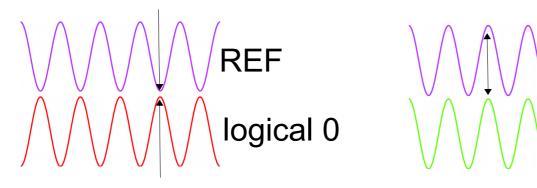
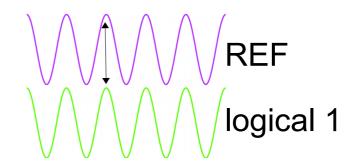
Boolean Computation using Oscillators

Tianshi Wang Jaijeet Roychowdhury

Department of Electrical Engineering and Computer Sciences
University of California, Berkeley

Encoding Bits Using Phase

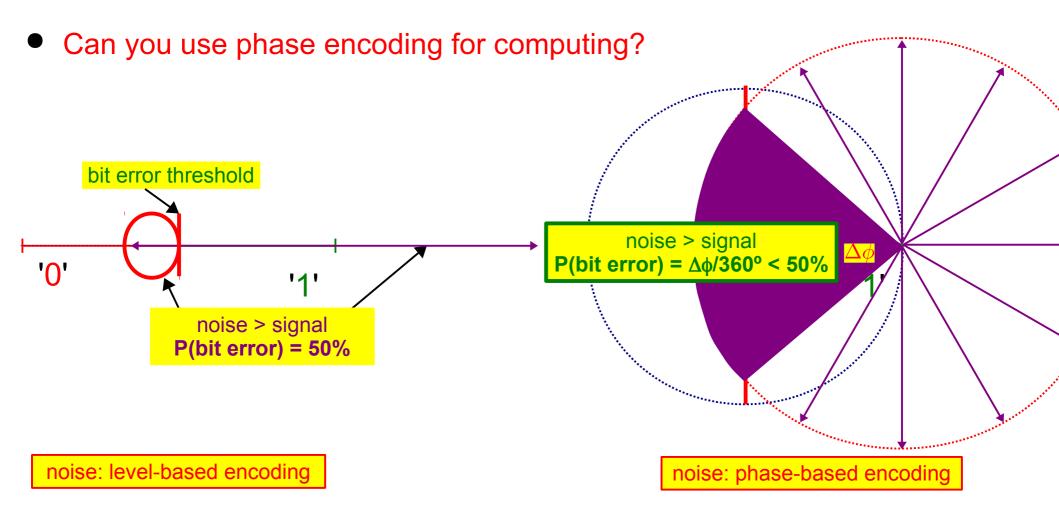




- Can you use this for computing?
- Even if you can: what is the advantage?

Superior Noise Immunity

- loose analogy: PM/FM vs AM in radio
- Same reason why the BER of BPSK is superior to that of BASK



Phase Logic Computers

Eiichi Goto, John von Neumann, 1950s and 60s

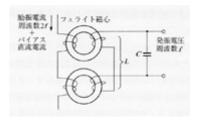
- "cheap and reliable"
 - » "widely used in Japan"
- not easy to miniaturise
 - » inductors, iron cores
 - » transistors/ICs dominated
 - -level-based logic

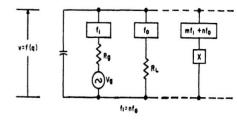
Phase Based Logic:

underlying circuitry/components have been <u>difficult to miniaturise</u> or <u>impractical for integration</u>



