multihop communication in a MANET, a mobile host has to work as a router and cooperate with other hosts to find routes and relay messages. Routing has been studied intensively under a MANET environment (e.g., unicast [2, 3, 6, 8, 9, 10, 13, 18], multicast [4, 7], and geocast [11]). A working group called "manet" has been formed in the Internet Engineering Task Force (IETF) to stimulate research in MANET [5, 14]. Applications of MANETs appear in places where fixed network infrastructures are difficult to build (e.g., fleets in the ocean, air fighters in the sky, and soldiers in march) or unavailable (e.g., rescue scenes, and archaeological or ecological surveys).

In this paper, we study the broadcasting problem in a MANET. Broadcasting is a fundamental operation in all kinds of network; it may be used for discovering neighbors, collecting global information, naming, addressing, and sometimes helping multicasting. In a MANET particularly, several routing protocols [2, 8, 9, 10, 18] have relied on broadcasting to propagate routing-related information (e.g., the request for a new route to a destination). In most networks (including MANET), a common approach is to broadcast by flooding. While most existing works on MANET taking flooding as a straightforward and direct solution, we show in [15] that a blind flooding may result in excessive redundancy, contention, and collision. These may lead to lower reachability (to the potential receiving hosts) and longer latency (for the broadcast to complete). (More discussion on this is in Section 2.) We thus refer to this scenario the broadcast storm problem.

To alleviate the broadcast storm, one should inhibit redundant rebroadcasts of the broadcast packet and differentiate the timing of rebroadcasts. Following this guideline, several schemes, called the counter-based, distance-based, and location-based schemes, were proposed in [15]. These schemes rely on various threshold mechanisms help a mobile host to assert the redundancy of a rebroadcast and decide whether to rebroadcast or not. Results did show that these schemes can effectively relieve the broadcast storm problem by delivering better reachability and lower latency as compared to flooding.

One problem associated with the above threshold-based schemes [15] is that the threshold which is used is a given constant. Given a fixed host density, we can easily determine a best threshold to use. However, since the topology of a MANET may change dynamically and quickly, it is desirable to be able to adjust the threshold on-the-fly. This is what motivates this paper. In this paper, we propose three dynamic solutions, called adaptive counter-based, adaptive location-based, and neighbor coverage schemes. These schemes all take local connectivity information into account. The first two schemes dynamically choose their threshold values according to a host's number of neighbors. The last scheme applies two-hop neighborhood information to decide whether a rebroadcast is necessary or not.

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Through simulations we justify that these schemes can further improve those schemes in [15]. Since the neighbor coverage scheme relies on the accuracy of neighborhood information, we also study the relationship between host mobility and the interval for a host to send a hello packet to announce its existence (which we call hello interval). Toward this goal, we propose a dynamic scheme to adjust a host’s hello interval based on the variation of its neighborhood. We verify that this can reduce unnecessary hello packets and yet still provide up-to-date neighborhood information.

The rest of this paper is organized as follows. Section 2 discusses the broadcast storm problem, and reviews some solutions to relieve the storm. Our adaptive schemes are proposed in Section 3. Simulation results are shown in Section 4. Conclusions are drawn in Section 5.

2 Preliminaries
In this paper, we consider a MANET consisting of a set of cooperating mobile hosts each equipped with a CSMA/CA transceiver which can access the air medium following a IEEE 802.11-like protocol [12].

2.1 Broadcasting in a MANET
Broadcasting refers to how a broadcast packet is propagated throughout the whole network. Any source host in the MANET can initiate a broadcast packet. All other hosts have responsibility to help propagating the packet by rebroadcasting it. Attempt should be made to distribute the packet to as many hosts as possible without paying too much effort. The broadcast problem considered here is assumed to have the following characteristics [15].

- The broadcasting is spontaneous. Any mobile host can issue a broadcast operation at any time. No global knowledge of network topology or synchronization is assumed. Little or no local connectivity information may be collected in advance.

