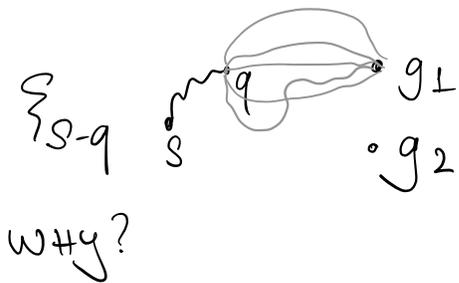


Inference Intuit



$$P(g_i | \xi_{s-q})$$

$$\hat{g} = \underset{g_i}{\operatorname{argmax}} P(g_i | \xi_{s-q})$$

Bayesian Inference! Easier to reason about $P(\xi_{s-q} | g)$

↳ assume that \hat{g} is approx optimal like in MaxEnt IRL

$$P(\xi_{s-q} | g) = \frac{e^{-\mathcal{U}(\xi_{s-q} | g)}}{\int_{\xi_{s-q}} e^{-\mathcal{U}(\xi_{s-q})}}$$

$$P(g_i | \xi_{s-q}) = \frac{P(\xi_{s-q} | g_i) P(g_i)}{\sum_g P(\xi_{s-q} | g) P(g)}$$

$$P(\xi_{s-q} | g) = \int_{\bar{\xi}_{q-g}} P(\xi_{s-q} \bar{\xi}_{q-g} | g)$$

$$= \int_{\bar{\xi}_{q-g}} \frac{e^{-\mathcal{U}(\xi_{s-q} \bar{\xi}_{q-g} | g)}}{\int_{\bar{\xi}_{s-g}} e^{-\mathcal{U}(\bar{\xi}_{s-g})}}$$

$$= e^{-\mathcal{U}(\xi_{s-q})} \cdot \frac{\int_{\dots} | \dots \int_{\bar{\xi}_{q-g}} e^{-\mathcal{U}(\bar{\xi}_{q-g})} | \dots \int_{\bar{\xi}_{s-g}} e^{-\mathcal{U}(\bar{\xi}_{s-g})}$$

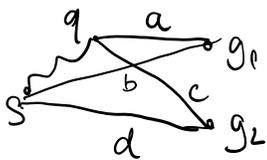
approximate integral via Laplace

$$\mathcal{U}(\xi) \approx \underbrace{\mathcal{U}(\xi^*)}_{\text{constant}} + \underbrace{\nabla \mathcal{U}^T(\xi - \xi^*)}_0 + \underbrace{\frac{1}{2} \|\xi - \xi^*\|_{\nabla^2 \mathcal{U}}^2}_{\text{Gaussian Integral}}$$

$$P(\xi_{s-q} | g) = e^{-u(\xi_{s-q})} \frac{e^{-u(\xi_{q-g}^*)} \int_{\xi_{q-g}} e^{-\frac{1}{2} \|\xi_{q-g} - \xi_{q-g}^*\|^2 / \sigma^2}}{e^{-u(\xi_{s-g}^*)} \int_{\xi_{s-g}} e^{-\frac{1}{2} \|\xi_{s-g} - \xi_{s-g}^*\|^2 / \sigma^2}}$$

even easier: approximate via $e^{-u(\xi^*)}$

$$P(g_1 | \xi_{s-q}) = \frac{e^{-u(\xi_{s-q})} \cdot e^{-u(\xi_{q-g_1}^*) + u(\xi_{s-g_1}^*)} P(g_1)}{e^{-u(\xi_{s-q})} \sum_g (e^{-u(\xi_{q-g}^*) + u(\xi_{s-g}^*)} P(g))}$$



$$P(g_1 | \xi_{s-q}) = \frac{e^{-u(\xi_{s-q})} \cdot \frac{e^{-a}}{e^{-b}}}{e^{-u(\xi_{s-q})} \left(\frac{e^{-a}}{e^{-b}} + \frac{e^{-c}}{e^{-d}} \right)}$$

Expressing Intent

• switch H and R: now H is computing $P(g | \xi_{s-q})$ ^{Rho_j}

• R wants H to put high prob on g^*

$$\text{LIP: } \max_{\xi} \int P(g^* | \xi_{s-\xi(t)}) dt.$$

Search over g : $\max_g P(g | \xi)$ - intent inference

Search over ξ : $\max_{\xi} P(\xi | g)$ - predictability

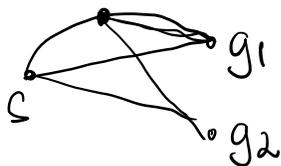
Search over ξ : $\max_{\xi} P(g | \xi)$ - legibility

Search over ξ

normalizer matters!

$$\Rightarrow \neq \max_{\xi} P(\xi | g)$$

even with uniform prior



optimizing L : gradient descent

$$\nabla_{\xi} L(t) = \frac{\partial F}{\partial \xi(t)} - \frac{d}{dt} J_{\xi}(t)$$

let $J_g(q) = \min_{\xi_{q-g}} U(\xi_{q-g})$ - optimal cost to go

$$F(t, \xi(t), \xi'(t)) = \frac{e^{-J_{g^*}(q) + J_{g^*}(s)} = h}{\sum_g e^{-J_g(q) + J_g(s)} = h}$$

/ assume uniform prior

$$\frac{\partial F}{\partial q} = \frac{e^1 h - h^1 e}{h^2} \quad \begin{aligned} e^1 &= e^{-J_{g^*}(q) + J_{g^*}(s)} \cdot (-\nabla_q J_{g^*}) \\ h^1 &= \sum_g e^{-J_g(q) + J_g(s)} \cdot (-\nabla_q J_g) \end{aligned}$$

grad of value function
for every goal

$$\left. \begin{aligned} e^1 h &= e^1 \sum_g e^1 (-\nabla_q J_{g^*}) \\ h^1 e &= e^1 \sum_g e^1 (-\nabla_q J_g) \end{aligned} \right\} \Rightarrow$$

gradient points in direction $\sum_g (\nabla_q J_g e^1 - \nabla_q J_{g^*} e^1)$

decrease cost to go to g^*
increase cost to go to others

