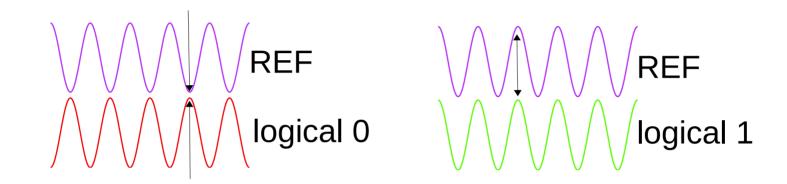
Design Tools for Oscillator-Based Computing Systems

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Encoding Bits Using Phase



- Can you use this for computing?
- Even if you can: what is the advantage?

noise immunity - loose analogy: PM/FM vs. AM in radio

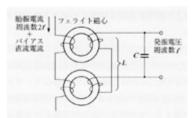
Phase Logic Computer: Eiichi Goto, John von Neumann, 1950s and 60s

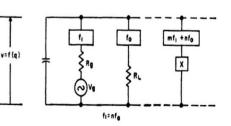
- "cheap and reliable"
 - "widely used in Japan"
- not easy to miniaturise
 - inductors, iron cores
 - transistors/ICs dominated
 - level-based logic



Phase Based Logic: underlying circuitry/components have been <u>difficult to miniaturise</u> or <u>impractical for integration</u>

Oi Electric Parametron X- ℵ-01, 1964 Ferro-Electronic Calculator

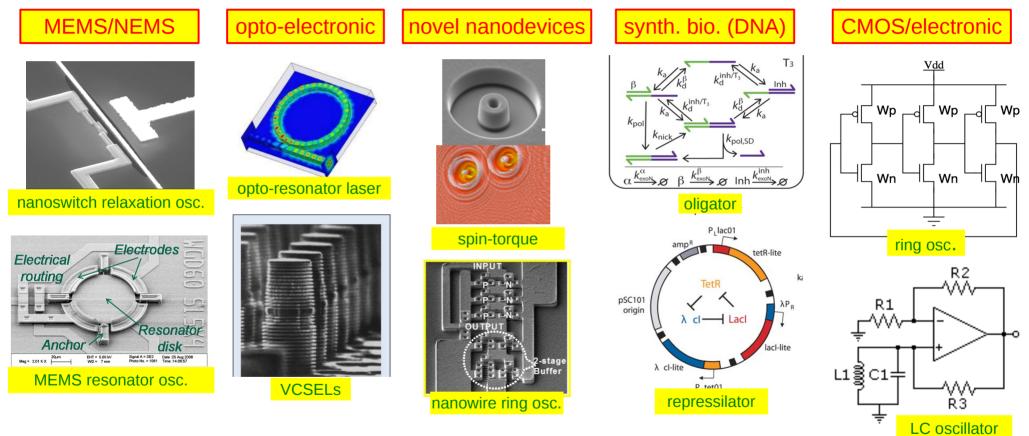




New Result: (almost) Any Oscillator will Do

details: Roychowdhury, "Boolean Computation Using Self-sustaining Nonlinear Oscillators", arXiv:1410.5016 [cs.ET], Oct, 2014.

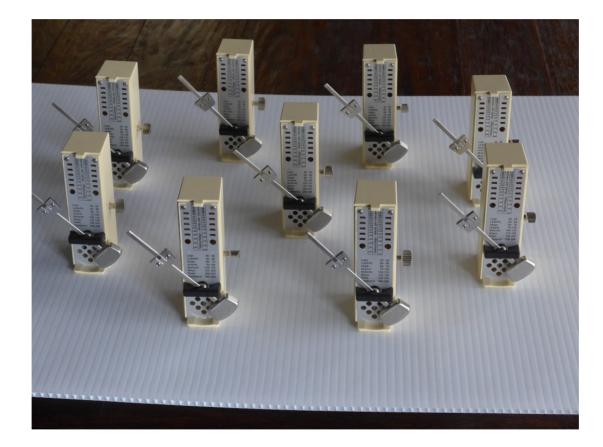
Wang/Roychowdhury, "PHLOGON: Phase-based LOGic using Oscillatory Nano-systems". UCNC, 2014.



