



Wireless Embedded Systems and Networking

Foundations of IP-based Ubiquitous Sensor Networks

WSN Technology and Hardware Architectures

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Technology Perspective

Client Tier: (desk,lap,PDA,phone)

- Interactivity, Human Interface, Form Factor, Ergonomics, Diversity of usage

Server Tier:

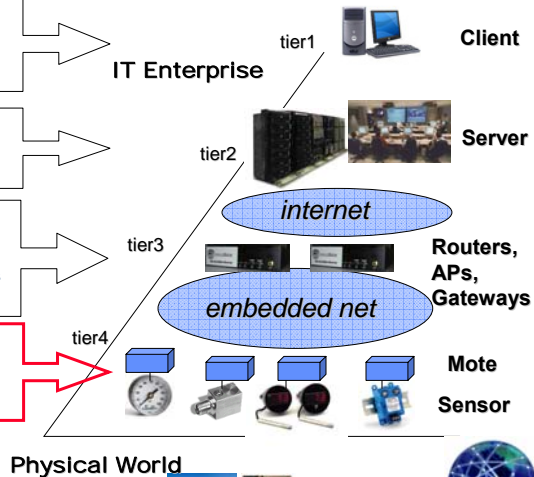
- Massive compute, storage, bandwidth
- Scalability, reliability, redundancy

Router/Gateway Tier:

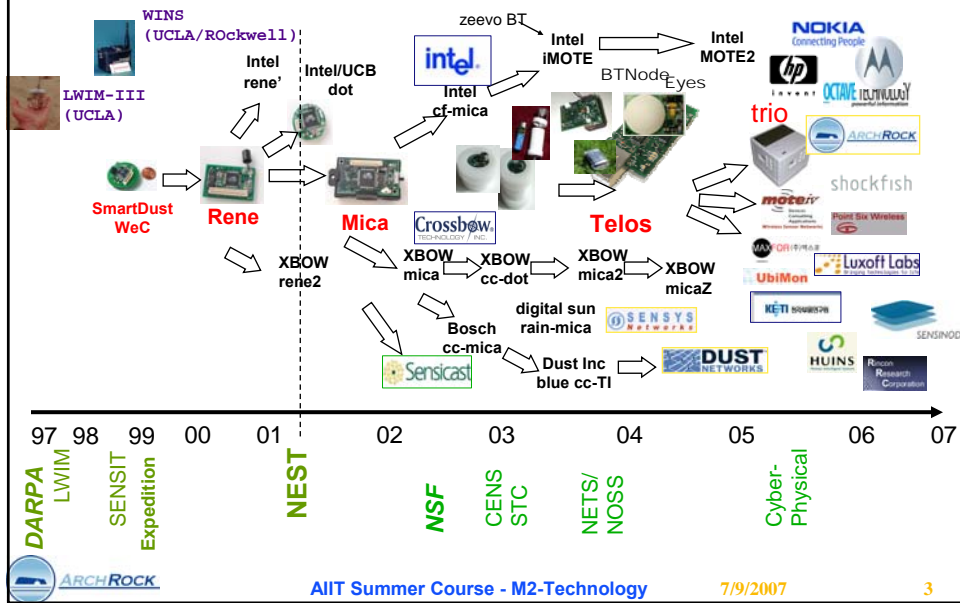
- Bridging: 802.15.4 ↔ (802.11, 802.3, GPRS)
- Routing: Embedded IP and IPv6/IPv4
- Caching, Transcoding, Logging, Gateway adapters
- Packet Processing

Embedded Tier: (mote)