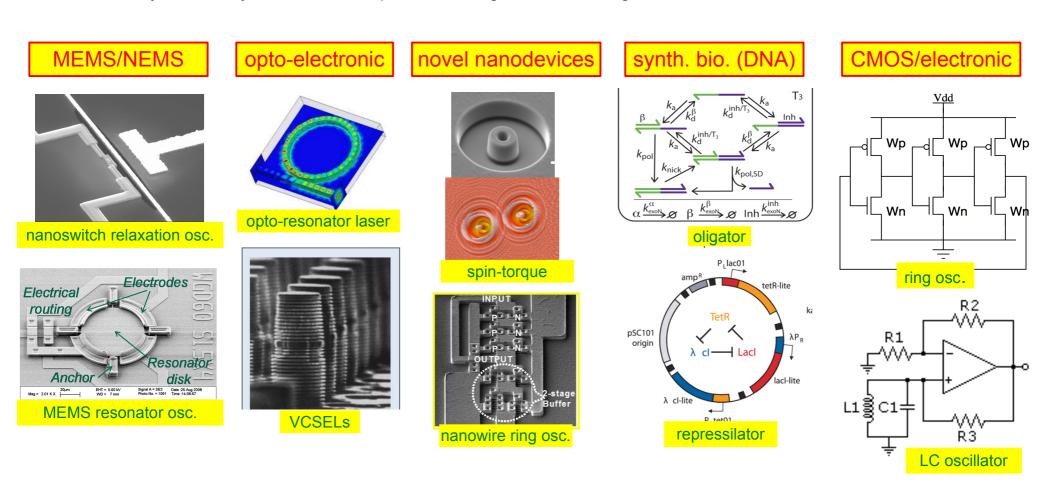
Oi Electric
Parametron X-ℵ-01, 1964
Ferro-Electronic Calculator





New Result: (almost) Any Oscillator will Do

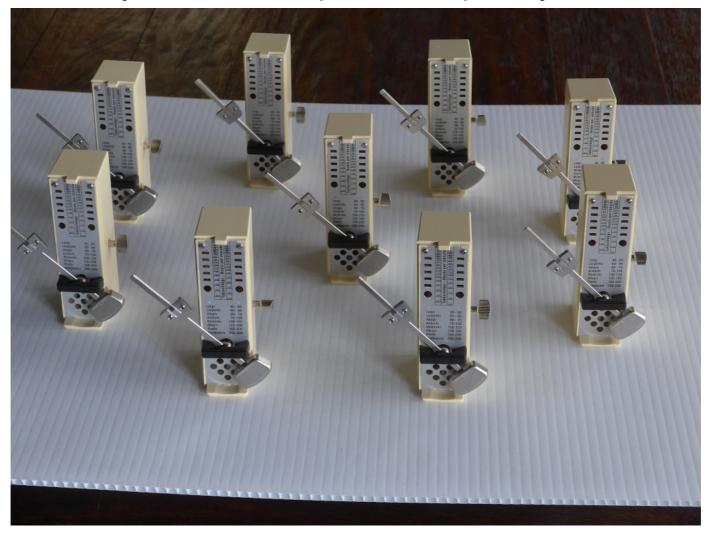
details: Wang/Roychowdhury, "PHLOGON: Phase-based LOGic using Oscillatory Nano-systems". UCNC, 2014. Roychowdhury, "Boolean Computation Using Self-Sustaining Nonlinear Oscillators". arXiv, 2014.