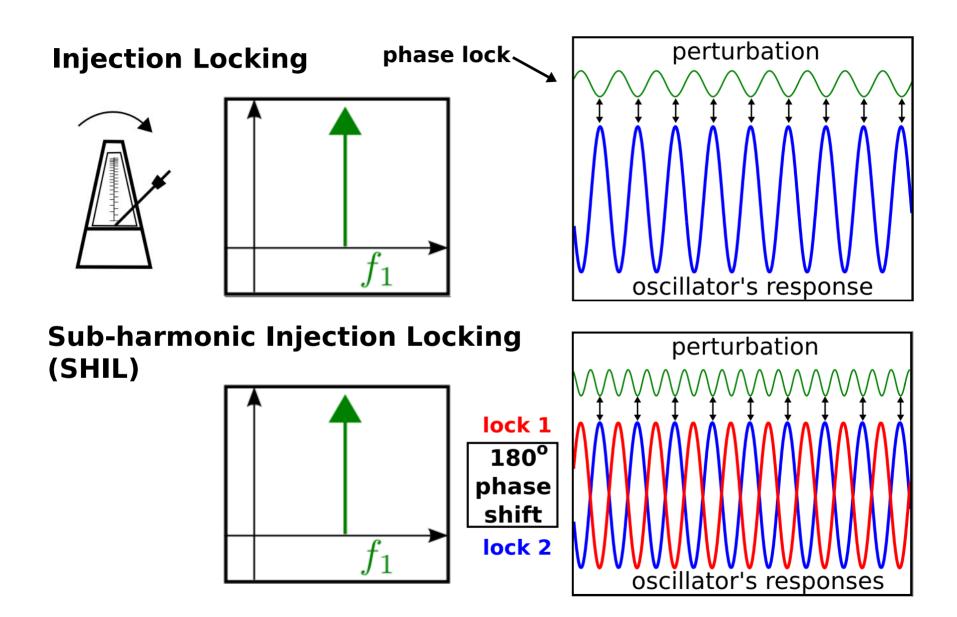
many are integrable and nano-scale

Underlying Mechanism: Injection Locking

• Oscillators can synchronize in phase/frequency

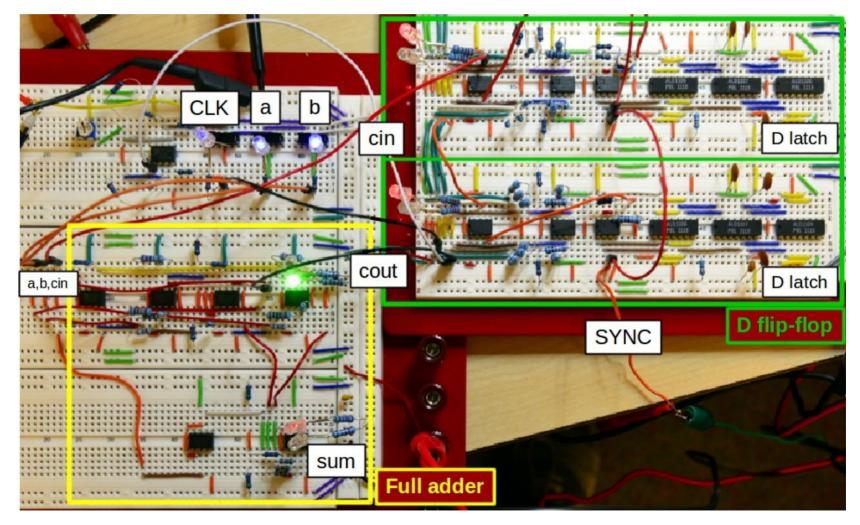


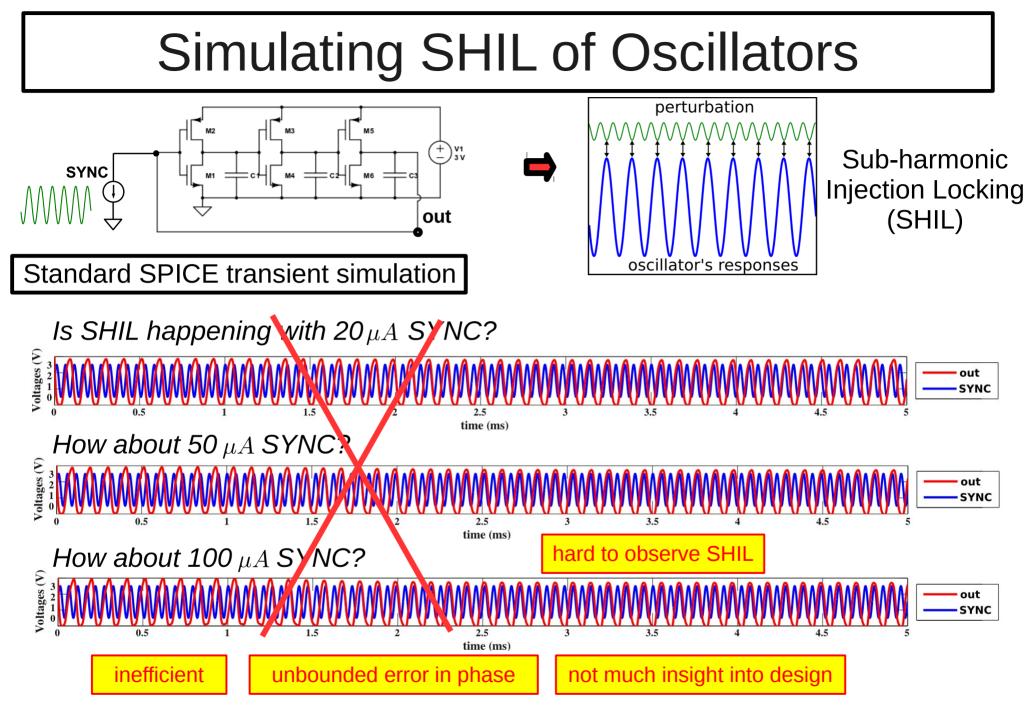
Underlying Mechanism: Injection Locking



First Phase Logic FSM with Oscillators

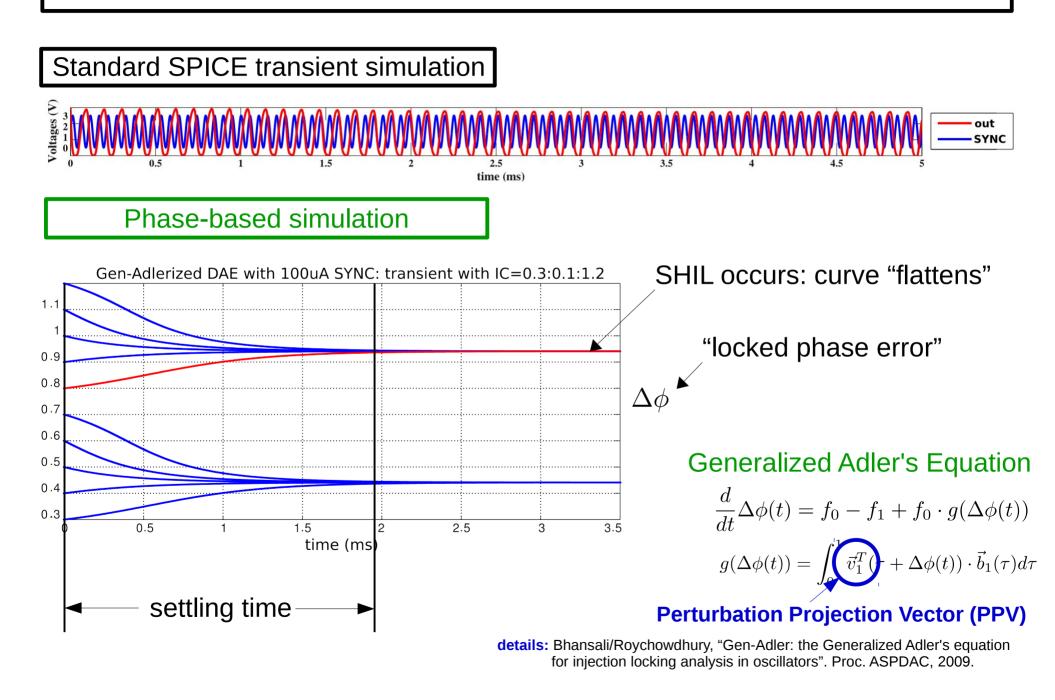
 PHLOGON: PHase LOGic using Oscillatory Nanosystems using <u>CMOS ring oscillators</u>



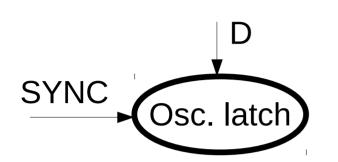


Design tools with phase macromodel analyses

Phase-macromodel-based Analyses



Phase-macromodel-based Analyses

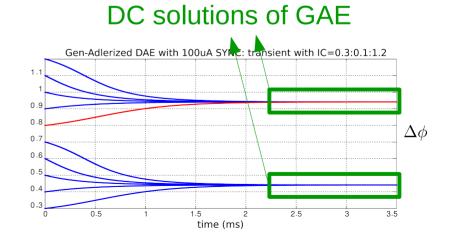


Generalized Adler's Equation (GAE)

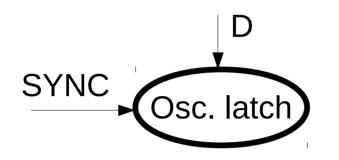
$$\frac{d}{dt}\Delta\phi(t) = f_0 - f_1 + f_0 \cdot g(\Delta\phi(t))$$
$$\frac{d}{dt}\Delta\phi(t) = 0$$
$$\frac{f_1 - f_0}{f_0} = g(\Delta\phi(t))$$

