

## THIRD-ORDER INTERMODULATION DISTORTION IN CAPACITIVELY-DRIVEN CC-BEAM MICROMECHANICAL RESONATORS

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### ABSTRACT

The mechanism behind third order intermodulation distortion ( $IM_3$ ) in capacitively driven clamped-clamped beam micromechanical ("CC-beam  $\mu$ mechanical") resonators is shown to arise mainly from nonlinear interactions between applied off-resonance electrical signals and the mechanical displacements they induce. Analytical formulations for the third-order input intercept point ( $IIP_3$ ) are then presented, first with simplifications that allow a closed form expression, then with additional complexities to account for second-order effects, such as beam bending due to an applied dc-bias voltage. Using this analytical formulation, predicted voltage  $IIP_3$ 's of 1.8V and 6.5V for 9.2 MHz and 17.4 MHz  $\mu$ mechanical resonators, respectively, closely match measured values of 1.8V and 6.3V. Extensive data on the dependence of  $IIP_3$  on dc-bias voltage, resonator  $Q$ , and resonator center frequency, are also included to lend further insight into the trade-offs involved when designing for a specific linearity requirement.

### I. INTRODUCTION

Despite recent increases in the frequency range of micromechanical resonators [1][2], and demonstrations of complex mechanical filtering circuits using such devices [3], efforts to apply micromechanical resonator technology to RF communication circuits have so far been delayed by lingering questions concerning the linearity of these devices, which must satisfy strict specifications for present-day cellular and cordless phone applications. For example, the European GSM standard for mobile communications requires a minimum total  $IIP_3$  of  $-18$  dBm in the receive path to insure adequate suppression of alternate-channel interferers [4].

Pursuant to determining whether or not  $\mu$ mechanical signal processors possess sufficient linearity for such applications, this paper presents a complete analytical formulation for the  $IIP_3$  of capacitively driven CC-beam  $\mu$ mechanical resonators (c.f., Fig. 1), then verifies the formulation via measurement, where voltage  $IIP_3$ 's of 1.8V and 6.3V are observed for 9.2MHz and 17.4MHz  $\mu$ mechanical resonators, respectively. After a brief review of  $IM_3$  and  $IIP_3$ , the analytical formulation is first presented in an intuitive form in Section III, then in a more complete form in Section IV. Section V then compares theoretical prediction with measurement.

### II. BACKGROUND: $IM_3$ AND $IIP_3$

Third-order intermodulation distortion ( $IM_3$ ) for a frequency fil-

ter occurs when system nonlinearities allow out-of-band signal components (tones) spaced from an in-band frequency  $\omega_o$  by  $\Delta\omega$  and  $2\Delta\omega$ , respectively, to generate an in-band component  $S_{IM_3}$  back at  $\omega_o$  [5]. This phenomenon can be illustrated quantitatively by applying an input containing the desired signal (i.e., the fundamental) plus the two out-of-band (interfering) tones, given by

$$S_{in} = S_i \left[ \underbrace{\cos \omega_o t}_{\text{Fundamental}} + \underbrace{\cos \omega_1 t}_{\text{Tone 1}} + \underbrace{\cos \omega_2 t}_{\text{Tone 2}} \right], \quad (1)$$

to the general nonlinear transfer function

$$S_{out} = A_o + A_1 S_{in} + A_2 S_{in}^2 + A_3 S_{in}^3 + \dots, \quad (2)$$

where  $A_o, \dots, A_n$  are constants if the system is memoryless. Inserting (1) into (2), then expanding, yields (among other components)

$$S_{out} = \dots + \underbrace{A_1 S_i \cos \omega_o t}_{\text{Fundamental}} + \underbrace{\frac{3}{4} A_3 S_i^3 \cos(2\omega_1 - \omega_2)t}_{\text{3rd-Order Intermod (} IM_3 \text{)}} + \dots, \quad (3)$$

where an  $IM_3$  component is seen to be generated via third-order nonlinearity represented by  $A_3$ .