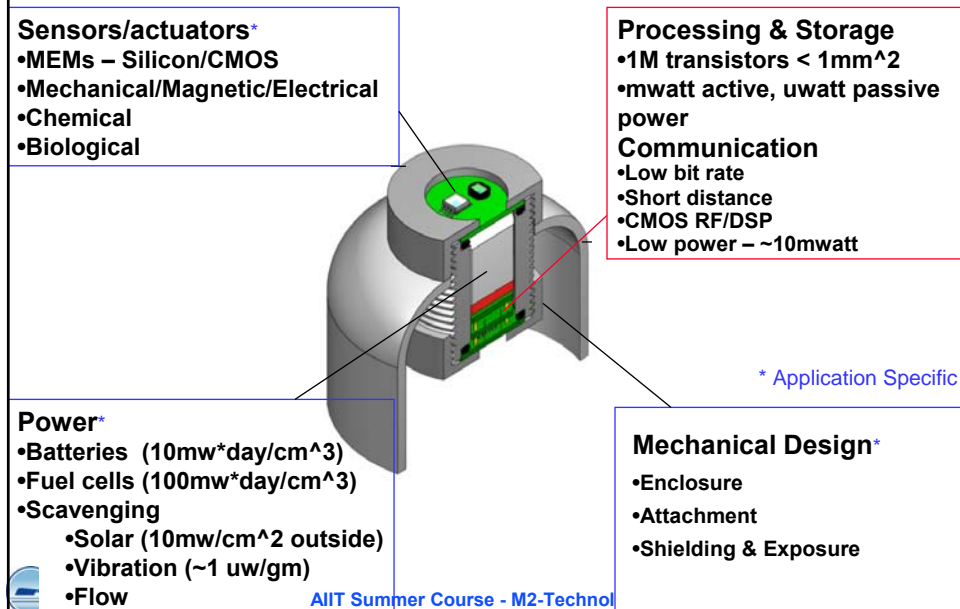
- Low-power, cost-effective, robust embedded devices. Digital and analog interfaces, converters.
- Self-organized network communication



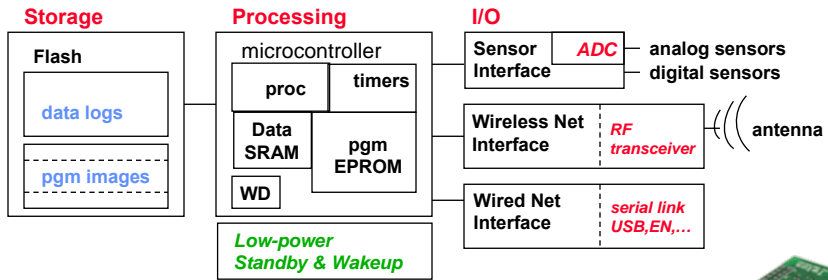
The Mote Lineage ...



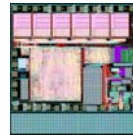
Anatomy of a Mote



Architecture of a Mote



- Efficient wireless protocol *primitives*
- Flexible sensor interface
- Ultra-low power standby
- Very Fast wakeup
- Watchdog and Monitoring
- Data SRAM is critical limiting resource



System Architecture Directions for Networked Sensors, Hill, Szewczyk, Woo, Culler, Hollar, Pister, ASPLOS 2000

Hands-on Examples

What we mean by “Low Power”

- 2 AA => 1.5 amp hours (~4 watt hours)
- Cell => 1 amp hour (3.5 watt hours)

Cell: 500 -1000 mW => few hours active

WiFi: 300 - 500 mW => several hours

GPS: 50 – 100 mW => couple days

WSN: 50 mW active, 20 uW passive

450 uW => one year

45 uW => ~10 years

* System design

* Leakage (~RAM)

* Nobody fools mother nature

$$\text{Ave Power} = f_{\text{act}} * P_{\text{act}} + f_{\text{sleep}} * P_{\text{sleep}} + f_{\text{waking}} * P_{\text{waking}}$$