Steady-state Adlerized locking analysis: f₀=9503.95, f₁=9600 0.025 Stable solutions 0.02 Adler locking equation RHS/LHS 0.015 0.01 0.005 0.005 -0.01 SYNC = 30 uA SYNC = 50 uA SYNC = 70 uA -0.015 SYNC = 100 uA SYNC = 150 uA -0.02 $(f_1 - f_0)/f_0$ -0.025 0.1 0.2 0.3 ٥ 0.4 0.5 0.6 0.7 0.8 0.9 $\Delta \phi$

visualize LHS and RHS using MAPP

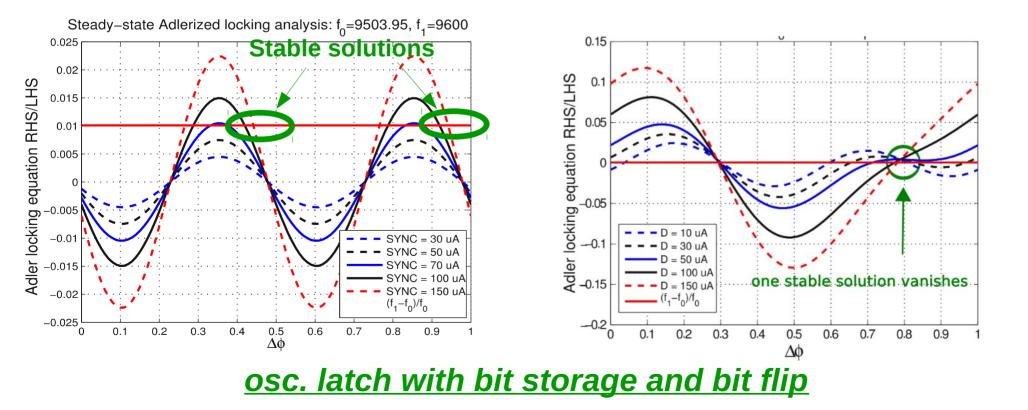


Phase-macromodel-based Analyses

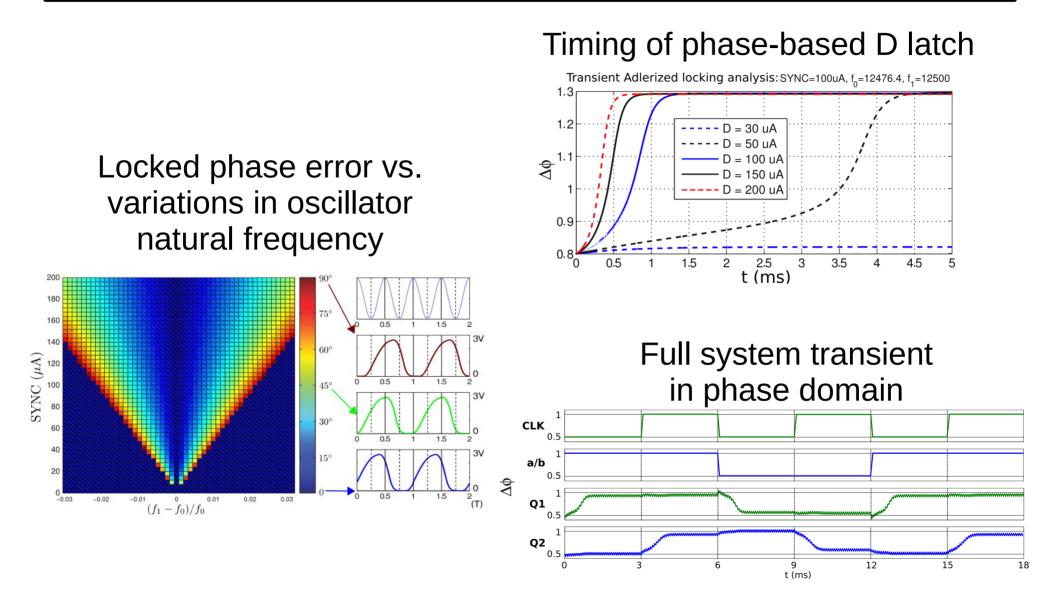


Generalized Adler's Equation (GAE)

$$\frac{d}{dt}\Delta\phi(t) = f_0 - f_1 + f_0 \cdot g(\Delta\phi(t))$$
$$\frac{d}{dt}\Delta\phi(t) = 0$$
$$\frac{f_1 - f_0}{f_0} = g(\Delta\phi(t))$$



More Capabilities of the Design Tools



open-source release this summer

Summary