For the common case where the interferers are located at frequencies  $\Delta\omega$  and  $2\Delta\omega$  from the fundamental (as shown in Fig. 2(a)), the quantity  $(2\omega_1 - \omega_2)$  will be equal to  $\omega_o$ , and the  $IM_3$  component will be at the same frequency as the fundamental, possibly masking it if either  $A_3$  or the interfering tone magnitudes are too large. In effect, as also illustrated in Fig. 2(a), even though the interfering tones are outside the filter passband, they still generate an in-band response—a highly undesirable situation for a filtering device designed to reject out-of-band signals. To suppress this effect, the third-order nonlinear term in (2) must be constrained below a minimum acceptable value in practical communication systems. Among the more useful metrics to gauge the ability of a system to suppress  $IM_3$  distortion is the third-order input intercept point  $IIP_3$ , defined as the input amplitude  $S_i$  at which the extrapolated  $IM_3$  and fundamental output components are equal in magnitude. In general, a large  $IIP_3$  is preferred for communication applications.

### III. FIRST-ORDER FORMULATION FOR $IIP_3$

Pursuant to determining the  $IIP_3$  for the devices of this work, Fig. 1 presents the perspective-view schematic for a capacitively-driven CC-beam  $\mu$ mechanical resonator embedded in the measurement set-up to be used for verification in Section V. As shown, this

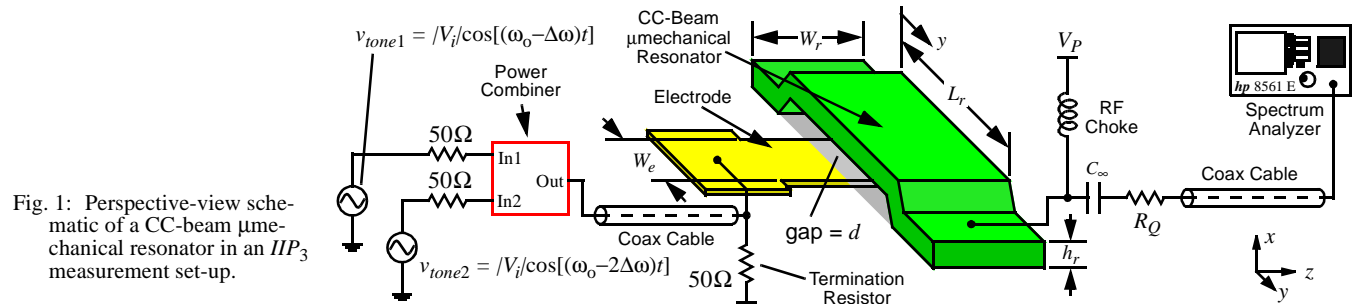


Fig. 1: Perspective-view schematic of a CC-beam  $\mu$ mechanical resonator in an  $IIP_3$  measurement set-up.