- The broadcasting is unreliable. A broadcast message is transmitted in a CSMA/CA manner. No acknowledging mechanism will be used. Note that in the IEEE 802.11 [12], the MAC specification does not allow acknowledging on receiving a broadcast transmission. After receiving a broadcast packet, a host may rebroadcast the message at most once. A broadcast message should not be stored for a fault-tolerance purpose.

In addition, we assume that a host can detect duplicate broadcast packets. This is essential to prevent endless flooding of the packet. One way to do so is to associate with each broadcast packet a tuple (source ID, sequence number) as that in [2, 18].

The motivations to solve unreliable broadcast are (i) a host may miss a broadcast message because it is off-line, it is temporarily isolated from the network, or it experiences successive collisions, (ii) acknowledgements may cause serious medium contention (and thus another “storm”) surrounding the sender, and (iii) in many applications (e.g., the route discovery in [2, 8, 9, 10, 18]), a 100% reliable broadcast is unnecessary. However, we remark that reliable broadcasting has also been studied [1, 16, 17], whose goal is to ensure all hosts receive a broadcast message. A lot of high-level acknowledgements between hosts are exchanged. Such protocols are typically accomplished at the application layer and is out of the scope of this paper (however, the result in this paper may serve as an underlying facility to implement reliable broadcast).

Finally, we comment that we do not confine ourselves to broadcasting the same packet. What we focus on in this paper is the packet propagation behavior in a MANET — the phenomenon where the transmission of a packet will trigger other surrounding hosts to transmit the same (or modified) packet. We shall show that if flooding is used blindly, many redundant packets will be sent and serious contention/collision will be incurred. Our goal is to solve broadcast with efficiency in mind.

2.2 The Broadcast Storm Problem
A straight-forward approach to perform broadcast is by flooding. A host, on receiving a broadcast packet for the first time, has the obligation to rebroadcast the packet. Clearly, this costs transmissions in a MANET of n hosts. In a CSMA/CA network, drawbacks of flooding include:

- Redundancy: When a mobile host decides to rebroadcast a broadcast packet to its neighbors, all of its neighbors might already have heard the packet.

- Contention: After a mobile host broadcasts a packet, if many of its neighbors decide to rebroadcast the packet, these transmissions (which are all from nearby hosts) may severely contend with each other.

- Collision: Because of the deficiency of backoff mechanism, the lack of RTS/CTS dialogue, and the absence of collision detection, collisions are more likely to occur and cause more damage.

Collectively, we refer to the above phenomena as the broadcast storm problem. More details can be found in [15].

2.2.1 Redundancy
The main reason for redundancy is that radio signals from different transceivers may overlap with each other seriously. Assuming that the area that can be covered by an transceiver forms a circle with a radius r. Let INTCD(d) be the intersection area of two circles of radius r whose centers are distance by d. On hearing a packet for the first time, the additional coverage provided by a host to rebroadcast the packet is \( \pi r^2 - INTCD(d) \).

When \( d = r \), the additional coverage is largest, which is about 0.61\( \pi r^2 \). That is to say, a rebroadcast can provide only 0 ~ 61% additional coverage over that already covered by the previous transmission. Also, let a rebroadcasting host randomly locate within a transmitter’s coverage. Through some calculus, we can determine the average additional coverage to be 0.41\( \pi r^2 \).

Let EAC(k) denote the expected additional coverage provided by a host’s rebroadcast after the host has heard the same broadcast packet k times. Fig. 1 shows our simulation result.

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1For instance, the routing protocols in [2, 8, 10, 18] rely on broadcasting a UDP packet called route request to search for a route from a source to a particular destination. When propagating such a request, a host generally appends its ID to the request so that appropriate routing information can be collected.
As can be seen, when \( k \geq 4 \), the expected additional coverage is below 5%.