Mote Platform Summary

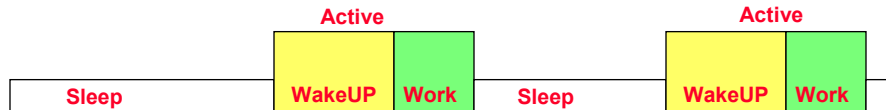
| Mote Type Year | HxC 1998 | Rene 1999 | Rene 2 2000 | Dot 2000 | Mica 2001 | Mica2Dot * 2002 | Mica 2 * 2002 | Telos 2004 |
|----------------------------------|------------------------------------------------------------------|--------------|----------------|-------------|--------------|--------------------|------------------|---------------|
| Microcontroller | AT90LS8535 | | ATmega163 | | ATmega128 | | TI MSP430 | |
| Type | 8 | | 16 | | 128 | | 48 | |
| Program memory (KB) | 0.5 | | 1 | | 4 | | 10 | |
| RAM (KB) | 15 | | 15 | | 15 | | 60 | |
| Active Power (mW) | 45 | | 45 | | 75 | | 75 | |
| Sleep Power (W) | 1000 | | 36 | | 180 | | 180 | |
| Wakeup Time (s) | | | | | | | | |
| Nonvolatile storage | | | | | | | | |
| Chip | 24LC256 | | | | AT45DB041B | | ST M24M01S | |
| Connection type | I ² C | | | | SPI | | I ² C | |
| Size (KB) | 32 | | | | 512 | | 128 | |
| Communication | | | | | | | | |
| Radio | TR1000 | | TR1000 | | CC1000 | | CC2420 | |
| Data rate (kbps) | 10 | | 40 | | 38.4 | | 250 | |
| Modulation type | OOK | | ASK | | FSK | | O-QPSK | |
| Receive Power (mW) | 9 | | 12 | | 29 | | 38 | |
| Transmit Power at 0dBm (mW) | 36 | | 36 | | 42 | | 35 | |
| Power Consumption | | | | | | | | |
| Minimum Operation (V) | 2.7 | | 2.7 | | 2.7 | | 1.8 | |
| Total Active Power (mW) | 24 | | | | 27 | | 44 | |
| 89 | | | | | | | 38.5 | |
| Programming and Sensor Interface | | | | | | | | |
| Expansion | none | 51-pin | 51-pin | none | 51-pin | 19-pin | 51-pin | 10-pin |
| Communication | IEEE 1284 (programming) and RS232 (requires additional hardware) | | | | | | | USB |
| Integrated Sensors | no | no | no | yes | no | no | no | yes |

* Crossbow variation

*** Newer options discussed later



Power: Model of operation



- Sleep – Active [Wakeup / Work]
- Peak Power
 - Essentially sum of subsystem components
 - MW in supercomputer, kW in server, Watts in PDA
 - milliwatts in “mote” class device
- Sleep power
 - Minimal running components + leakage
 - Microwatts in mote-class
- Average power
 - $P_{ave} = (1-f_{active}) * P_{sleep} + f_{active} * P_{active}$
 - $P_{ave} = f_{sleep} * P_{sleep} + f_{wakeup} * P_{wakeup} + f_{work} * P_{work}$
- Lifetime
 - EnergyStore / (P_{ave} - P_{gen})



Initial 802.15.4 Mote Platforms

- Focused on low power
- Sleep - Majority of the time
 - Telos: 2.4μA
 - MicaZ: 30μA
- Wakeup
 - As quickly as possible to process and return to sleep
 - Telos: 290ns typical, 6μs max
 - MicaZ: 60μs max internal oscillator, 4ms external
- Process
 - Get your work done and get back to sleep
 - Telos: 4MHz 16-bit
 - MicaZ: 8MHz 8-bit
- TI MSP430
 - Ultra low power
 - » 1.6μA sleep
 - » 460μA active
 - » 1.8V operation
- Standards Based
 - IEEE 802.15.4, USB
- IEEE 802.15.4
 - CC2420 radio
 - 250kbps
 - 2.4GHz ISM band
- TinyOS support
 - New suite of radio stacks
 - Pushing hardware abstraction
 - Must conform to std link
- Ease of development and Test
 - Program over USB
 - Std connector header
- Interoperability
 - Telos / MicaZ / ChipCon dev



UCB Telos



Xbow MicaZ



Microcontrollers

- **Memory starved**
 - Far from Amdahl-Case 3M rule
 - 2005 => 4x improvement
- **Fairly uniform active inst per nJ**
 - Faster MCUs generally a bit better
 - Improving with feature size
- **Min operating voltage**
 - 1.8 volts => most of battery energy
 - 2.7 volts => lose half of battery energy
- **Standby power**
 - Recently a 10x improvement
 - Probably due to design focus
 - Fundamentally SRAM leakage
 - Wake-up time is key
- **Trade sleep power for wake-up time**
 - Memory restore
- **DMA Support**
 - permits ADC sampling while processor is sleeping

