

# CS281A/Stat241A Lecture 19

## *Junction Tree Algorithm*

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# Announcements

- My office hours:  
Tuesday Nov 3 (today), 1-2pm, in 723 Sutardja Dai Hall.  
Thursday Nov 5, 1-2pm, in 723 Sutardja Dai Hall.
- Homework 5 due 5pm Monday, November 16.

# Key ideas of this lecture

- Junction Tree Algorithm.
  - (For directed graphical models:) Moralize.
  - Triangulate.
  - Construct a junction tree.
  - Define potentials on maximal cliques.
  - Introduce evidence.
  - Propagate probabilities.

# Junction Tree Algorithm

- Inference: Given
  - Graph  $G = (V, \mathcal{E})$ ,
  - Evidence  $x_E$ , for  $E \subseteq V$ ,
  - Set  $F \subseteq V$ ,compute  $p(x_F | x_E)$ .

# Junction Tree Algorithm

- Elimination:
  - Single set  $F$ .
  - Any  $G$ .
- Sum-product:
  - All singleton sets  $F$  simultaneously.
  - $G$  a tree.
- Junction tree:
  - All cliques  $F$  simultaneously.
  - Any  $G$ .

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
2. Triangulate.
3. Construct a junction tree.
4. Define potentials on maximal cliques.
5. Introduce evidence.
6. Propagate probabilities.

# 1. Moralize

- In a directed graphical model, local conditionals are functions of a variable and its parents:

$$p(x_i | x_{\pi(i)}) = \psi_{\pi(i) \cup \{i\}}.$$

- To represent this as an undirected model, the set

$$\pi(i) \cup \{i\}$$

must be a clique.

- We consider the **moral graph**: all parents connected.

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
2. Triangulate. (e.g., run `UNDIRECTEDGRAPHELIMINATE`)
3. Construct a junction tree.
4. Define potentials on maximal cliques.
5. Introduce evidence.
6. Propagate probabilities.



## 2. Triangulate: Motivation

### Theorem:

A graph  $G$  is chordal iff it has a **junction tree**.

Recall that all of the following are equivalent:

- $G$  is chordal
- $G$  is decomposable
- $G$  is recursively simplicial
- $G$  is the fixed point of `UNDIRECTEDGRAPHELIMINATE`
- an oriented version of  $G$  has moral graph  $G$ .
- $G$  implies the same cond. indep. as some directed graph.

# Chordal/Triangulated

## Definitions:

A **cycle** for a graph  $G = (V, E)$  is a vertex sequence  $v_1, \dots, v_n$  with  $v_1 = v_n$  but all other vertices distinct, and  $\{v_i, v_{i+1}\} \in E$ .

A cycle has a **chord** if it has a pair  $v_i, v_j$  with  $1 < |i - j| < n$  and  $\{i, j\} \in E$ .

A graph is **chordal** or **triangulated** if every cycle of length at least four has a chord.