2.3 Review of Some Efficient Broadcasting Schemes

To alleviate the broadcast storm problem, reference [15] suggests two directions: to inhibit redundant rebroadcasts and to differentiate the timing of rebroadcasts. Following these directions, a series of threshold-based broadcasting schemes were proposed in [15]. Below, we review two representative schemes: counter-based scheme and location-based schemes.

2.3.1 Counter-Based Scheme

From the analysis of redundancy in Section 2.2.1, we see that the more times a host has heard the same broadcast packet, the less additional coverage the host will provide if it rebroadcasts the packet. This can be seen from the descending trend of EAC(\( k \)) as \( k \) increases. In the counter-based scheme, a counter \( c \) that records the number of times a host has received the same broadcast packet is maintained by each host for each broadcast packet. When \( c \) reaches a predefined threshold \( C \), we inhibit the host from rebroadcasting this packet because the benefit (the additional coverage) could be low. It was shown in [15] that a threshold \( C \) of 3 or 4 can save many rebroadcasts in a dense network while achieving a reachability better or comparable to that of flooding. A larger threshold of \( C > 6 \) will provide less saving in a sparse network but behave almost like flooding.

2.3.2 Location-Based Scheme

In the location-based scheme, it is assumed that each host is equipped with a positioning device such as GPS. Thus, a receiver can accurately calculate the additional coverage that it can offer from the location(s) of the source(s) from which it heard the broadcast packet. A predefined threshold \( A \) is used to determine whether the receiving host should rebroadcast or not. Since more accurate information is used, the location-based scheme can achieve better performance in terms of both reachability and the amount of saving than that counter-based scheme.

3 Adaptive Broadcasting Schemes

As reviewed earlier, reducing the number of redundant rebroadcasts is our primary means to alleviating the broadcast storm. However, one problem with the schemes in [15] is that the threshold used is a predefined fixed value. This in fact poses a dilemma between reachability and the amount of saving on rebroadcasts as the host distribution of the MANET changes. It is desirable if a host can dynamically adjust its threshold value on-the-fly. In this section, we propose three adaptive schemes to resolve such dilemma. Consistently in each scheme, a host will decide whether to rebroadcast a broadcast packet or not based on its local neighborhood information.

3.1 Adaptive Counter-Based Scheme

The counter-based scheme in [15] uses a fixed threshold \( C \) to inhibit redundant rebroadcasts. If a host already heard the same broadcast packet more than \( C \) times, the host will not rebroadcast the packet because it is unlikely that the rebroadcast will provide anything new to its neighborhood. According to [15], the counter-based scheme does provide significant saving when a small threshold (such as \( C = 2 \)) is used. Unfortunately, the reachability will degrade sharply in a sparse network. Increasing the value of \( C \) will improve the reachability, but once again the amount of saving will be sacrificed.

To resolve the dilemma between reachability and saving, we propose an adaptive counter-based scheme, in which each individual host can dynamically adjust its threshold \( C \) based on its neighborhood status. Specifically, we will extend the fixed threshold \( C \) into a function \( C(n) \), where \( n \) is the number of neighbors of the host under consideration. Thus, each host will use a threshold \( C(n) \) depending on its current value of \( n \) to determine whether to rebroadcast or not. Each host now executes the following steps.

S1. On hearing a broadcast packet \( P \) for the first time, the host initializes a local counter \( c = 1 \). In S2, if \( P \) is heard again, interrupt the waiting and perform S4.

S2. Wait for a random number (0 \( \sim \) 31) of slots. Then submit \( P \) for transmission and wait until the transmission actually starts.

S3. Packet \( P \) is on the air. The procedure exits.

S4. Increase \( c \) by one. If \( c < C(n) \), resume the interrupted waiting in S2. Otherwise, proceed to S5.

S5. Cancel the transmission of \( P \) if it was submitted in S2. The host is inhibited from rebroadcasting \( P \) in the future. Then the procedure exits.

The function \( C(n) \) is undefined yet. To give some intuition, we make two observations below.