| Manufacturer | Device | RAM (kB) | Flash (kB) | Active (mA) | Sleep (μ A) | Release |
|-------------------|-------------------|----------|------------|-------------|------------------|---------|
| Atmel | AT90LS8535 | 0.5 | 8 | 5 | 15 | 1998 |
| | Mega128 | 4 | 128 | 8 | 20 | 2001 |
| | Mega165/325/645 | 4 | 64 | 2.5 | 2 | 2004 |
| General | PIC | 0.025 | 0.5 | 19 | 1 | 1975 |
| Instruments | PIC Modem | 4 | 128 | 2.2 | 1 | 2002 |
| Microchip | 4004 | 0.625 | 4 | ?? | ?? | 1971 |
| Intel | 8051 Classic | 0.5 | 32 | 30 | 5 | 1995 |
| | 8051 16-bit | 1 | 16 | 45 | 10 | 1996 |
| | 80C51 16-bit | 2 | 60 | 15 | 3 | 2000 |
| Philips | 80C51 16-bit | 2 | 60 | 15 | 3 | 2000 |
| Motorola | HC05 | 0.5 | 32 | 6.6 | 90 | 1988 |
| | HC08 | 2 | 32 | 8 | 100 | 1993 |
| | HCS08 | 4 | 60 | 6.5 | 1 | 2003 |
| Texas Instruments | TSS400 4-bit | 0.03 | 1 | 15 | ?? | 1974 |
| | MSP430F14x 16-bit | 2 | 60 | 1.5 | 1 | 2000 |
| | MSP430F16x 16-bit | 10 | 48 | 2 | 1 | 2004 |
| Atmel | AT91 ARM Thumb | 256 | 1024 | 38 | 160 | 2004 |
| Intel | XScale PXA27X | 256 | N/A | 39 | 574 | 2004 |

2004: Microcontroller market responded substantially to WSN requirements

2005/6: Radio integration

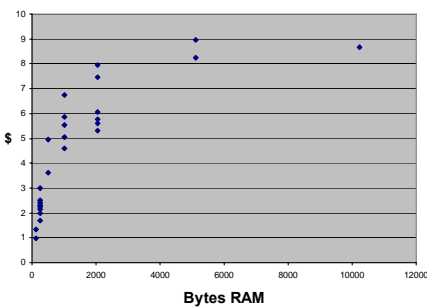
2006/7: Proliferation and solidification

? - Complete SoC

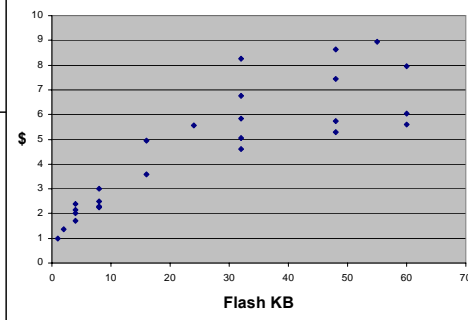


Critical Memory Footprint

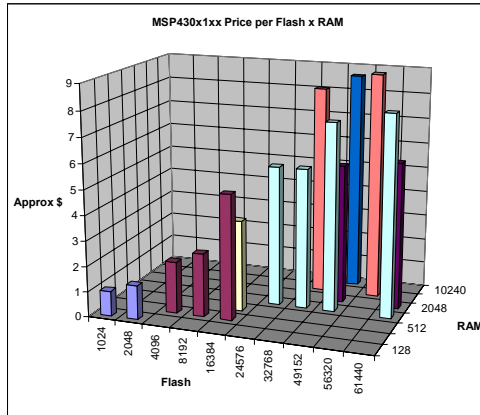
TI-MSP430x1xx Approx. 1KU Price (US\$) vs RAM Capacity



TI-MSP430x1xx Approx. 1KU Price (US\$) vs Flash Size



Memory Footprint continued



- **Regression**
 - RAM: \$0.397 per kB
 - FLASH: \$0.074 per kB
- **Compare with standard SRAM/DRAM**
 - 1M SRAM: \$0.002 per kB
 - 256M DRAM ~ \$10⁻⁵ per kB