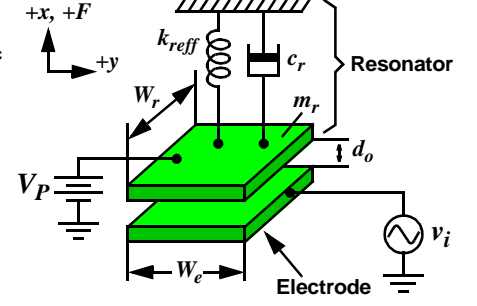
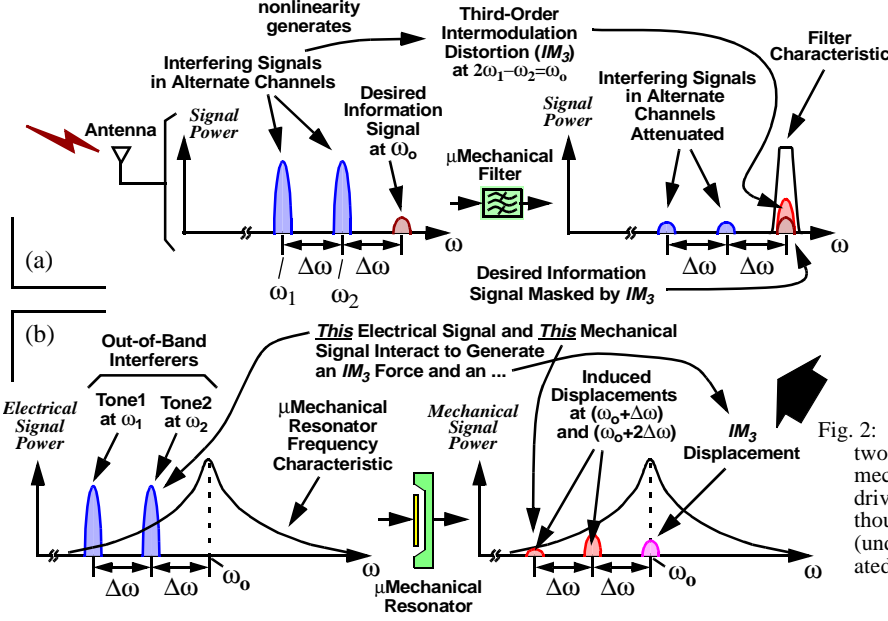


Fig. 3: Simplified lumped-parameter model for a capacitively-driven CC-beam for a first-order  $IIP_3$  analysis.

device consists of a single conductive beam, fixed to the substrate at both ends, with a conductive electrode underlying the central portion of the beam. The electrode and beam essentially comprise the two plates of the transducer capacitor  $C(x)$ , across which an input voltage consisting of the sum of a dc-bias  $V_P$  and ac signal  $v_i$  are applied to drive the beam into vibration.

Because high frequency CC-beam  $\mu$ mechanical resonators generally vibrate with amplitudes much smaller than their lengths (e.g., 100Å amplitude for a 40 $\mu$ m-long beam), it is often not mechanical nonlinearity that governs the degree of  $IM_3$  distortion seen, but rather nonlinearity in its capacitive transducer. In particular,  $C(x)$  is quite nonlinear for VHF resonators due to the need for small electrode-to-resonator gaps [1]. Thus, as shown in Fig. 2(b), the mechanism for  $IM_3$  distortion then involves nonlinear interplay across  $C(x)$  between applied electrical interferer tones and the tiny off-resonance displacements they generate, giving rise to an in-band  $IM_3$  force component (at  $2\omega_1 - \omega_2 = \omega_0$ ).

A first-order expression for this  $IM_3$  force component can be obtained by approximating the beam and electrode by the lumped mass-spring-damper equivalent shown in Fig. 3, where static bending of the beam caused by the applied dc-bias  $V_P$  has been neglected, and where expressions for the lumped elements can be found in [3]. For this simplified system, the total force acting on the suspended mass under an applied input  $V_P - v_i$  is given by

$$F_{tot} = \frac{1}{2}(V_P - v_i)^2 \frac{\partial C}{\partial x} = \frac{1}{2}(V_P - v_i)^2 \frac{\partial}{\partial x} \left[ C_o \left( 1 + \frac{x}{d_o} \right)^{-1} \right] \quad (4)$$

$$= \frac{1}{2}(V_P - v_i)^2 \left[ -\frac{C_o}{d_o} \right] \left\{ 1 - \frac{2}{d_o}x + \frac{3}{d_o^2}x^2 - \frac{4}{d_o^3}x^3 + \dots \right\}$$

where  $d_o$  and  $C_o$  are the electrode-to-resonator gap spacing and capacitance, respectively, when the beam is stationary, and where the final form comprises a Taylor expanded approximation. In (4), if  $v_i$  is composed of the sum of two off-resonance tone signals