Obs. 1: When a host has very few neighbors, rebroadcasting a broadcast packet is relatively more important for two reasons. First, the redundancy of its rebroadcast is lower because the host is responsible for covering a larger area. This also costs less because there will be less contention. Second, the host is more likely to be located in a critical position (e.g., an articulation point). Inhibiting its rebroadcast may cause a large part of the network to not receiving the broadcast packet.

Obs. 2: If the neighborhood of a host is crowded enough, we can concentrate more on saving because using a loose threshold will not sacrifice the reachability, but may save many re-broadcasts (and thus alleviate the contention and collision problems).

Intuitively, when \( n \) is small, we should use a higher counter threshold because we expect a host to rebroadcast according to Obs. 1. On the other hand, Obs. 2 suggests that saving is getting more and more important when \( n \) increases. The dashed line in Fig. 2 suggests an abstract curve for \( C(n) \) based the above...
observations. It is roughly inversely proportional to the value of \( n \).

However, the solid line in Fig. 2 shows the actual shape of \( C(n) \) we are about to use for this scheme. The main difference from the dotted line is before the point \( n_1 \). Intuitively, this represents the range where we expect a host to rebroadcast. But a host with \( n \) neighbors is unlikely to hear the same broadcast packet more than \( n \) times. So a better way is to let \( C(n) = n + 1 \) (a \( C(n) \) too large would be too strong). After \( n \geq n_2 \), it is unreasonable to completely prohibit rebroadcasting, so we use the lowest possible threshold \( C(n) = 2 \). In Section 4.1, we will derive the exact shape of function \( C(n) \) through experiments.

Finally, we comment that there should be a neighbor discovery mechanism running at each host to estimate its current \( n \). This can be simply achieved by having each host send a HELLO packet periodically. Such information may be readily available from other protocols (e.g., the routing protocols in [6, 10, 18] all send HELLO periodically).

### 3.2 Adaptive Location-Based Scheme

The location-based scheme is shown to outperform the counter-based scheme in [15]. However, using a fixed threshold, the scheme still has a dilemma between reachability and saving, especially in a sparse network. In this section, we further extend the location-based scheme to an adaptive one. Specifically, we will extend the fixed threshold \( A(n) \) to a function \( A(n) \), where \( n \) is the number of neighbors of the host under consideration. A host will choose its threshold \( A(n) \) based on its current value of \( n \) to determine whether to rebroadcast or not. The detailed scheme is spelled out below.

- **S1.** On hearing a broadcast packet \( P \) for the first time, the host initializes \( ac \) to be the additional coverage provided by its rebroadcast based on the sender's location. If \( ac < A(n) \), proceed to S3. In S2, if \( P \) is heard again, interrupt the waiting and perform S4.
- **S2.** Wait for a random number (0 ~ 31) of slots. Then submit \( P \) for transmission and wait until the transmission actually starts.
- **S3.** Packet \( P \) is on the air. The procedure exits.
- **S4.** Update \( ac \). If \( ac < A(n) \), proceed to S3. Otherwise, resume the interrupted waiting in S2.
- **S5.** Cancel the transmission of \( P \) if it was submitted in S2. The host is inhibited from rebroadcasting \( P \) in the future. Then the procedure exits.

Following Obs. 1 and 2, Fig. 3 draws an abstract shape of \( A(n) \). With few neighbors (\( n \leq n_1 \)), we should use a threshold \( A(n) = 0 \) to enforce a host to rebroadcast. Between \( n_1 \) and \( n_2 \), the threshold should gradually increase to balance saving and reachability. After \( n \geq n_2 \), a threshold \( A(n) = EAC(2)/πr^2 = 0.187 \) is used. Intuitively, this is the expected additional coverage after a host received the same broadcast packet twice (recall the counter-based scheme). In Section 4.2, we will derive the exact shape of function \( A(n) \) through experiments.