Radio

| Type | Narrowband | | | | Wideband | | |
|----------------------|------------|-----------|--------------|-------------|-------------|-------------|------------|
| | RFM | Chipcon | Chipcon | Nordic | Chipcon | Motorola | Zeevo |
| Vendor | TR1000 | CC1000 | CC2400 | nRF2401 | CC2420 | MC13191/92 | ZV4002 |
| Part no. | | | | | | | |
| Max Data rate (kbps) | 115.2 | 76.8 | 1000 | 1000 | 250 | 250 | 723.2 |
| RX power (mA) | 3.8 | 9.6 | 24 | 18 (25) | 19.7 | 37(42) | 65 |
| TX power (mA/dBm) | 12 / 1.5 | 16.5 / 10 | 19 / 0 | 13 / 0 | 17.4 / 0 | 34(30) / 0 | 65 / 0 |
| Powerdown power (µA) | 1 | 1 | 1.5 | 0.4 | 1 | 1 | 140 |
| Turn on time (ms) | 0.02 | 2 | 1.13 | 3 | 0.58 | 20 | * |
| Modulation | OOK/ASK | FSK | FSK,GFSK | GFSK | DSSS-O-QPSK | DSSS-O-QPSK | FHSS-GFSK |
| Packet detection | no | no | programmable | yes | yes | yes | yes |
| Address decoding | no | no | no | yes | yes | yes | yes |
| Encryption support | no | no | no | no | 128-bit AES | no | 128-bit SC |
| Error detection | no | no | yes | yes | yes | yes | yes |
| Error correction | no | no | no | no | yes | yes | yes |
| Acknowledgments | no | no | no | no | yes | yes | yes |
| Interface | bit | byte | packet/byte | packet/byte | packet/byte | packet/byte | packet |
| Buffering (bytes) | no | 1 | 32 | 16 | 128 | 133 | yes * |
| Time-sync | bit | SFD/byte | SFD/packet | packet | SFD | SFD | Bluetooth |
| Localization | RSSI | RSSI | RSSI | no | RSSI/LQI | RSSI/LQI | RSSI |

* Manufacturer's documentation does not include additional information.

- **Trade-offs:**
 - resilience / performance => slow wake up
 - Wakeup vs interface level
 - Ability to optimize vs dedicated support

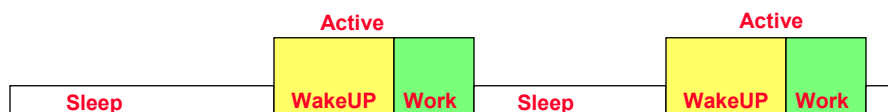
CMOS Radios

- CMOS radios now widely available
 - 1 mW transmit power
 - Consume 10s mW transmitting, receiving, or listening
 - Nominal range 10's of meters
 - » Power grows as R^3 or worse
- Substantial improvements in link coding
 - On/Off => Amplitude Shift => Frequency Shift narrow band
 - => Frequency tunable spread spectrum (802.15.4)
- 802.15.4 radio has gained wide adoption
 - IEEE only standardizes Phy to MAC
 - Many competing higher level protocols
 - » ZIGBEE, several TinyOS Stacks, Ember, Dust, Sencicast, Millennial, ... , IPv6
- Higher level hardware interfaces reduce processor load, but limit power optimizations
- Reliability must be addressed at higher levels too