$$v_i = V_1 \cos \omega_1 t + V_2 \cos \omega_2 t, \quad (5)$$

then the resulting displacement can be written as

$$x = X_1 \cos(\omega_1 t + \phi_1) + X_2 \cos(\omega_2 t + \phi_2) \quad (6)$$

where the values of  $X_1$ ,  $X_2$ ,  $\phi_1$ , and  $\phi_2$ , can be obtained from the voltage-to-displacement transfer function of the  $\mu$ mechanical beam

$$\frac{X(j\omega)}{V(j\omega)} = \frac{V_P C_o}{k_{reff} d_o} \Theta(\omega), \quad (7)$$

where

$$\Theta(\omega) = \frac{1}{1 - (\omega/\omega_0)^2 + j\omega/(Q\omega_0)}, \quad (8)$$

and where  $k_{reff}$  is the effective integrated stiffness at the midpoint of the beam [3].

Applying (5) and (6) to (4) with  $V_1 = V_2 = V_i$ , then expanding and collecting only  $IM_3$  terms with frequency  $(2\omega_1 - \omega_2)$ , the expression for the  $IM_3$  force is found to be

$$F_{IM3} = V_i^3 \cdot \left\{ \frac{1(\epsilon_o A_o)^2 V_P}{4 d_o^5 k_{reff}} [2\Theta_1 + \Theta_2^*] + \frac{3(\epsilon_o A_o)^3 V_P^3}{4 d_o^8 k_{reff}^2} \Theta_1 [\Theta_1 + 2\Theta_2^*] + \frac{3(\epsilon_o A_o)^4 V_P^5}{2 d_o^{11} k_{reff}^3} \Theta_1^2 \Theta_2^* \right\} \quad (9)$$

where  $\epsilon_o$  is the permittivity in vacuum,  $A_o = W_r W_e$  is the electrode-to-resonator overlap area,  $\Theta_1 = \Theta(\omega_1)$ , and  $\Theta_2 = \Theta(\omega_2)$ .

By equating (9) with the fundamental force component

$$F_{fund} = V_P \frac{C_o}{d_o} V_i = V_P \frac{\epsilon_o A_o}{d_o^2} V_i, \quad (10)$$

then solving the expression for  $V_i$ , the input voltage magnitude at the  $IIP_3$  is found to be

$$V_{IIP3} = \left\{ \frac{1\epsilon_o A_o}{4 d_o^3 k_{reff}} [2\Theta_1 + \Theta_2^*] + \frac{3(\epsilon_o A_o)^2 V_P^2}{4 d_o^6 k_{reff}^2} \Theta_1 [\Theta_1 + 2\Theta_2^*] + \frac{3(\epsilon_o A_o)^3 V_P^4}{2 d_o^9 k_{reff}^3} \Theta_1^2 \Theta_2^* \right\}^{-1/2} \quad (11)$$

Equations (9) and (11) clearly show that for a given set of tone frequencies,  $\omega_1$  and  $\omega_2$ , the  $IIP_3$  can be increased by reducing  $V_P$  and  $A_o$ , and by increasing  $d_o$  and  $k_{reff}$ —all modifications that will increase the series motional resistance  $R_x$  of a  $\mu$ mechanical resonator. Thus, a clear trade-off between linearity and series motional resistance (which for matching purposes often must be small) exists for capacitively transduced  $\mu$ mechanical beam resonators.