### 3.3 Neighbor-Coverage Scheme

Although the location-based/adaptive location-based schemes can perform quite well, they are based on a stronger assumption that each mobile host is equipped with a positioning device. In this section we propose a neighbor-coverage scheme that does not count on positioning devices, but on more accurate neighborhood information.

For each host \( x \) in the MANET, the following sets are maintained:
- \( N_x \): the set neighbors of \( x \).
- \( N_{x,h} \): the set of neighbors of \( h \) known by host \( x \), where \( h \in N_x \).

The first set can be obtained by having each host broadcasting a HELLO packet periodically. The second set can be obtained by having host \( h \) append its set \( N_h \) to its HELLO packet. Note that these sets may not be completely accurate depending on host's mobility. We also remark that such information is readily available in some routing protocols, such as CBRP (Cluster Based Routing Protocol [10]) or ZRP (Zone Routing Protocol [8]).

The basic idea of this scheme is as follows. Host \( x \) will be allowed to rebroadcast a broadcast packet only if it believes that there exists at least one neighbor \( h \in N_x \) who may not have received the packet yet. This is achieved by keeping track of a set \( T \) containing the pending hosts in \( x \)'s neighborhood who have not received the broadcast packet. Whenever a broadcast packet from a host, say \( h \), is received, the set \( N_{x,h} \) is subtracted from \( T \). Once \( T \) becomes empty, host \( x \)'s rebroadcast will be inhibited. More formally, each host runs the following steps:

- **S1.** On a host \( x \) hearing a broadcast packet \( P \) for the first time, it initializes its set \( T = N_x - N_{x,h} - \{h\} \), where \( h \) is the host from which the packet was received. If \( T = \emptyset \), proceed to S5. In S2, if packet \( P \) is heard again, interrupt the waiting and perform S4.
- **S2.** Wait for a random number of slots. Then submit \( P \) for transmission and wait until the transmission actually starts.
S3. Packet $P$ is on the air. The procedure exits.

S4. Let $h$ be the host from which the same $P$ is heard again. Update $T = T - N_{s,A} - \{h\}$. If $T = \emptyset$, proceed to S5. Otherwise, resume the interrupted waiting in S2.

S5. Cancel the transmission of $P$ that was submitted in S2. The host is inhibited from rebroadcasting $P$ in the future. Then the procedure exits.

4 Performance Simulations

To test our new schemes, we developed a simulator using C++. Central to the simulator is a discrete event-driven engine designed to simulate systems that can be modeled by processes communicating through signals. The MAC specification in IEEE 802.11 Standard is followed to simulate the CSMA/CA behavior among hosts.

The fixed parameters in our simulations are the transmission radius of an transceiver (500 meters), the broadcast packet size (280 bytes), the transmission rate (1M bits per second), and the DSSS physical layer timing (PLCP overhead, slot time, inter-frame spacing, backoff window size, etc., as suggested in IEEE 802.11).

In each simulation, 100 mobile hosts in a geometric area called a map are simulated. 10,000 broadcast requests are simulated in each simulation with an arrival rate of one broadcast per second to the whole map, and the broadcasting host is randomly picked for each request. To simulate sparse and dense host distributions, a map can be of size $1 \times 1, 3 \times 3, 5 \times 5, 7 \times 7, 9 \times 9, 11 \times 11$, where a unit is of length 500 meters (the transmission radius). Each host will roam around randomly in the map during the simulation. The roaming pattern of each host consists of a series of turns. In each turn, the direction, speed, and time interval are randomly generated. The direction is uniformly distributed from $0^\circ$ to $360^\circ$, the time interval from 1 to 100 seconds, and the speed from 0 to a given maximum speed. Unless otherwise specified, the maximum speed is 10 km/hour in the $1 \times 1$ map, 30 km/hour $3 \times 3$ map, 50 km/hour $5 \times 5$ map, etc. Intuitively, this is to make a host to move through a wider range in a larger map.