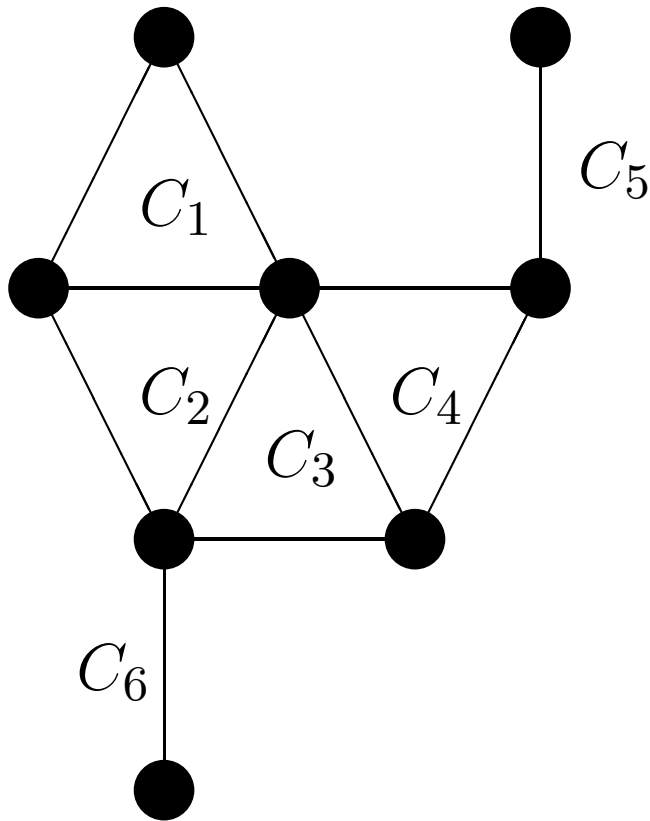
# Junction Tree: Definition

A **clique tree** for a graph  $G = (V, E)$  is a tree  $T = (V_T, E_T)$  where

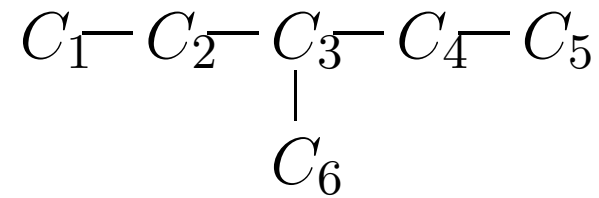
- $V_T$  is a set of cliques of  $G$ ,
- $V_T$  contains all maximal cliques of  $G$ .

A **junction tree** for a graph  $G$  is a clique tree  $T = (V_T, E_T)$  for  $G$  that has the **running intersection** property: for any cliques  $C_1$  and  $C_2$  in  $V_T$ , every clique on the path connecting  $C_1$  and  $C_2$  contains  $C_1 \cap C_2$ .

# Junction Tree: Example



Clique Tree:



## 2. Triangulate

**Theorem:**

A graph  $G$  is chordal iff it has a **junction tree**.

Chordal  $\Leftrightarrow$  Recursively Simplicial, and we'll show:  
Recursively Simplicial  $\Rightarrow$  Junction Tree  $\Rightarrow$  Chordal

# Recursively Simplicial $\Rightarrow$ Junction Tree

**Recall:** A graph  $G$  is **recursively simplicial** if it contains a simplicial vertex  $v$  (neighbors form a clique), and when  $v$  is removed, the remaining graph is recursively simplicial.

**Proof idea—induction step:**

Consider a recursively simplicial graph  $G$  of size  $n + 1$ .

When we remove a simplicial vertex  $v$ , it leaves a subgraph  $G'$  with a junction tree  $T$ .

Let  $N$  be the clique in  $T$  containing  $v$ 's neighbors.

Let  $C$  be a new clique of  $v$  and its neighbors.

To obtain a junction tree for  $G$ :

- If  $N$  contains only  $v$ 's neighbors, replace it with  $C$ .
- Otherwise, add  $C$  with an edge to  $N$ .

# Junction Tree $\Rightarrow$ Chordal

**Proof idea—induction step:**

Consider a junction tree  $T$  of size  $n + 1$ .

Consider a leaf  $C$  of  $T$  and its neighbor  $N$  in  $T$ .

Remove  $C$  from  $T$  and remove  $C \setminus N$  from  $V$ .

The remaining tree is a junction tree for the remaining (chordal) graph.

All cycles have a chord, since either

1. Cycle is completely in remaining graph,
2. Cycle is completely in  $C$ , or
3. Cycle is in  $C \setminus N$ ,  $C \cap N$ , and  $V \setminus C$   
(and  $C \cap N$  is complete, so contains a chord).

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
2. Triangulate.
3. Construct a junction tree:  
Find a maximal spanning tree.
4. Define potentials on maximal cliques.
5. Introduce evidence.
6. Propagate probabilities.



# Junction Tree is Maximal Spanning Tree

**Define:**

The **weight** of a clique tree  $T = (\mathcal{C}, E)$  is

$$w(T) = \sum_{(C, C') \in E} |C \cap C'|.$$

A **maximal spanning tree** for a clique set  $\mathcal{C}$  of a graph is a clique tree  $T = (\mathcal{C}, E^*)$  with maximal weight over all clique trees of the form  $(\mathcal{C}, E)$ .