many are integrable and nano-scale

Underlying Mechanism: Injection Locking

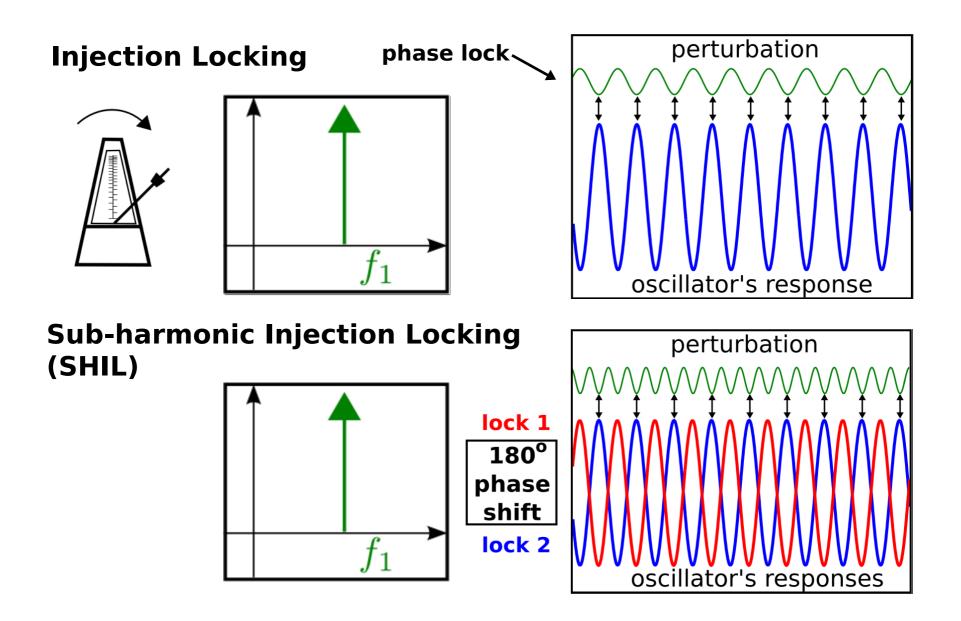
Oscillators can synchronize in phase/frequency