The performance metrics to be observed are:

- **Reachability (RE):** $r/e$, where $r$ is the number of hosts receiving the broadcast packet, and $e$ is the number of mobile hosts that are reachable, directly or indirectly, from the source host at the moment when the broadcast is taken.

- **Saved ReBroadcast (SRB):** $\frac{(r-t)}{t}$, where $r$ is the number of hosts receiving the broadcast packet, and $t$ is the number of hosts actually rebroadcasting the packet.

- **Average latency:** the interval from the time the broadcast being initiated to the time the last host finishing its rebroadcasting or deciding not to rebroadcast.

In this paper, we take RE as the primary goal. In the following, we first discuss each scheme separately. At last, an overall comparison will be given.

\footnote{This is to take network partitioning into account.}

![Figure 4: Tuning the threshold function $C(n)$ for the adaptive counter-based scheme: (a) determining the slope before $n_1$, (b) determining the value of $n_2$, (c) determining the value of $n_3$, and (d) tuning the thresholds between $n_1$ and $n_2$. RE (reachability) is shown in lines, and SRB (saved rebroadcast) in bars. The thresholds used are represented by a sequence $x_1 x_2 x_3 \ldots$, i.e., $C(1) = x_1, C(2) = x_2, C(3) = x_3$, etc.}

4.1 Performance of the Adaptive Counter-Based Scheme

In the following, we first present how we determine the best threshold function $C(n)$. Then we compare our adaptive counter-based scheme to the fixed-threshold counter-based scheme.

Fig. 2 already gives an abstract shape of $C(n)$. Let's denote the thresholds by a sequence of integers, $x_1 x_2 x_3 \ldots$, i.e., $C(1) = x_1, C(2) = x_2, C(3) = x_3$, etc. The way we determine the best $C(n)$ is in fact through extensive simulations and refinements. The steps are outlined below.

1. **Determine the slope before $n \leq n_1$.** As discussed earlier, before $n_1$ we should enforce a host to rebroadcast. We compare three sequences: $C(n) = 2223354455555 \ldots$ (slope = 1/3), $C(n) = 22334455555 \ldots$ (slope = 1/2), and $C(n) = 234555555 \ldots$ (slope = 1). Fig. 4(a) shows that the reachability of $C(n) = 234555555 \ldots$ is the best in sparser maps ($7 \times 7, 9 \times 9, 11 \times 11$). This justifies our **Obs. 1** that enforcing a host to rebroadcast is essential to improve reachability in sparser networks. The next question is: to what extent should we enforce rebroadcasting?

2. **Determine the value of $n_1$.** We use the function $C(n) = \frac{n+1}{2}$ when $n \leq n_1$, and $C(n) = n_1 + 1$ when $n > n_1$.
Figure 5: The functions used to tune $C(n)$ between $n_1$ and $n_2$ for the adaptive counter-based scheme.

by varying the value of $n_1$. In Fig. 4(b), four functions are tested: $C(n) = 233 \ldots$, $C(n) = 2344 \ldots$, $C(n) = 23455 \ldots$, and $C(n) = 234566 \ldots$. The results indicate that $n_1 = 4$ and $n_2$ both give satisfactory reachability. By further taking SRB into consideration, using $n_1 = 4$ will give better saving.

3. Determine the value of $n_2$. As discussed earlier, after $n_2$ we should use the smallest possible threshold of 2. To find the best $n_2$, we fix $n_1$ at 4, vary $n_2$ (= 8, 12, or 16), and let $C(n)$ linearly decrease between $n_1$ and $n_2$. From the results in Fig. 4(c), we see that setting $n_2 = 12$ gives better reachability and saving. In particular, $n_2 = 12$ gives the best reachability at sparse networks.

4. Tune the thresholds between $n_1$ and $n_2$. We already know that the threshold should gradually decrease from $n_1$ to $n_2$. As a final step, we try different decreasing functions for this range, as shown in Fig. 5, by letting $n_1 = 4$ and $n_2 = 12$. The results are shown in Fig. 4(d).