# Junction Tree is Maximal Spanning Tree

**Theorem:** Suppose that a graph  $G$  with clique set  $\mathcal{C}$  has a junction tree. Then a clique tree  $(\mathcal{C}, E)$  is a junction tree iff it is a maximal spanning tree for  $\mathcal{C}$ .

And there are efficient greedy algorithms for finding the maximal spanning tree:

- While graph is not connected:
  - Add an edge for the biggest weight separating set that does not lead to a cycle.

# Maximal Spanning Tree: Proof

Consider a graph  $G$  with vertices  $V$ .

For a clique tree  $(\mathcal{C}, E)$ , define the separators

$$\mathcal{S} = \{C \cap C' : (C, C') \in E\}.$$

Since  $T$  is a tree, for any  $k \in V$ ,

$$\sum_{S \in \mathcal{S}} 1[k \in S] \leq \sum_{C \in \mathcal{C}} 1[k \in C] - 1,$$

with equality iff the subgraph of  $T$  of nodes containing  $k$  is a tree.

# Maximal Spanning Tree: Proof

Thus,

$$\begin{aligned}w(T) &= \sum_{S \in \mathcal{S}} |S| \\&= \sum_{S \in \mathcal{S}} \sum_k 1[k \in S] \\&\leq \sum_k \left( \sum_{C \in \mathcal{C}} 1[k \in C] - 1 \right) \\&= \sum_{C \in \mathcal{C}} |C| - n,\end{aligned}$$

with equality iff  $T$  is a junction tree.

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
2. Triangulate.
3. Construct a junction tree
4. Define potentials on maximal cliques.
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# Define potentials on maximal cliques

To express a product of clique potentials as a product of maximal clique potentials:

$$\psi_{S_1}(x_{S_1}) \cdots \psi_{S_N}(x_{S_N}) = \prod_{C \in \mathcal{C}} \psi_C(x_C),$$

1. Set all clique potentials to 1.
2. For each potential, incorporate (multiply) it into a potential containing its variables.

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
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# Introduce Evidence

Two equivalent approaches:

1. Introduce evidence potentials

$$\delta(x_i, \bar{x}_i) \quad \text{for } i \text{ in } E,$$

so that marginalizing fixes  $x_E = \bar{x}_E$ .

2. Take slice of each clique potential:

$$\psi_C(x_C) := \psi_C(x_{C \cap (V \setminus E)}, \bar{x}_{C \cap E}).$$



# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
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# Hugin Algorithm

Add potentials for **separator sets**.

**Recall:** If  $G$  has a junction tree  $T = (\mathcal{C}, \mathcal{S})$ , then any probability distribution that satisfies the conditional independences implied by  $G$  can be factorized as

$$p(x) = \frac{\prod_{C \in \mathcal{C}} p(x_C)}{\prod_{S \in \mathcal{S}} p(x_S)},$$

where, if  $S = \{C_1, C_2\}$  then  $x_S$  denotes  $x_{C_1 \cap C_2}$ .

# Hugin Algorithm

Represent  $p$  with potentials on separators:

$$p(x) = \frac{\prod_{C \in \mathcal{C}} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)}$$

- This can represent any distribution that an undirected graphical model can (since we can set  $\phi_S \equiv 1$ ).
- But nothing more (since we can incorporate each  $\phi_S$  into one of the  $\psi_C$ 's that have  $S \subseteq C$ ).

# Hugin Algorithm

## 1. Initialize:

$\psi_C(x_C) =$  appropriate clique potential

$$\phi_S(x_S) = 1.$$

## 2. Update potentials so that

•  $p(x)$  is invariant

•  $\psi_C, \phi_S$  **become the marginal distributions.**

# Algorithm:

- Messages are passed between cliques in the junction tree.
- A message is passed from  $V$  to adjacent vertex  $W$  once  $V$  has received messages from all its other neighbors.
- The message corresponds to the updates:

$$\phi_S^{(1)}(x_S) = \sum_{x_{V-S}} \psi_V(x_V),$$

$$\psi_W^{(1)}(x_W) = \psi_W(x_W) \frac{\phi_S^{(1)}(x_S)}{\phi_S(x_S)},$$

$$\psi_V^{(1)}(x_V) = \psi_V(x_V),$$

where  $S = V \cap W$  is the separator.