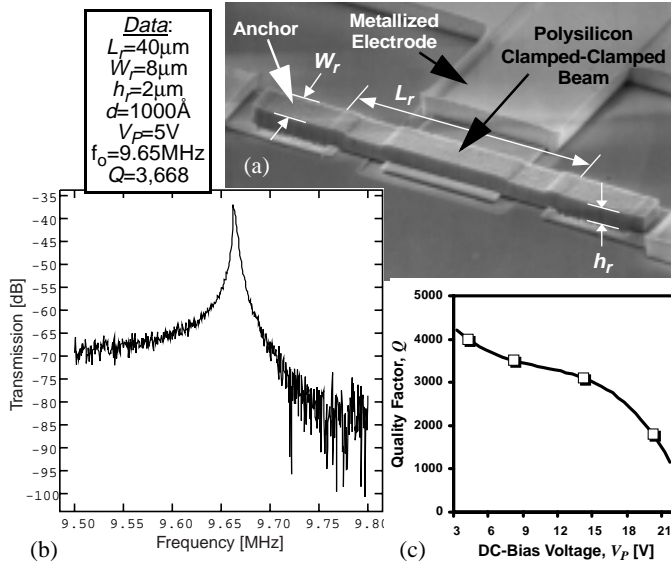


Fig. 4: (a) SEM and (b) measured frequency response and numerical data for a 9.65 MHz polysilicon CC-beam  $\mu$ mechanical resonator. (c) Measured plot of  $Q$  versus  $V_p$  for this resonator.

#### IV. COMPLETE FORMULATION FOR $IIP_3$

Equation (11) clearly shows that the  $IIP_3$  for a CC-beam  $\mu$ mechanical resonator depends heavily on the electrode-to-resonator gap spacing  $d_o$ . Thus, although (11) provides design insight and comes fairly close to the correct value for  $V_{IIP3}$ , it is not exact, since its derivation neglects the effect of beam bending due to the applied dc-bias  $V_p$ , which makes the gap spacing a function of location  $y$ . In addition, the use of a lumped rather than distributed  $k_{\text{eff}}$  also contributes an error.

To fully model these effects, expressions for  $d(y)$  and  $k_r(y)$  [3] must be used in the above derivation to attain  $F_{IM3}$  and  $F_{fund}$  as functions of  $y$ , which then must be integrated along the electrode width to obtain values for the total displacements  $X_{IM3}$  and  $X_{fund}$ . The  $V_{IIP3}$  is then found by equating these two total displacements and solving for  $V_i=V_{IIP3}$ . Although this procedure cannot be reduced to a single closed-form expression and so yields less design insight than (11), it does yield a more accurate value for  $V_{IIP3}$ .

#### V. EXPERIMENTAL RESULTS

CC-beam  $\mu$ mechanical resonators were fabricated using a polysilicon surface micromachining process similar to previous renditions [3], except for specific provisions to dope the electrodes n-type, but the resonator beams p-type. The use of different dopants for electrodes and structures was found to alleviate phenomena, such as depletion, that might otherwise increase the achievable gap spacing  $d_o$  over the target spacing [3]. Using this p/n-doping strategy, the CC-beam resonators of this work were able to match the target gap spacing of 1000 $\text{\AA}$  much more closely than previous devices [3]. Figure 4 presents the scanning electron micrograph (SEM) of a 9.65 MHz CC-beam  $\mu$ mechanical resonator, along with a frequency characteristic and a curve-fitted plot of  $Q$  versus dc-bias  $V_p$ , both measured on a network analyzer under 50  $\mu$ Torr vacuum achieved via a custom-built vacuum chamber.

$IIP_3$  measurements were made using the test set-up of Fig. 1, with  $\Delta\omega=2\pi(200\text{kHz})$ . As shown, interferer tones at  $f_o-200\text{kHz}$  and  $f_o+400\text{kHz}$  are combined, then applied to the input electrode of a CC-beam resonator to generate an  $IM_3$  output response, which is measured at  $f_o$  via a spectrum analyzer. Figure 5 plots the funda-