From the above steps, we suggest that the solid line in Fig. 5 should be used by the adaptive counter-based scheme by taking both RE and SRB into consideration.

Finally, we compare the fixed-threshold counter-based scheme ($C = 2, 4, 6$) to our adaptive counter-based scheme using the above suggested threshold function (denoted by AC). Fig. 6(a) shows the obtained RE and SRB. As can be seen, the fixed-threshold scheme does have the dilemma between RE and SRB. Using a small threshold (such as 2) can give both satisfactory RE and SRB in denser maps (1 x 1, 3 x 3, 5 x 5), but RE degrades sharply if the host distribution is sparser. On the other hand, using a larger threshold (such as 6) indeed raises RE, but SRB degrades in all maps. The proposed scheme can resolve the dilemma effectively. RE is always maintained at high level, and except in very sparse networks the SRB is significant.

Fig. 6(b) compares the broadcast latency. The latency of AC is the smallest in maps 1 x 1 and 3 x 3. In other maps, the latency of AC is slightly larger than that of $C = 2$ because AC is targeting at higher RE in sparser maps. These results justify the effectiveness of our adaptive scheme.

4.2 Performance of the Adaptive Location-Based Scheme

In the following, we first show how we determine the best threshold function $A(n)$ for our adaptive location-based scheme.

Figure 6: Comparison of the adaptive counter-based scheme (AC) and fixed-threshold counter-based scheme ($C = 2, 4, 6$). (a) RE (shown in lines) and SRB (shown in bars), and (b) average broadcast latency.

Figure 7: The functions used to tune $A(n)$ for the adaptive location-based scheme.

Then we compare it to the fixed-threshold location-based scheme.

Fig. 3 already indicates an abstract curve for $A(n)$. Before $n_1$, we should enforce a host to rebroadcast by setting $A(n) = 0$, and after $n_2$ we tend to inhibit a host from rebroadcasting by setting $A(n) = 0.187$ (this is the average additional coverage after a host hearing the same broadcast packet twice). In our experiments, we will fix $n_1$ and $n_2$, and simply make $A(n)$ a linear function between $n_1$ and $n_2$. Fig. 7 shows the curves for $A(n)$ used in our experiments.

Each curve in Fig. 7 can be denoted by $(n_1, n_2)$ depending on the values of $n_1$ and $n_2$ chosen for use. We then conducted extensive simulations on different maps to compare these threshold functions. The result is in Fig. 8 (for clarity, we partition the results into four sub-figures). It indicates that (6, 12), (8, 12), and (8, 10) deliver quite satisfactory RE. By further considering their SRB, we would suggest to pick (6, 12) (observe the SRB of (8, 12), and (8, 10) on sparser maps).

Based on the above result, we then compare the fixed-threshold location-based scheme ($A = 0.1871$, $A = 0.0469$, and $A = 0.0134$, which are used in (15)) to our adaptive location-based scheme using $n_1 = 6$ and $n_2 = 12$. As shown in Fig. 9(a), the RE of the fixed-threshold scheme will degrade significantly in sparser maps. The problem can be conquered by our adaptive scheme. Moreover, the SRB will not be sacrificed as high RE is achieved. Fig. 9(b) compares the broadcast latency. On denser maps, the adaptive scheme has the lowest latency, and on sparser maps, the latency is slightly higher than

486
that of $A = 0.1871$ so as to maintain high RE.

### 4.3 Performance of the Neighbor Coverage Scheme and Dynamic Hello Interval

The neighbor coverage scheme can adaptively assess the redundancy of a host’s rebroadcast based on its neighborhood information and the sources from which it received the same broadcast packet. However, as shown below, the accuracy of the neighborhood information may have significant effect on this scheme. To collect neighborhood information, HELLO packets are sent periodically by each host. A host $x$ enlists another host $h$ as its one-hop neighbor when a HELLO is received from $h$. If no HELLO has been received from $h$ for the past two hello intervals, host $x$ deletes $h$ as its one-hop neighbor. Below, we first discuss the effect of hello interval, and then propose a dynamic hello interval scheme on top of our neighbor coverage scheme.