# Analysis:

1.  $p(x)$  is invariant under these updates.
2. In a tree, messages can path in both directions over every edge.
3. The potentials are *locally consistent* after messages have passed in both directions.
4. In a graph with a junction tree, local consistency implies global consistency.

# Analysis:

$$p(x) = \frac{\prod_{C \in \mathcal{C}} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)}.$$

In this ratio, only  $\frac{\psi_V \psi_W}{\phi_S}$  changes, to

$$\begin{aligned} \frac{\psi_V^{(1)} \psi_W^{(1)}}{\phi_S^{(1)}} &= \frac{\psi_V \psi_W \phi_S^{(1)}}{\phi_S^{(1)} \phi_S} \\ &= \frac{\psi_V \psi_W}{\phi_S}. \end{aligned}$$

# Analysis:

1.  $p(x)$  is invariant under these updates.
2. In a tree, messages can path in both directions over every edge.
3. The potentials are *locally consistent* after messages have passed in both directions.
4. In a graph with a junction tree, local consistency implies global consistency.



# Analysis: Local Consistency

Suppose that messages pass both ways, from  $V$  to  $W$  and back:

1. a message passes from  $V$  to  $W$ :

$$\phi_S^{(1)}(x_S) = \sum_{x_{V-S}} \psi_V(x_V),$$

$$\psi_W^{(1)}(x_W) = \psi_W(x_W) \frac{\phi_S^{(1)}(x_S)}{\phi_S(x_S)},$$

$$\psi_V^{(1)}(x_V) = \psi_V(x_V),$$

# Analysis: Local Consistency

2. other messages pass to  $W$ :

$$\phi_S^{(2)} = \phi_S^{(1)}$$

$$\psi_V^{(2)} = \psi_V^{(1)}$$

$$\psi_W^{(2)} = \dots$$

# Analysis: Local Consistency

3. a message passes from  $W$  to  $V$ :

$$\phi_S^{(3)}(x_S) = \sum_{x_{W-S}} \psi_W^{(2)}(x_W),$$

$$\psi_V^{(3)}(x_V) = \psi_V^{(2)}(x_V) \frac{\phi_S^{(3)}(x_S)}{\phi_S^{(2)}(x_S)},$$

$$\psi_W^{(3)}(x_V) = \psi_W(x_W).$$

Subsequently,  $\phi_S, \psi_V, \psi_W$  remain unchanged.

# Analysis: Local Consistency

After messages have passed in both directions, these potentials are *locally consistent*:

$$\sum_{x_{V \setminus S}} \psi_V^{(3)}(x_V) = \sum_{x_{W \setminus S}} \psi_W^{(3)}(x_W) = \phi_S^{(3)}(x_S).$$

c.f.: 
$$\sum_{x_{V \setminus S}} p(x_V) = \sum_{x_{W \setminus S}} p(x_W) = p(x_S).$$

# Analysis: Local Consistency Proof

$$\begin{aligned}\sum_{x_{V \setminus S}} \psi_V^{(3)}(x_V) &= \sum_{x_{V \setminus S}} \psi_V^{(2)}(x_V) \frac{\phi_S^{(3)}(x_S)}{\phi_S^{(2)}(x_S)} && (W \rightarrow V) \\ &= \frac{\phi_S^{(3)}(x_S)}{\phi_S^{(1)}(x_S)} \sum_{x_{V \setminus S}} \psi_V(x_V) && (\text{to } W) \\ &= \phi_S^{(3)}(x_S) && (V \rightarrow W) \\ &= \sum_{x_{W \setminus S}} \psi_W^{(2)}(x_W) \\ &= \sum_{x_{W \setminus S}} \psi_W^{(3)}(x_W).\end{aligned}$$

# Analysis:

1.  $p(x)$  is invariant under these updates.
2. In a tree, messages can path in both directions over every edge.
3. The potentials are *locally consistent* after messages have passed in both directions.
4. In a graph with a junction tree, local consistency implies global consistency.