we use a variant: sub-harmonic injection locking

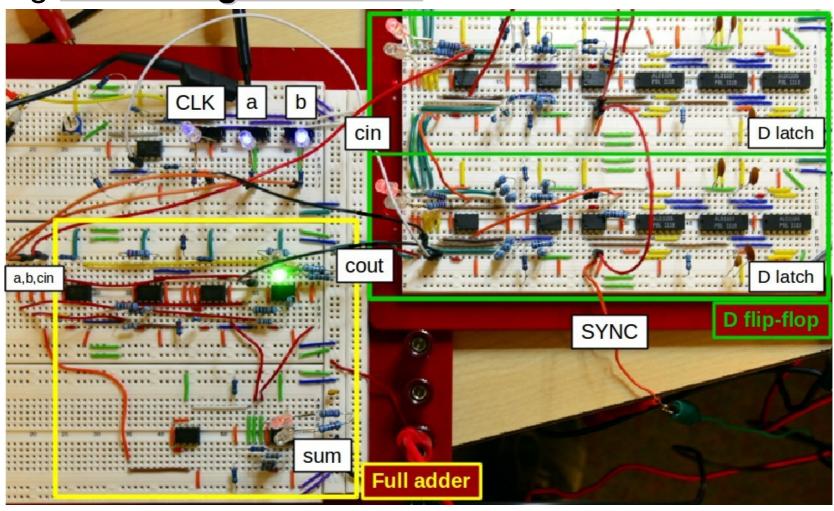
Tianshi Wang, UC Berkeley

Underlying Mechanism: Injection Locking

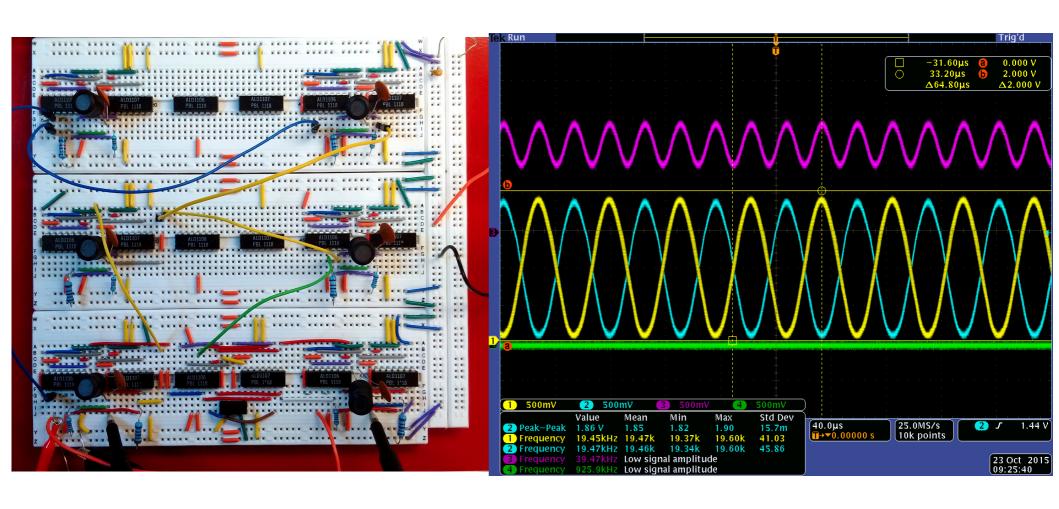


First Phase Logic FSM with Oscillators

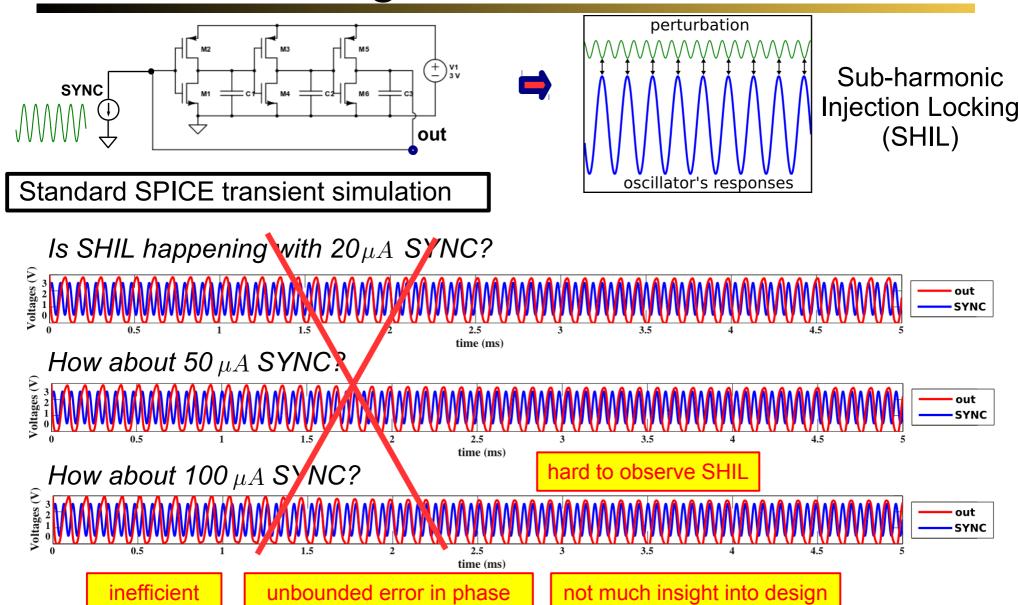
 PHLOGON: Phase Logic using Oscillatory Nanosystems using CMOS ring oscillators



Prototype with CMOS LC Oscillators



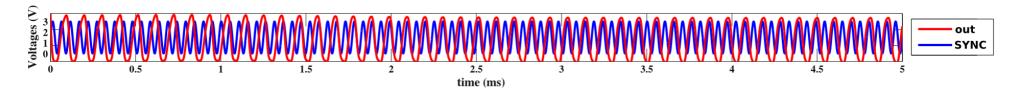
Simulating SHIL of Oscillators



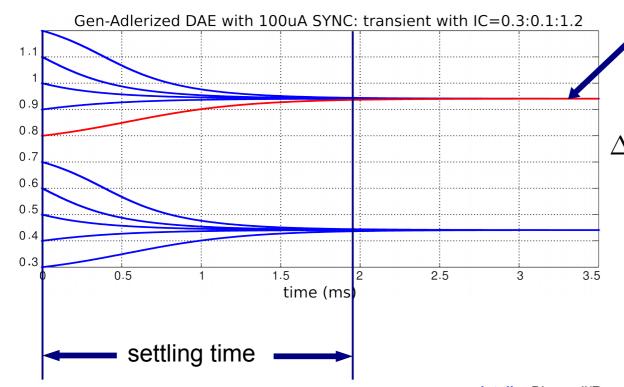
Design tools with phase macromodel analyses