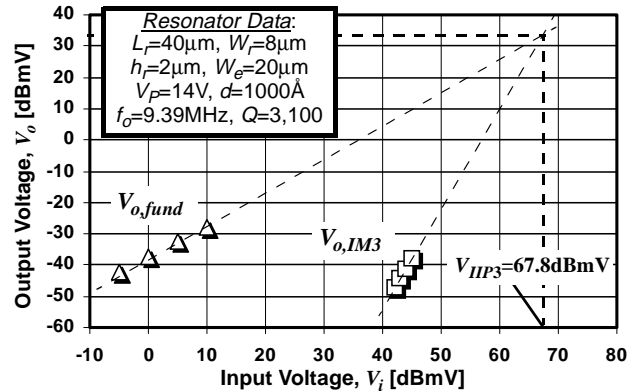


Fig. 5: Measured plot of  $V_o$  versus  $V_i$  for the  $\mu$ mechanical resonator of Fig. 4, showing an extrapolated  $V_{IIP3}=2.45\text{V}$ .

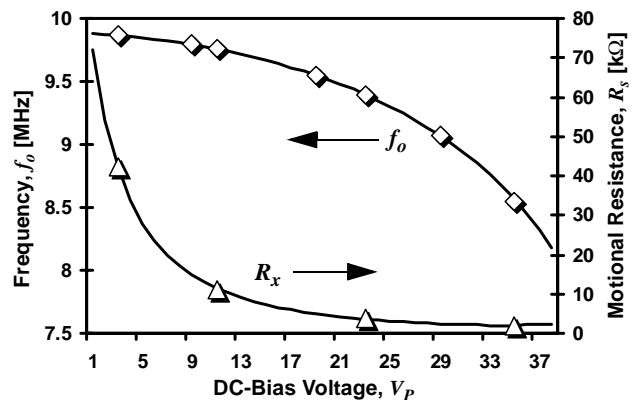


Fig. 6: Measured points and predicted plots of resonance frequency and  $R_x$  vs.  $V_p$  for a  $\sim 10$  MHz CC-beam  $\mu$ resonator.

mental and  $IM_3$  output components versus the input voltage amplitude for a 9.39 MHz CC-beam  $\mu$ mechanical resonator biased as specified in the figure. From the intersection point in Fig. 5, the  $V_{IIP3}$  is seen to be 67.8 dBmV (or 2.45V).

Given the very strong dependence of  $IIP_3$  on the initial electrode-to-resonator gap spacing  $d_o$  (seen in (11)), it is important that  $d_o$  be known accurately to insure a sufficiently accurate theoretical prediction for comparison with measurement. To obtain an accurate value for the initial gap  $d_o$ , a plot of frequency  $f_o$  versus dc-bias  $V_p$  is measured, from which the value of  $d_o$  and the effective  $h$  are extracted via curve-fitting with a proven expression for  $f_o$  vs.  $V_p$  [3]. Figure 6 presents such a plot of  $f_o$  vs.  $V_p$  for a  $\sim 10$  MHz CC-beam, obtained by measuring frequency characteristics such as in Fig. 4(a) for various values of  $V_p$ . By curve-fitting the measured points to a theoretical curve (shown in the figure) generated by Eq. (12) from [3],  $d_o$  is found to be 1029 $\text{\AA}$ , and the effective  $h$  is 1.9 $\mu\text{m}$ . Using these values of  $d_o$  and  $h$  in Eq. (18) from [3], a curve for the series motional resistance  $R_x$  of this resonator is also plotted in Fig. 6, and this matches well with data taken from the measured frequency characteristics, giving further confidence in both the extracted value for  $d_o$  and in the models from [3].

To verify the accuracy of the formulation in Section IV, Fig. 7 plots measured and predicted values of  $V_{IIP3}$  versus  $V_p$  for a  $\sim 10$  MHz CC-beam  $\mu$ mechanical resonator, showing very close agreement between measurement and theory. Note that Figs. 6 and 7 together verify the theoretical prediction of Section III that  $IIP_3$  can be increased often only at the expense of increasing  $R_x$ .