# Analysis: Local implies Global

Local consistency:

For all adjacent cliques  $V, W$  with separator  $S$ ,

$$\sum_{x_{V \setminus S}} \psi_V^{(3)}(x_V) = \sum_{x_{W \setminus S}} \psi_W^{(3)}(x_W) = \phi_S^{(3)}(x_S).$$

Global consistency:

For all cliques  $C$ ,

$$\psi_C(x_C) = \sum_{x_{C^c}} \frac{\prod_C \psi_C(x_C)}{\prod_S \phi_S(x_S)} = p(x_C)$$

# Local implies Global: Proof

Induction on number of cliques.

Trivial for one clique.

Assume true for all junction trees with  $n$  cliques.

Consider a tree  $T_W$  of size  $n + 1$ .

Fix a leaf  $B$ , attached by separator  $R$ .

Define

$W =$  all variables

$N = B \setminus R$

$V = W \setminus N$

$T_V =$  junction tree without  $B$ .



# Local implies Global: Proof

The junction tree  $T_V$ :

- Has only variables  $V$  (from the junction tree property).
- Satisfies local consistency.
- Hence satisfies global consistency for  $V$ :  
for all  $A \in T_V$ ,

$$\psi_A(x_A) = \sum_{x_{V \setminus A}} \frac{\prod_{C \in \mathcal{C}_V} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_V} \phi_S(x_S)}.$$

# Local implies Global: Proof

- But viewing this  $A$  in the larger  $T_W$ , we have

$$\begin{aligned}\sum_{x_{W \setminus A}} \frac{\prod_{C \in \mathcal{C}_W} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_W} \phi_S(x_S)} &= \sum_{x_{V \setminus A}} \sum_{x_N} \frac{\psi_B(x_B)}{\phi_R(x_R)} \frac{\prod_{C \in \mathcal{C}_V} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_V} \phi_S(x_S)} \\ &= \sum_{x_{V \setminus A}} \frac{\prod_{C \in \mathcal{C}_V} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_V} \phi_S(x_S)} \\ &= \psi_A(x_A).\end{aligned}$$

# Local implies Global: Proof

And for the new clique  $B$ :

Suppose  $A$  is the neighbor of  $B$  in  $T_W$ .

$$\begin{aligned}\sum_{x_{W \setminus B}} \frac{\prod_{C \in \mathcal{C}_W} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_W} \phi_S(x_S)} &= \sum_{x_{A \setminus R}} \sum_{x_{V \setminus A}} \frac{\psi_B(x_B)}{\phi_R(x_R)} \frac{\prod_{C \in \mathcal{C}_V} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_V} \phi_S(x_S)} \\ &= \frac{\psi_B(x_B)}{\phi_R(x_R)} \sum_{x_{A \setminus R}} \left( \sum_{x_{V \setminus A}} \frac{\prod_{C \in \mathcal{C}_V} \psi_C(x_C)}{\prod_{S \in \mathcal{S}_V} \phi_S(x_S)} \right) \\ &= \psi_B(x_B) \frac{\sum_{x_{A \setminus R}} \psi_A(x_A)}{\phi_R(x_R)} \\ &= \psi_B(x_B).\end{aligned}$$

# Junction Tree Algorithm

1. (For directed graphical models:) Moralize.
2. Triangulate.
3. Construct a junction tree
4. Define potentials on maximal cliques.
5. Introduce evidence.
6. Propagate probabilities.

# Junction Tree Algorithm: Computation

- Size of largest maximal clique determines run-time.
- If variables are categorical and potentials are represented as tables, marginalizing takes time exponential in clique size.
- Finding a triangulation to minimize the size of the largest clique is NP-hard.

# Key ideas of this lecture

- Junction Tree Algorithm.
  - (For directed graphical models:) Moralize.
  - Triangulate.
  - Construct a junction tree.
  - Define potentials on maximal cliques.
  - Introduce evidence.
  - Propagate probabilities.