Phase-macromodel-based Analyses

Standard SPICE transient simulation



Phase-based simulation



SHIL occurs: curve "flattens"

"locked phase error"

Generalized Adler's Equation

$$\frac{d}{dt}\Delta\phi(t) = f_0 - f_1 + f_0 \cdot g(\Delta\phi(t))$$

$$g(\Delta\phi(t)) = \int_{0}^{\infty} \vec{v}_{1}^{T} (t) + \Delta\phi(t) \cdot \vec{b}_{1}(\tau) d\tau$$

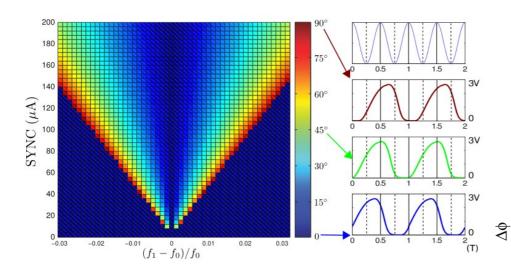
Perturbation Projection Vector (PPV)

details: Bhansali/Roychowdhury, "Gen-Adler: the Generalized Adler's equation for injection locking analysis in oscillators". Proc. ASPDAC, 2009.

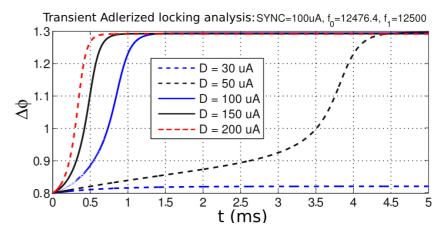
More Capabilities of the Design Tools

details: Wang/Roychowdhury, "Design Tools for Oscillator-based Computing Systems", DAC, 2015.

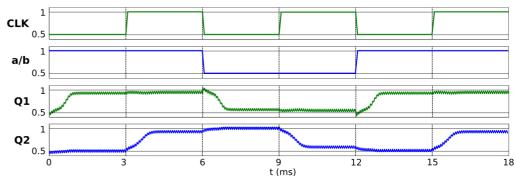
Locked phase error vs. variations in oscillator natural frequency



Timing of phase-based D latch



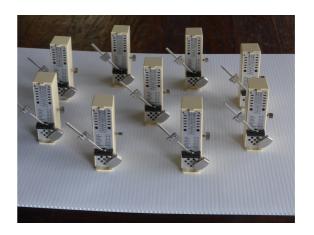
Full system transient in phase domain

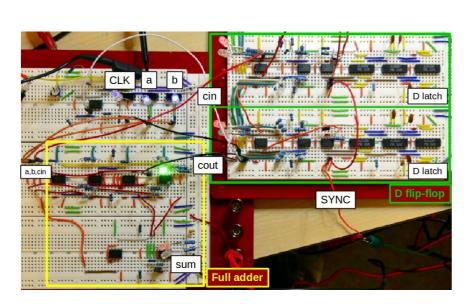


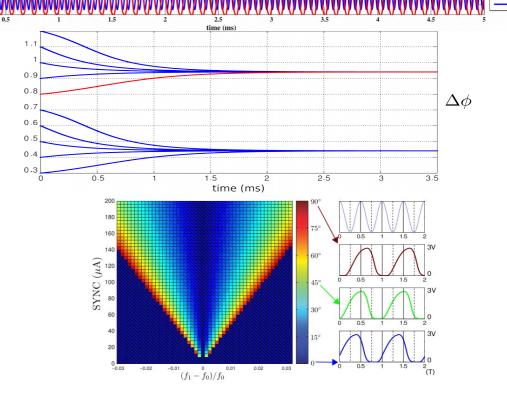
open-source release: PHLOGON.eecs.berkeley.edu

Summary









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