Although  $V_{IIP3}$  is widely used for expressing  $IIP_3$ , some applications may prefer that  $IIP_3$  be expressed as a power instead. The  $IIP_3$  power  $P_{IIP3}$  can be determined from  $V_{IIP3}$  via the expression

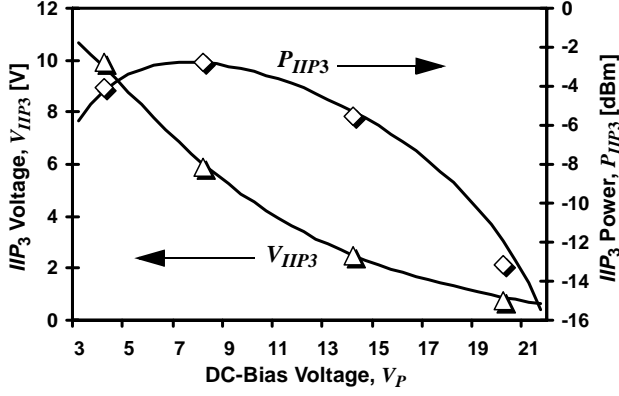


Fig. 7: Voltage and power  $IIP_3$ 's vs.  $V_P$  for a  $\sim 10$  MHz CC-beam  $\mu$ mechanical resonator.

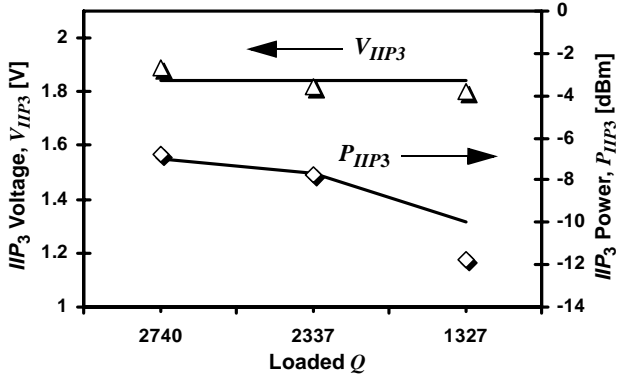


Fig. 8: Voltage and power  $IIP_3$ 's versus  $Q$  for a  $\sim 10$  MHz CC-beam  $\mu$ mechanical resonator.

$$P_{IIP3} = 10 \text{Log} \left( \frac{V_{IIP3}^2}{2R_Q} \right) \quad (12)$$

where  $R_Q$  might, for example, represent a termination resistor needed in  $\mu$ mechanical filters to control the  $Q$  of filter end resonators [3]. Figure 7 also compares measured and calculated values (using  $R_Q=3R_x$ ) for  $P_{IIP3}$ , showing that in contrast to  $V_{IIP3}$ , which decreases monotonically with increasing  $V_P$ , there is an optimum  $V_P$  at which the  $P_{IIP3}$  is maximized (at a value of  $-3$  dBm). This can be explained by recognizing that as  $V_P$  increases,  $R_x$  decreases, hence  $R_Q$  decreases, leading to an increase in  $P_{IIP3}$ , as governed by (12). However, as  $V_P$  becomes even larger, the  $IM_3$  force governed by (9) also steadily increases, due to both the direct increase in  $V_P$  and due to a decrease in  $d_o$  caused by  $V_P$ -induced beam bending. This latter effect begins to dominate after some threshold voltage  $V_P$  beyond which the  $P_{IIP3}$  decreases with increasing  $V_P$ .

To quantify the dependence of  $IIP_3$  on the loaded  $Q$  of a given CC-beam resonator, Fig. 8 presents a plot of both  $V_{IIP3}$  and  $P_{IIP3}$  versus  $Q$  for a  $\sim 10$  MHz  $\mu$ mechanical resonator. To obtain this plot, the  $Q$  of the resonator was controlled by adding an  $R_Q$  resistor in series with the resonator. As seen from Fig. 8,  $V_{IIP3}$  remains relatively constant with  $Q$  changes, as predicted by (11) for interferers sufficiently far from the resonator center frequency; i.e., for  $\Delta f \gg f_o/(2Q)$ . On the other hand,  $P_{IIP3}$  degrades with decreasing  $Q$ , even for distant interferers, as governed by (12).