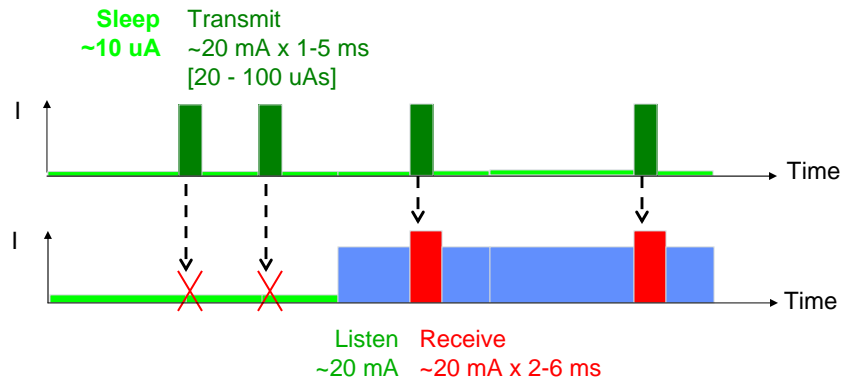


Power States at Node Level

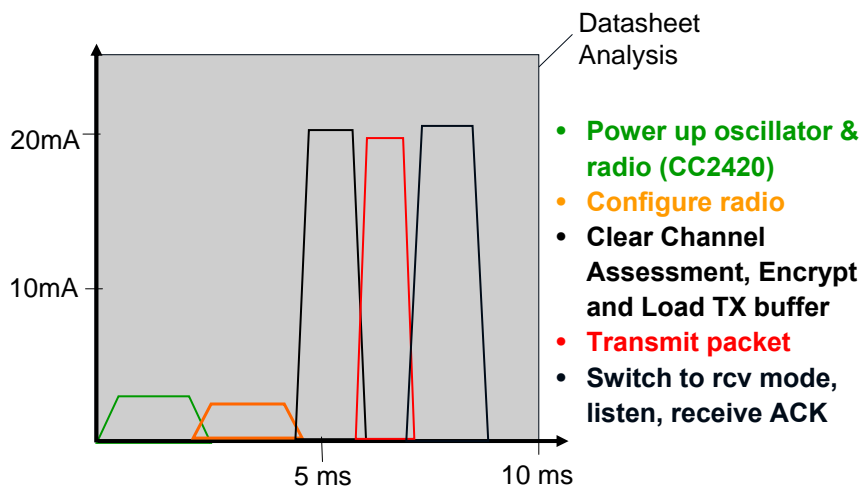
| Operation | Telos | Mica2 | MicaZ |
|-----------------------|--------------|--------------|--------------|
| Minimum Voltage | 1.8V | 2.7V | 2.7V |
| Module Standby | 5.1 μ A | 19.0 μ A | 27.0 μ A |
| MCU Idle | 54.5 μ A | 3.2 mA | 3.2 mA |
| MCU Active | 1.8 mA | 8.0 mA | 8.0 mA |
| MCU + Radio RX | 21.8 mA | 15.1 mA | 23.3 mA |
| MCU + Radio TX (0dBm) | 19.5 mA | 25.4 mA | 21.0 mA |
| MCU + Flash Read | 4.1 mA | 9.4 mA | 9.4 mA |
| MCU + Flash Write | 15.1 mA | 21.6 mA | 21.6 mA |
| MCU Wakeup | 6 μ s | 180 μ s | 180 μ s |
| Radio Wakeup | 580 μ s | 1800 μ s | 860 μ s |



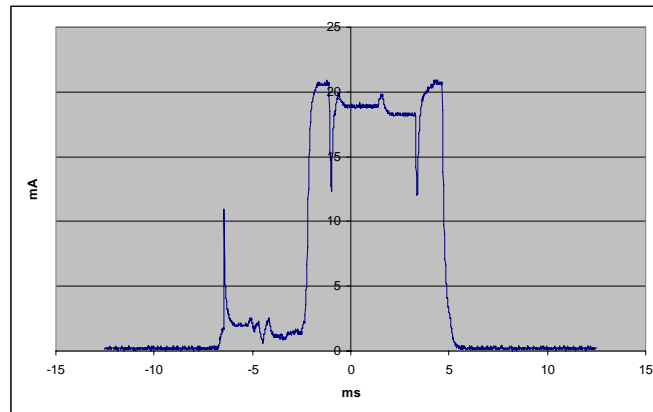
Communication Power Consumption



Energy Profile of a Transmission



Example: TX maximum packet



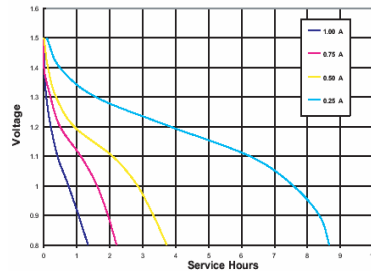
The “Idle Listening” Problem

- The power consumption of “short range” (i.e., low-power) wireless communications devices is roughly the same whether the radio is transmitting, receiving, or simply ON, “listening” for potential reception
 - includes IEEE 802.15.4, Zwave, Bluetooth, and the many variants
 - WiFi too!
 - Circuit power dominated by core, rather than large amplifiers
 - Radio must be ON (listening) in order receive anything.
 - Transmission is infrequent. Reception \propto Transmit x Density
 - Listening (potentially) happens all the time
- ⇒ Total energy consumption dominated by *idle listening*

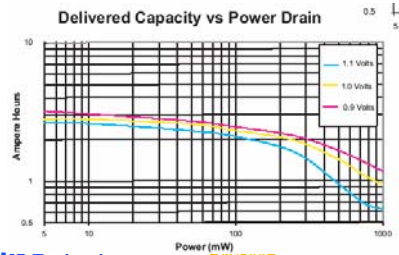
Energy Sources

- Batteries still the best energy store
 - Voltage
 - Source current
 - Leakage
 - Voltage profile
 - Recharge
- SuperCaps have improved dramatically
 - High leakage
- Power-harvesting
 - Nearby AC
 - Solar
 - Vibration
 - Mechanical
- Introduces new control loop on the node