Obviously, a shorter hello interval will make neighborhood information more up-to-date. To study this effect, we compare the RE achieved by different hello intervals ($1,000$, $3,000$, $10,000$, $20,000$, and $30,000$ milliseconds) under different host mobility ($20$, $40$, $60$, and $80$ km/hour) at different maps in Fig. 10. As can be seen, on sparser maps a long hello interval may significantly degrade RE, especially when the host mobility is high. Note that only in smaller maps (such as $5 \times 5$ in Fig. 10(a)) host mobility has little impact on RE, because hosts hardly roam away from the source host too far away.

Although a lower hello interval can offer better RE, too many HELLO’s may also hurt the network by taking up too much network bandwidth, especially in a crowded environment. Below, we propose a way to dynamically adjust the hello interval by each host. First, we define a host $x$’s neighborhood variation $n_{x}$ as

$$n_{x} = \frac{\text{no of hosts joining or leaving set } N_{x} \text{ in the past } 10 \text{ sec.}}{|N_{x}| \times 10}$$

Intuitively, $n_{x}$ is a quantitative estimation of the change at $x$’s neighborhood learned in the near past. Note that the change may be caused by $x$’s neighbors or $x$ itself.

Then, we use the neighborhood variation to adjust the hello interval $h_{x}$ of $x$:

$$h_{x} = \max(h_{\min}, \frac{n_{\text{max}} - n_{x}}{n_{\text{max}}} \times h_{\text{max}})$$

where $n_{\text{max}}$ is the predefined maximum neighborhood variation, and $h_{\min}$ and $h_{\text{max}}$ the predefined shortest and longest hello intervals, respectively. Intuitively, the hello interval is inverse to the value of $n_{x}$ and is guarded by a minimal and a maximal value. We comment that since each host’s hello interval may change dynamically, this value should be appended to its HELLO packets so that surrounding hosts can determine its existence. We also comment that in AODV [18], a Hello Interval Extension is also specified, but without much detail.

To verify the effectiveness of the above scheme, we conducted some simulations using $n_{\text{max}} = 0.02$, $h_{\min} = 1,000$ms, and $h_{\text{max}} = 10,000$ms. Fig. 11(a) shows that using the dynamic hello interval can maintain high RE independent of the host mobility and host density. The SRB is also very significant compared to other schemes. This is a merit that can not be achieved by neither the adaptive counter-based scheme nor the adaptive location-based scheme. Fig. 11(b) evaluates the number of HELLO packets sent on different scenarios. Generally speaking, on sparser maps ($9 \times 9$ and $11 \times 11$), the neighborhood variation will be higher (around 0.02 in our simulations). So most hosts will pick the smallest hello interval of $h_{\min} = 1000$ms, which is the reason for raising RE. On $3 \times 3$ and $5 \times 5$ maps, the number of hellos will increase with higher host mobility. On the smallest $1 \times 1$ map, there is almost no neighborhood variation, so the hello interval is very close to $h_{\text{max}} = 10,000$ms.
5 Conclusions

Broadcasting in a MANET has quite different characteristics from that in other networks. It could cause serious redundancy, contention, and collision. We have proposed three adaptive broadcasting schemes, namely, adaptive counter-based, adaptive location-based, and neighbor-coverage schemes, for the broadcast storm problem in a MANET. The first two adaptive schemes have effectively resolved the dilemma between reachability and efficiency in the fixed-threshold counter-based and location-based schemes that we proposed in [15]. If positioning devices are not available, the last scheme is also a very good choice. Because of their adaptive nature, these schemes can be used without concerning host density and host mobility.

References