Having verified (11) by comparison with actual measurements at frequencies near 10 MHz, projections for the  $IIP_3$  values expected for even higher frequencies are now in order. In particular, given the direct dependence of  $V_{IIP3}$  on resonator stiffness  $k_{\text{reft}}$  shown in

Table I: CC-Beam  $\mu$ Mechanical Resonator  $IIP_3$  Data

Parameter	9.2MHz	17.4MHz	Units
$\mu$ Resonator Dimensions: $L_r, W_r, h$	40,8,1.93	29,8,1.79	$\mu\text{m}$
Electrode Width, $W_e$	20	14	$\mu\text{m}$
Electrode-to-Resonator Gap, $d_o$	1,031	1,120	$\text{\AA}$
DC-Bias Voltage, $V_P$	16	16	V
Quality Factor, $Q$	1,371	1,261	—
Measured Motional Resistance, $R_x$	8.46	23.77	k $\Omega$
Predicted $IIP_3$ Voltage, $V_{IIP3}$	1.84	6.49	V
Measured $IIP_3$ Voltage, $V_{IIP3}$	1.8	6.27	V
Predicted $IIP_3$ Power, $P_{IIP3}$	$-9.97$	$-5.27$	dBm
Measured $IIP_3$ Power, $P_{IIP3}$	$-11.77$	$-5.57$	dBm

(11), the  $V_{IIP3}$  for a CC-beam is expected to increase as its resonance frequency increases. For example, the theory of Section IV predicts  $V_{IIP3}=19.6\text{V}$  for a 70 MHz CC-beam  $\mu$ mechanical resonator with  $Q=4000$ ,  $V_P=27\text{V}$ ,  $L_r=18.8\mu\text{m}$ ,  $d_o=1000\text{\AA}$ ,  $h=3\mu\text{m}$ ,  $W_e=L_r/2$ ,  $W_r=10\mu\text{m}$ , and  $\Delta f=200\text{kHz}$ . On the other hand, although (11) and (12) also predict an increase in  $P_{IIP3}$  with resonance frequency, the expected increase is not quite as fast, since its rate of increase is counteracted by a simultaneous increase in  $R_x$  (hence  $R_Q$ ) with frequency. For the example resonator above, with  $R_Q=3R_x$ ,  $P_{IIP3}=+6$  dBm—still adequate for most receive path applications in communications. Table I summarizes predicted and measured data for both the 10 MHz CC-beam discussed so far, and a 17.4 MHz CC-beam, clearly showing an increase in  $IIP_3$  with frequency.

## VI. CONCLUSIONS

Analytical expressions for the  $IIP_3$  of capacitively driven CC-beam  $\mu$ mechanical resonators were presented and verified, showing  $IIP_3$ 's as high as  $-3$  dBm for a 10 MHz CC-beam terminated via an impedance  $3X$  its own series motional resistance. (The  $P_{IIP3}$  is even larger for smaller termination impedances.) Although this measured value at 10 MHz easily satisfies GSM receive path requirements, it is still short of the  $+7.6$  dBm needed for RF channel-selection in CDMA handsets (assuming a duplexer with  $>58$  dB transmit power rejection precedes the  $\mu$ mechanical filter) [6]. Given that  $IIP_3$  increases with frequency, according to the theory presented, this CDMA requirement should easily be achievable by a capacitively-driven UHF  $\mu$ mechanical filter. Whether or not  $\mu$ mechanical filters can eventually satisfy the duplexer requirement, on the other hand, is still the subject of ongoing research.

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