Typical Ultra AA Discharge Characteristics



Delivered Capacity vs Power Drain



Sensors

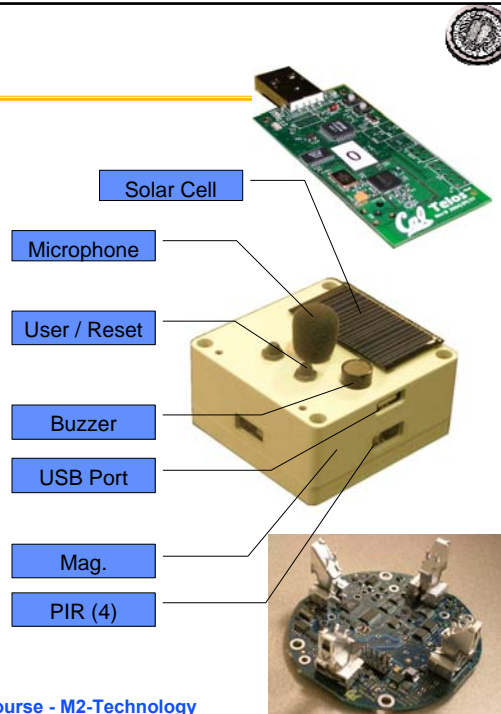
- Wide array of low-power micro sensors available
 - Temp, Light, Humidity, Acceleration, Mag, Pressure, ...
- Several digital interfaces
 - RS232, SPI, I2C, ...
- Too many analog interfaces
- Conventional external sensor very diverse
 - Excitation voltage
 - Bandpass, Op Amps, sensitivity, range, ...
- In all cases, mechanical design is critical
 - Expose sensors, protect electronics

=> Hassle for node developers

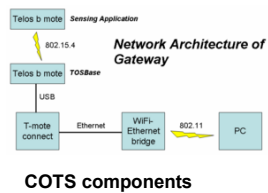
=> Vastly easier to integrate wireless (or wired) sensor modules than the sensors themselves

Trio Node

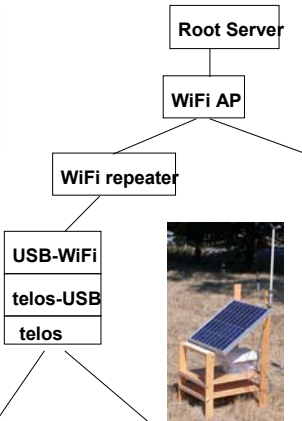
- Platform Goals
 - Permanent deployment
 - Weather resistance
 - Research-friendly
- Features
 - Telos (MCU, radio, flash)
 - Rich sensor-board
 - Solar Harvesting
 - Passive Infrared
 - Microphone
 - Magnetometer
 - Grenade Timer
- Improved Usability
 - Pushbuttons
 - Integrated Antenna
 - Exposed USB Connector



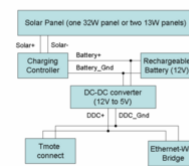
Self-powered MultiTier Network



COTS components



Tier2 node power supply schematic



The New Power Point



- **Microcontrollers:**
 - 1-10 mW active, 1 uW passive => 10-100 uW average
- **Micro-sensors (MEMS, Materials, Circuits)**
 - acceleration, vibration, gyroscope, tilt, magnetic, heat, motion, pressure, temp, light, moisture, humidity, barometric
 - chemical (CO, CO₂, radon), biological, microradar, ...
 - actuators too (mirrors, motors, smart surfaces, micro-robots)
- **Micro-Radios**
 - CMOS, short range (10 m), low bit-rate (200 kbps), 10 mW
- **Micro-Power**
 - Batteries: 1,000 mW*s/mm³, fuel cells
 - solar (10 mW/cm², 0.1 mW indoors), vibration (~uW/gm), flow
- 1 cm³ battery => 1 year at 1 msg/sec

Passive Vigilance



- **Sense only when there is something useful to detect**
- **Listen only when there is something useful to hear**
- **How do you know?**
 - By arrangement
 - By cascade of lower power triggers

Trends and issues



- 2006-7 integrate 802.15.4 radio with microcontroller
 - 8051 or XAP2 1-address arch. with poor compilers
- Rapid migration of RISC cores
 - ARM and XSCALE moving down
- Improved system support

- Microcontroller + Radio + Flash is universal
- Sensor suite, power subsystem, mechanical design are application specific
- ⇒ Mote will be *manufactured in* to end devices and building fixtures (or materials)
- ⇒ Solution integrated through software



Recent Developments



- ATMEL 1281 – more data RAM
- ATMEL RF230 – more TX and RX
 - Crossbow IRIS, Meshnetics Zigbit
- CC2430 – integrated 8051
 - Sensinode
- EM250 / EM260 – integrated XAP + zigbee stack
- Jennic – 32-bit processor + MB
- ARM Cortex – 32-bit Processor



Brief Comparison

| Vendor | TI | Crossbow | MeshNetics | Ember | DustNetworks |
|------------------------------|---------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------|
| Model | CC2430 | IRIS M2110CA | ZigBit ZDM-A1281 | EM250 | SmartMesh-XT M2030 |
| Type | System-on-Chip | OEM module | OEM module | System-on-Chip | OEM module |
| Link | http://www.ti.com/lit/gpn/cc2430 | http://www.xbow.com/Products/productdetails.aspx?siid=264 | http://www.meshnetics.com/zigbee-products/ | http://www.ember.com/pdf/EM250120-0082-000H_EM250_Datasheet.pdf | http://www.dustnetworks.com/docs/M2030.pdf |
| Micro Controller | 8051 core integrated in CC2430 | Atmega 1281 | Atmega1281 | Integrated 16-bit XAP2b MCU | Integrated |
| Program Memory (KB) | 32/64/128 | 128 | 128 | 128 | |
| SRAM (KB) | 8 | 8 | 8 | 5 | |
| Nominal Voltage (V) | 3 | 3 | 3 | 1.8 | 3 |
| MCU Active current (mA) | 9.5 | 8 | 14 | 8.5 | |
| MCU Active RX current (mA) | 26.7 | 24 | 19 | 35.5 | 22 |
| MCU Active TX current (mA) | 26.9 (at 0 dBm) | 25 (at 3 dBm) | 18 (at 0 dBm) | 35.5 (at 0 dBm) | 20 (at -2 dBm) |
| Number of power saving modes | 3 | 1 | 1 | 1 | 2 |
| Power mode 1 (uA) | 190 | 8 (sleep mode) | 6 (power save mode) | 1 (deep sleep) | 51 (low power networking) |
| Power mode 2 (uA) | 0.5 | | | | 10 (sleep) |
| Power mode 3 (uA) | 0.3 | | | | |
| Number of timers | 4 | 6 | 6 | 3 | |
| Granularity of timers | one general 16-bit timer two general 8-bit timers one MAC timer | four general 16-bit timers two general 8-bit timers | four general 16-bit timers two general 8-bit timers | two 16-bit general timer one 16-bit sleep timer | |
| ADC | | | | | |
| precision (bits) | 12 | 10 | 10 | 12 | |
| # channels | 8 | 8 | 4 | 4 | |
| DMA | Yes | | | Yes | |
| Radio | CC2430 | AT86RF230 | AT86RF230 | EM250 | Integrated |
| Data rate (kbps) | 250 | 250 | 250 | 250 | 250 |
| Receiver Sensitivity (dBm) | -92 | -101 | -101 | -97 | -90 |
| Current at RX (mA) | 17.2 | 16 | 16 | 27 | |
| Current at TX at 0dBm (mA) | 17.4 (at 0 dBm) | | | 24.3 (at 0 dBm) | |
| Current at minimum TX (mA) | 18.3 (at -25.2 dBm) | 10 (at -17 dBm) | 10 (at -17 dBm) | 19.5 (at -32 dBm) | |
| Current at maximum TX (mA) | 32.4 (at 0.6 dBm) | 17 (at 3 dBm) | 17 (at 3 dBm) | 27 (at 3 dBm) | |
| Any link or signal indicator | RSSI, LQI | RSSI, LQI | RSSI, LQI | RSSI, LQI | |
| Non standard mode | | | | | |
| How high in the stack | 802.15.4/ZigBee | 802.15.4/XMesh | 802.15.4/ZigBee | 802.15.4/ZigBee | 802.15.4/TSMP |

AIIT Summer Course - MZ-Technology

7/9/2007

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Discussion